



Developments in meshfree modeling for multiphysics laboratory experiments, astrophysics, and planetary defense

Presented at the 2025 SPHERIC World Conference
June 17-19, 2025

J. Michael Owen

Lawrence Livermore National Laboratory

Prepared by LLNL under Contract DE-AC52-07NA27344.



Meshfree methods have been around for decades, but acceptance is spotty across different fields.

- Smoothed Particle Hydrodynamics (SPH^{1,2}) is the ancestor of most of the more general meshfree methods we use today.
- Those early papers from the 70's and 80's developed SPH to provide hydrodynamics in N-body gravitational models, where meshfree is the most natural discretization.
- The Lagrangian nature of SPH was also an essential practicality.
 - Gravitationally driven collapse leads to large changes in the required resolution (orders of magnitude), and this was problematic for the standard meshed hydrodynamics to resolve on all scales/times.

¹Lucy, L.B., 1977. A numerical approach to the testing of the fission hypothesis. *Astron. J.* 82, 1013–1024.

²Gingold, R.A., Monaghan, J.J., 1977. Smoothed particle hydrodynamics: theory and application to non-spherical stars. *Mon. Not. R. Astron. Soc.* 181, 375–389.

The early experiments with SPH were rather successful, but why?

- SPH (particularly early on) was quite a bit less sophisticated than the competing meshed based hydrodynamics algorithms of the time.
 - SPH interpolation is quite crude, with many deficiencies we are all too aware of:
 - Lack of reproducibility for fields of any order – for points that are not perfectly uniform SPH is not even zeroth-order consistent!
 - Even granted this lack of reproducibility SPH interpolation also tends to be noisy.
 - Some folks analyzed SPH interpolation as a Monte-Carlo approximation, but it's not that bad!
 - Adding more neighbors reduces the noise but aggravates the fact that SPH also tends to be more expensive than competing meshed discretizations (on a cost per element basis, which is not necessarily entirely fair depending on the problem).
- One important factor is that SPH (and related methods) can be formulated to match the relevant physics invariants for many classes of problems.



The traditional SPH equations preserve many of the physics invariants important in their applications.

- Despite its many numerical drawbacks, even the early traditional SPH formulations preserve a remarkable set of important physical principles:
 - Exact conservation of mass, linear, and **angular** momentum
 - Even better these properties are expressed on a local pairwise basis
 - **Galilean invariance** (i.e., the answer is frame independent)
 - The numerics are naturally expressed in a **Lagrangian** framework
 - Just as importantly the method remains robust in that moving framework
- Competing mesh based discretizations have difficulties with the highlighted properties, even to this day.
 - Despite the fact such methods were (and are) substantially more numerically sophisticated (better accuracy, less diffusive, much more amenable to analysis), they often struggle in problem areas where SPH succeeds.



This principle of reflecting the physical properties of the continuum equations is well-known.

- The idea of exactly reproducing properties of continuum equations in their discrete counterparts has been referred to as “mimetic”¹.
 - This just means the discrete equations “mimic” (or reproduce) some set of crucial properties from the continuum physics equations.
 - Note: “exact” discrete conservation means to numerical roundoff.
 - These ideas go back to at least the 1960’s
- Related literature² also refers to these discretization as “compatible”.
- Examples from the broader world of numerical modeling include:
 - Exact conservation of mass, momentum, and energy
 - Exact divergence-free velocity fields for incompressible flow
 - Exact divergence-free magnetic fields for ideal magneto-hydrodynamics

¹Lipnikov, K., Manzini, G., Shashkov, M., 2014. Mimetic finite difference method. J. Comput. Phys. 257, 1163–1227. <https://doi.org/10.1016/j.jcp.2013.07.031>.

²Caramana, E.J., Burton, D.E., Shashkov, M.J., 1998. The construction of compatible hydrodynamics algorithms utilizing conservation of total energy. J. Comput. Phys. 146, 227–262.



Know your problem: numerical methods are a series of compromises – what's important for your case?

- Many of the problems I work with are dominated by the presence and evolution of strong shocks in compressible flows.
 - Astrophysics: supernova, large-scale cosmological structure, galaxy formation
 - Laboratory physics: Laser-driven experiments, inertial confinement fusion (ICF)
 - Planetary defense: cratering and impact physics on planetary bodies and asteroids
- All the conservation properties SPH already meets mentioned previously are important: mass, linear momentum, and angular momentum.
 - Also frame (Galilean) invariance and working in a Lagrangian frame.
- Two more properties are critical however: energy conservation and entropy preservation.

Exact energy conservation is achievable, but how we do it matters!



- Many non-conservative formulations evolve the specific thermal energy (u) via a PDE representation for $\frac{Du}{Dt} = \sigma^{\alpha\beta} \dot{\epsilon}^{\beta\alpha}$, $\dot{\epsilon}^{\alpha\beta} = \frac{1}{2} (\partial_\beta v^\alpha + \partial_\alpha v^\beta)$
 - This approach generally yields **reasonable entropy evolution** but **does not conserve total energy**
- It is simple to exactly conserve energy by directly evolving the total energy.
 - This is very common in Eulerian discretizations for strong shocks
 - While **energy is conserved to roundoff**, there are serious drawbacks to this approach
 - The thermal energy must be formed from the difference $u = \frac{E}{m} - \frac{1}{2}v^2$
 - This sort of difference can **lead to noisy thermal energy, temperature, and poor entropy evolution**
- It is also possible to directly evolve the entropy¹ rather than energy.
 - This yields **good entropy and thermal energy behavior**, but **does not conserve energy**
 - Also **can be difficult to work with general equations of state**

We can construct an exactly energy conserving scheme “compatibly” with the momentum discretization¹.

- The momentum equation we solve for the velocity update is generally constructed to enforce exact linear momentum conservation.
- Starting from the total energy conservation equation, we can account for the exact discrete work from the velocity update.

$$E^1 - E^0 = \sum_i m_i \left[\frac{1}{2} ((v_i^1)^2 - (v_i^0)^2) + u_i^1 - u_i^0 \right] = 0$$

$$\Delta E_{ij}^{\text{thermal}} = m_i \left[(v_j^\alpha)^{1/2} - (v_i^\alpha)^{1/2} \right] (a_{ij}^\alpha)^0 \Delta t$$

$$\Delta u_{ij} = f_{ij} \Delta E_{ij}^{\text{thermal}} / m_i$$

- f_{ij} is the fraction of the pairwise work applied to point i of pair (i,j)
- So long as $f_{ij} + f_{ji} = 1$, exact energy conservation is maintained.

The physics in the compatible energy update is now in choosing the conservative partitioning in f_{ij}

- In our original paper we show it is possible to reproduce conservative forms of several classic SPH energy equations for choices of f_{ij} (such as $\frac{1}{2}$).
- However, we are free to choose this partitioning depending on our goal:
 - Variation diminishing in thermal energy (smoothly or monotonically)
 - Equipartitioning of entropy changes
- In general entropy is treated at least as accurately as the non-conservative approaches.
- Perhaps just as importantly, this formalism works for any discretization producing a discrete pairwise acceleration.
 - We use this compatible energy update for all our meshfree discretizations (both fluid and solid): SPH, CRKSPH, FSISPH, SVPH, ...



Conservative Reproducing Kernel Hydrodynamics

Including work with Cody Raskin, Nicholas Frontiere, and Will Gray

Reproducing Kernels: one approach to improving the underlying numerics of our methods.

- As we mentioned earlier, SPH is not a great interpolation method due low accuracy and lack of consistency.
- Reproducing Kernels (RK)^{1,2} proposes enriching the interpolation basis in order to enforce accuracy and consistency:

$$W(x_{ij}^\alpha, h) \rightarrow W^R(x_{ij}^\alpha, h) = A_i (1 + B_i^\alpha x_{ij}^\alpha + \dots) W(x_{ij}^\alpha, h)$$

- This form corrects to linear terms, so linear fields are reproduced exactly.
- While Reproducing Kernels are a huge improvement in accuracy, the simplest formulations give up momentum conservation (as well as energy).
 - Due to the fact that $W^R(x_{ij}^\alpha, h)$ is not symmetric in (i, j)
 - Acceptable for the low-energy engineering applications RK was developed for, but entirely inappropriate for the high-energy strong shock regime.



We can derive a form of Reproducing Kernels that is conservative for our applications.

- The loss of symmetry in the reproducing kernel complicates enforcing exact momentum conservation, but it is still possible.
- We derive and extensively test a Conservative Reproducing Kernel (CRKSPH)¹ formulation with a momentum equation of the form

$$m_i \frac{Dv_i^\alpha}{Dt} = -\frac{1}{2} \sum_j V_i V_j (P_i + P_j) (\partial_\alpha W_{ij}^R - \partial_\alpha W_{ji}^R)$$

- CRKSPH exactly conserves mass, momentum, and energy (via the compatible energy methodology already described).
 - Improvements such as a monotonically limited artificial viscosity are also introduced in this paper.

¹Frontiere, N., Raskin, C.D., Owen, J.M., 2017. CRKSPH – A Conservative Reproducing Kernel Smoothed Particle Hydrodynamics Scheme. Journal of Computational Physics 332, 160–209.



CRKSPH represents a tradeoff between consistency and conservation.

- Note the CRKSPH momentum equation implies we are sacrificing the exact consistency of gradients gained by a direct RK implementation.

- CRKSPH (conservative): $m_i \frac{Dv_i^\alpha}{Dt} = -\frac{1}{2} \sum_j V_i V_j (P_i + P_j) (\partial_\alpha W_{ij}^R - \partial_\alpha W_{ji}^R)$

- RK (consistent): $m_i \frac{Dv_i^\alpha}{Dt} = -\sum_j V_j P_j \partial_\alpha W_{ij}^R$

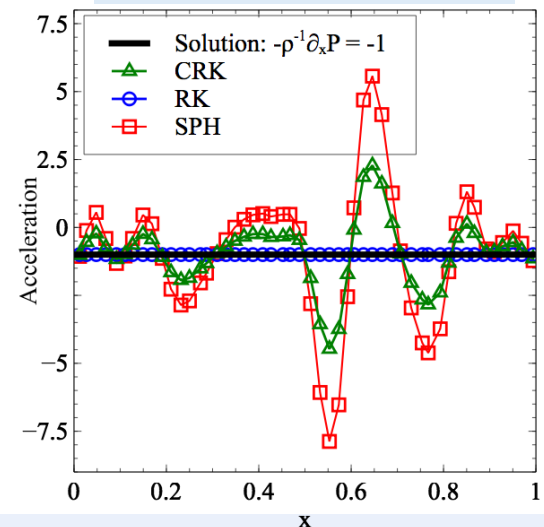
- Evaluating the above relations on an analytic pressure distribution demonstrates this tradeoff:

$$P(x) = 1.0 + x, \quad \rho(x) = 1$$

$$\frac{Dv}{Dx} = -\rho^{-1} \partial_\alpha P = -1$$

- We pay a price for conservation, but it's essential!

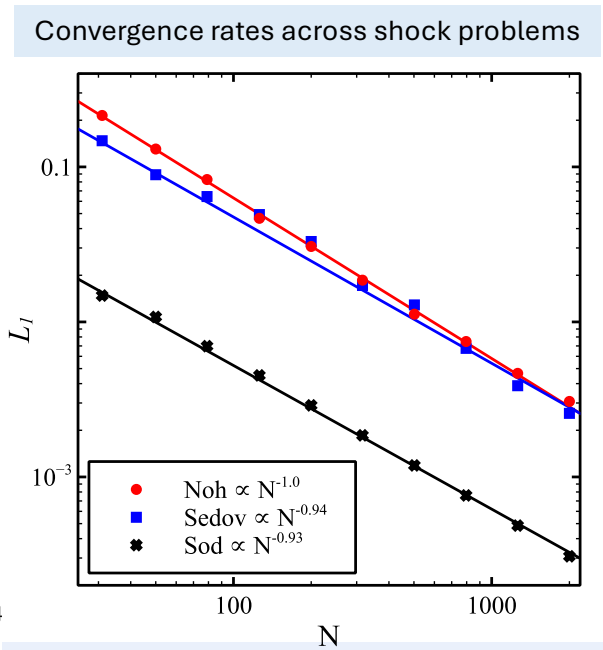
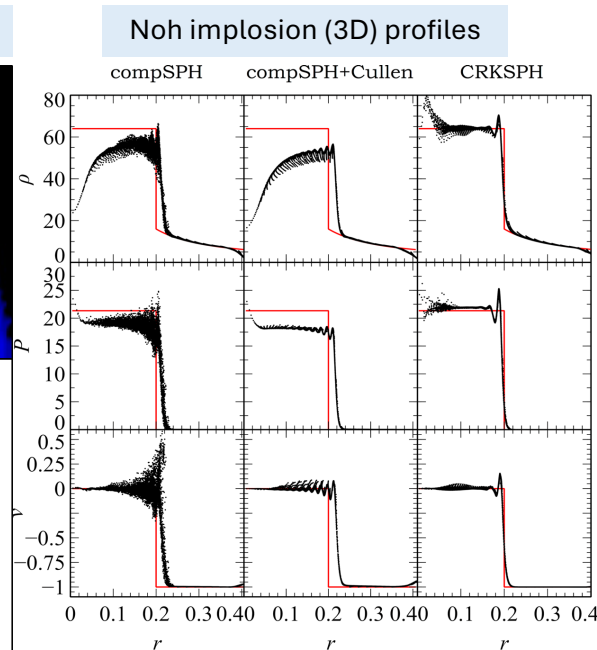
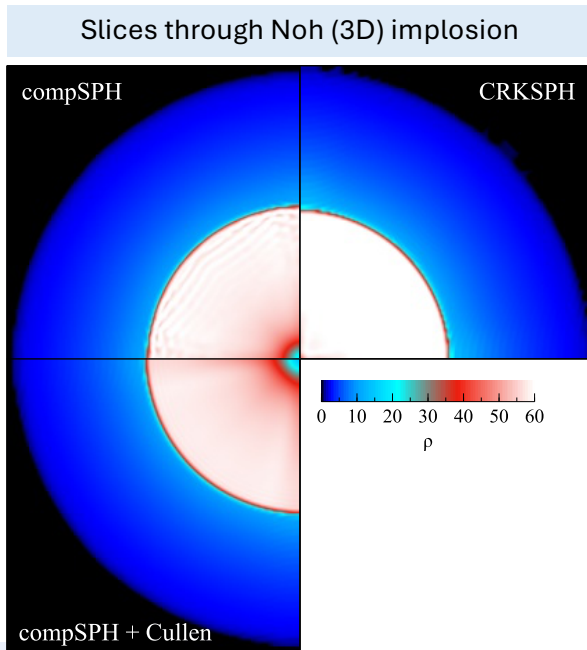
CRK vs RK acceleration for an analytic pressure distribution





CRKSPH performs well across a wide variety of shock dominated compressible problems.

- CRKSPH demonstrates our analytically expected first-order convergence for shock dominated problems.
- Also greater accuracy than the competing SPH methodologies.

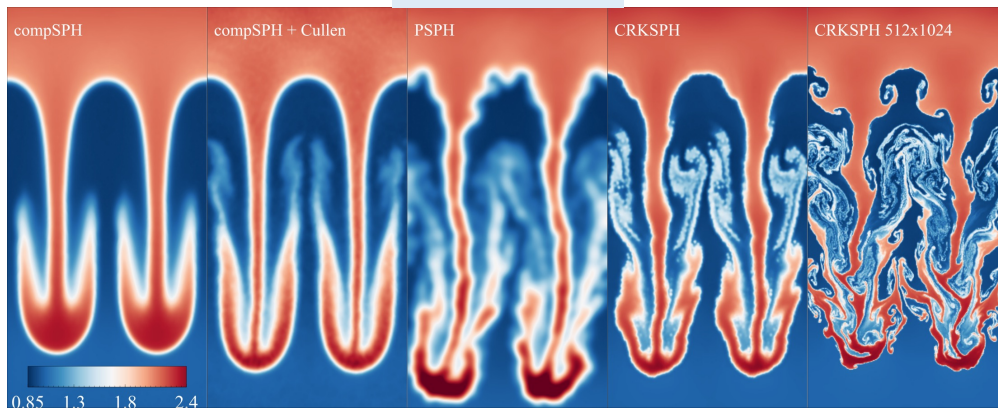




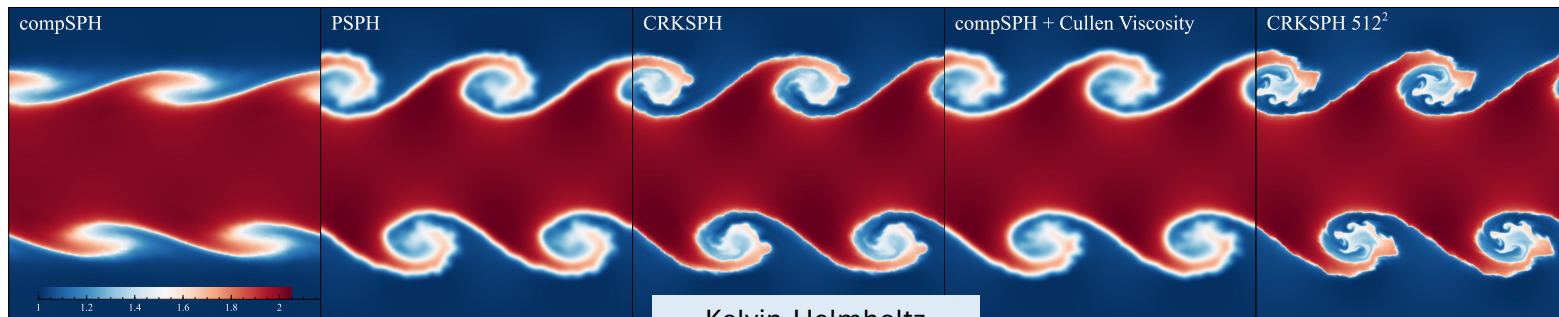
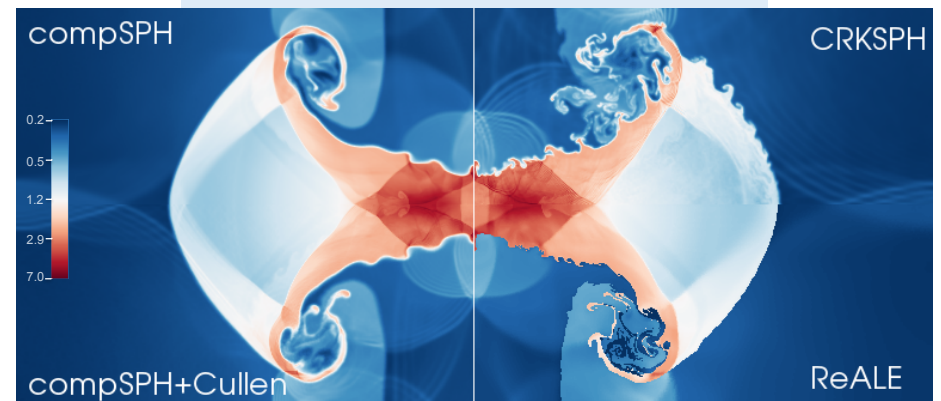
The improved accuracy of CRKSPH is important for modeling the evolution of fluid instabilities.

- Of particular importance is the reduction in numerical diffusion.

Rayleigh-Taylor



“Triple point” (3 region shock-tube)

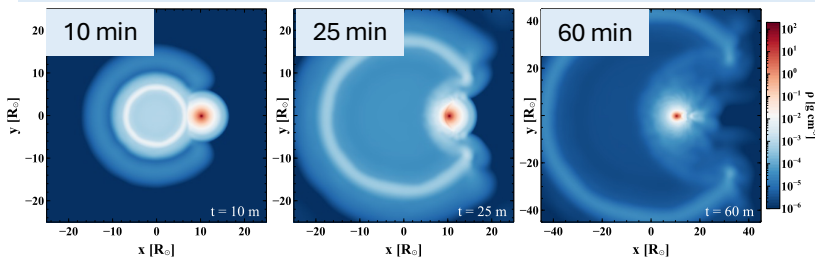


Kelvin-Helmholtz

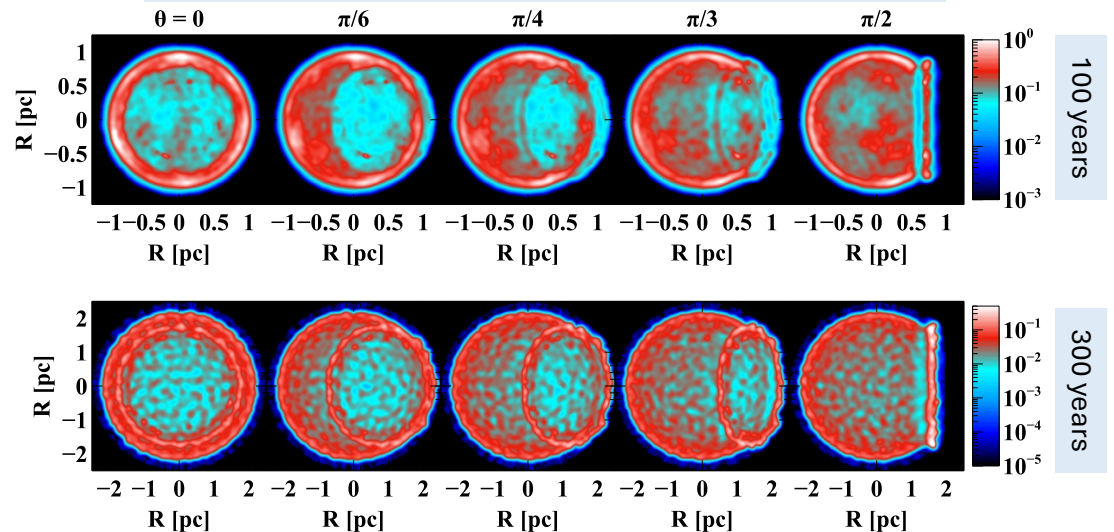
One application area we've explored with CRKSPH is supernova remnants.

- Testing classical theory for Type Ia supernova:
 - Gas transfer from main-sequence star to white dwarf – will the existence of the donor star be evident by a hole in the supernova remnant?

Time evolution of shock wrapping around primary star



Projected X-ray images from various viewing angles



- This analysis suggests we should see the final asymmetry in the SN remnant.
 - Not clear in any observed to date.
 - Support for white-dwarf collisions as Type Ia progenitors?

Note: density variations in these images are due to Rayleigh-Taylor instabilities



Radiation Hydrodynamics

Work with Brody Bassett and Tom Brunner



Radiation hydrodynamics is of interest for a wide variety of laboratory and astrophysical problems.

- The diffusion rad-hydro conservation equations we need to solve are

$\frac{D\rho}{Dt} = -\rho\partial_\alpha v^\alpha$	E_r	radiation energy density
$\rho\frac{Dv^\alpha}{Dt} = -\partial_\alpha P - \lambda\partial_\alpha E_r$	F^α	radiation flux
$\rho\frac{Du}{Dt} = -\partial_\alpha P v^\alpha - c\sigma_a B + c\sigma_a E_r + Q_u$	$P_r^{\alpha\beta}$	radiation pressure
$\frac{DE_r}{Dt} = -\frac{4}{3}E_r\partial_\alpha v^\alpha + \partial_\alpha\frac{c\lambda}{\sigma_t}\partial_\alpha E_r - c\sigma_a E_r + c\sigma_a B + Q_{E_r}$	λ	flux limiter
$c^{-1}\frac{DF^\alpha}{Dt} = -c^{-1}F^\alpha\partial_\beta v^\beta - c\partial_\beta P_r^{\alpha\beta} - \sigma_t F^\alpha$	σ_a	absorption opacity
	σ_t	total opacity
	B	integrated photon emission
	c	speed of light
	Q_u	material energy source
	Q_{E_r}	radiation energy source

- We have integrated over all radiation energies and angles from the full transport equations (i.e., “gray diffusion”)^{1,2}

¹Bassett, B.R., Owen, J.M., Brunner, T.A., 2021. Efficient smoothed particle radiation hydrodynamics I: thermal radiative transfer. J. Comput. Phys. 429, 109996.

²Bassett, B.R., Owen, J.M., Brunner, T.A., 2021. Efficient smoothed particle radiation hydrodynamics II: radiation hydrodynamics. J. Comput. Phys. 429, 109994.



We operator split the update into hydrodynamics, radiation, and radiative work.

- The radiation step uses implicit time integration (backward Euler).
 - We also need a second-derivative operator for the $\partial_\alpha \frac{c\lambda}{\sigma_t} \partial_\alpha E_r$ term.
 - The common SPH low-order discretization works surprisingly well

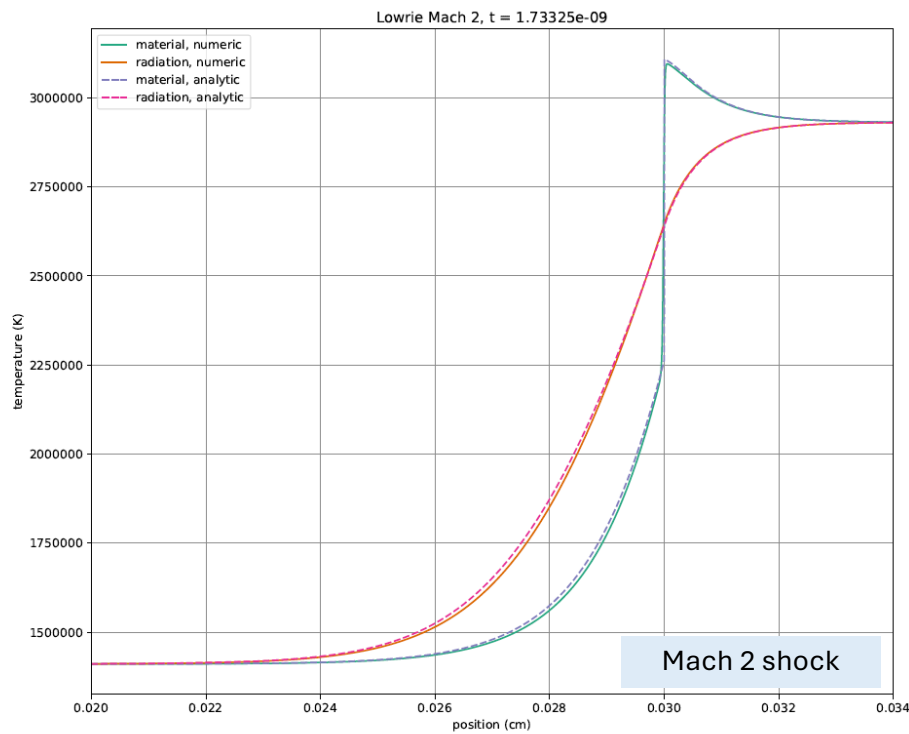
$$\left\langle \partial_\alpha \frac{c\lambda}{\sigma_t} \partial_\alpha E_r \right\rangle \approx \sum_j V_j (D_i + D_j) (E_{ri} - E_{rj}) \frac{x_{ij}^\alpha}{x_{ij}^\beta x_{ij}^\beta} \partial_\alpha W_{ij}, \quad D_i \equiv \frac{c\lambda_i}{\sigma_{ti}}$$

- We also have a RK version of the diffusion operator that works well
- The implicit time discretization is challenging due to the highly nonlinear terms involved.
 - Our work is based on the hard-won knowledge of experts in transport preceding us.
 - We are using the method of nonlinear elimination^{1,2}
 - The details are too much to cover here, but see the refs by Brody (previous slide) and below.



The Lowrie radiating shock¹ is a semi-analytic radiation-hydrodynamics problem and provides an essential test.

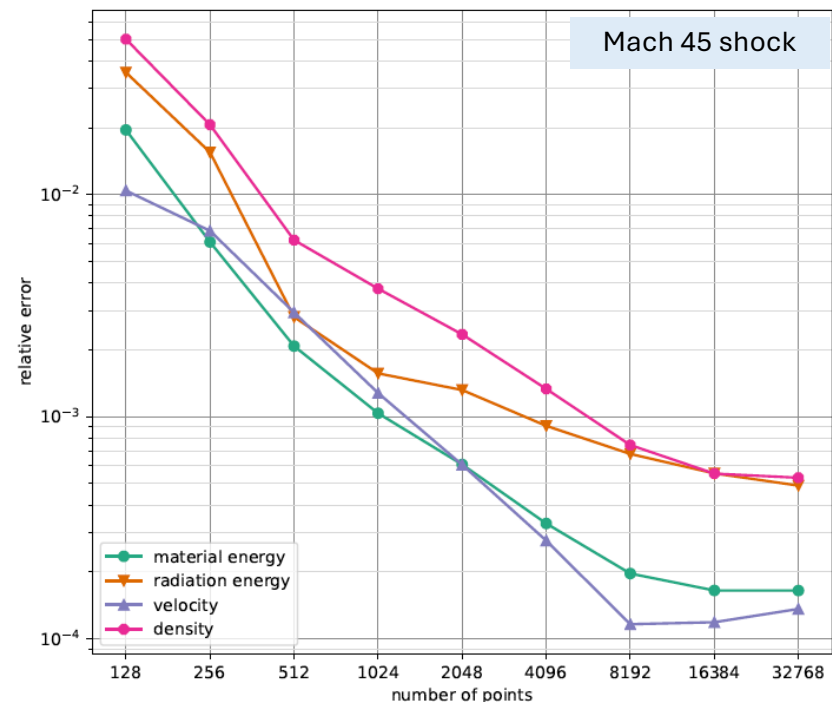
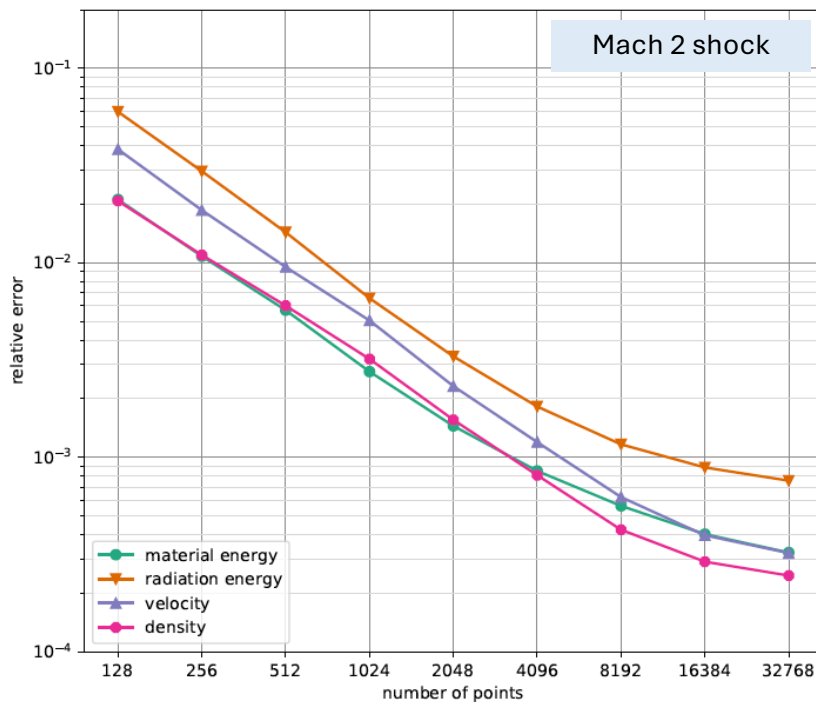
- Rad-hydro problems with an analytic solution are scarce!





The Lowrie radiating shock demonstrates second-order convergence (until limited by time step).

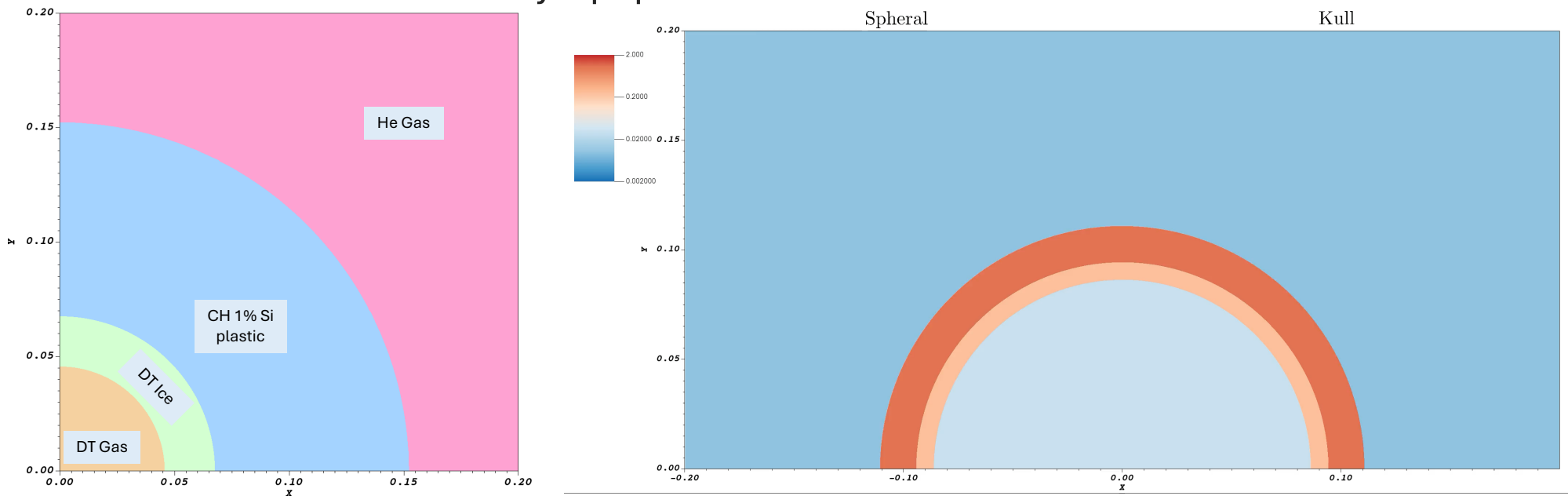
- Second-order is only possible here because radiative effects smooth the discontinuities.





An idealized ICF-like ablation problem shows promise when comparing with more mature codes.

- This is a simplified example of a test case proposed by Robert Tipton¹.
 - Comparison with Kull shows reasonable agreement for very different methodologies.
 - For more details see Brody's paper².





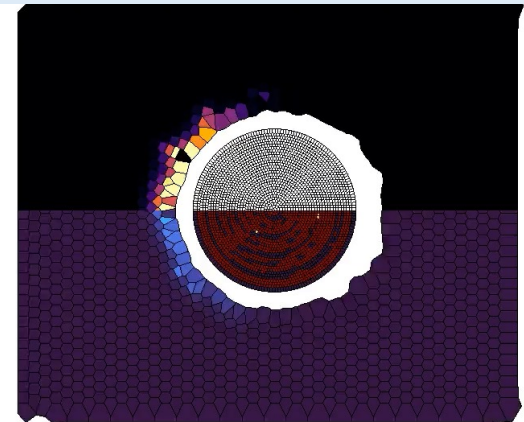
Fluid-Solid Interface Smoothed Particle Hydrodynamics

Work with Jason Pearl and Cody Raskin

Compressible flows with high-density ratio materials in contact requires some special treatment.

- Our target problem is following the entry, breakup, and energy deposition from small asteroids (or bolides) in Earth's atmosphere.
 - This problem entails high-Mach number flows (with entry velocities ~ 20 km/sec) and density contrasts $\sim 10^4$
 - Requires compressible and solid hydrodynamics, porosity, damage modeling, fracture and failure with strong shocks.
- The standard symmetrized momentum equation in SPH methods results in an artificial repulsion between points with differing masses.
 - In our case with mass ratios $\sim 10^4$ between air and rock nodes this error is unacceptable.

Standard SPH model of bolide in air



FSISPH¹ modifies the standard SPH equations explicitly to handle interfaces with high density contrasts.

- We bring together components of other discretizations combined with a few newish tidbits at interfaces.

$$\begin{aligned} \frac{D\rho_i}{Dt} &= -2\rho_i \sum_j \frac{m_j}{\rho_j} (v_i^\alpha - v_*^\alpha) \partial_\alpha W_i & \rho_i &= \sum_j m_* W_i & \Pi_{ij} &= \frac{\rho_i \rho_j}{\rho_i + \rho_j} C_l c_{ij} \mu_{ij} + C_q \mu_{ij}^2 \\ \frac{Dv_i^\alpha}{Dt} &= \frac{m_j}{\rho_i \rho_j} \left(\sigma_i^{\alpha\beta} \partial_\beta W_i - \sigma_j^{\alpha\beta} \partial_\beta W_j \right) & m_* &= \begin{cases} m_j, & \text{same material} \\ m_i, & \text{different material} \end{cases} & v_{ij}^{\dagger\alpha} &= v_i^\alpha - v_j^\alpha - \frac{\phi_{ij}}{2} (\partial_\beta v_i^\alpha + \partial_\beta v_j^\alpha) x_{ij}^\alpha \\ \frac{Du_i}{Dt} &= 2 \sum_j \frac{m_j}{\rho_i \rho_j} \left(\sigma_i^{\alpha\beta} \partial_\beta W_i (v_i^\alpha - v_*^\alpha) \right) & & & \mu_{ij} &= \max(-v_{ij}^{\dagger\alpha} \hat{x}_{ij}^\alpha, 0) \end{aligned}$$

- GDF (geometric density averaged force)²** helps with differing node masses
- HLLC reconstructed interface velocity** at material boundaries¹
- Second-order artificial viscosity** improves shock capturing³

¹Pearl, J.M., Raskin, C.D., Michael Owen, J., 2022. FSISPH: An SPH formulation for impacts between dissimilar materials. JCP 469, 111533.

²Wadsley, J.W., Keller, B.W., Quinn, T.R., 2017. Gasoline2: a modern smoothed particle hydrodynamics code. Mon. Not. R. Astron. Soc. 471, 2357.

³Frontiere, N., Raskin, C.D., Owen, J.M., 2017. CRKSPH – A Conservative Reproducing Kernel Smoothed Particle Hydrodynamics Scheme. JCP 332, 160–209



For the bolide problem we need to add explicit surface treatments at material interfaces.

Velocity discontinuity leads to overactive artificial viscosity

At slip interfaces reduce the viscous pressure by a scalar factor

$$P_{visc} \rightarrow P_{visc} f_{ij}$$

$$f_{ij} = (1 - s_{ij}) + s_{ij} \hat{v}_{ij} \cdot \hat{n}_{ij}$$

s_{ij} - surface smoothness ranges between 0 and 1 used to turn off slide surface when interface and normals are poorly defined.

\hat{n}_{ij} - orientation of surface normal

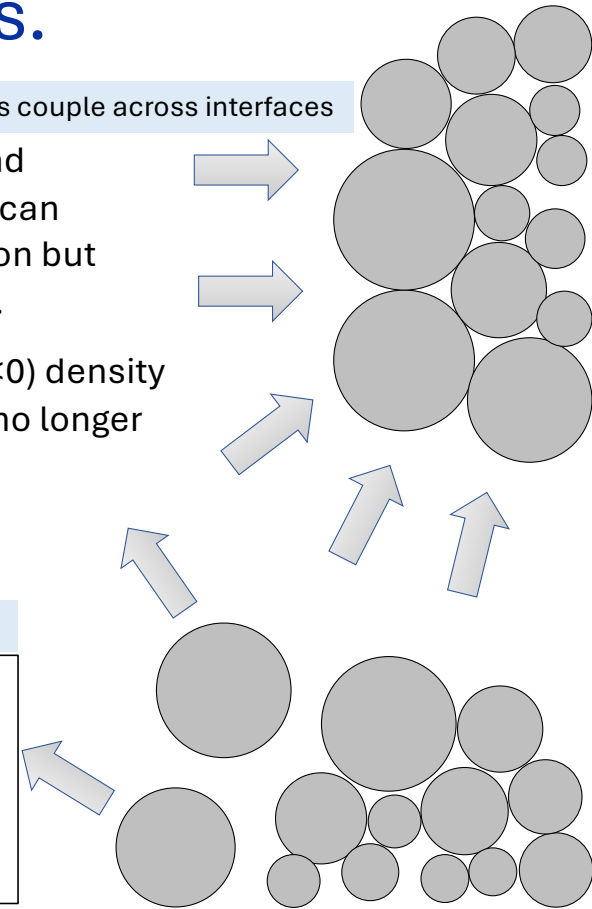
In compression materials couple across interfaces

Damaged rubble and material interfaces can support compression but separate in tension.

After separation ($P < 0$) density and energy should no longer evolve

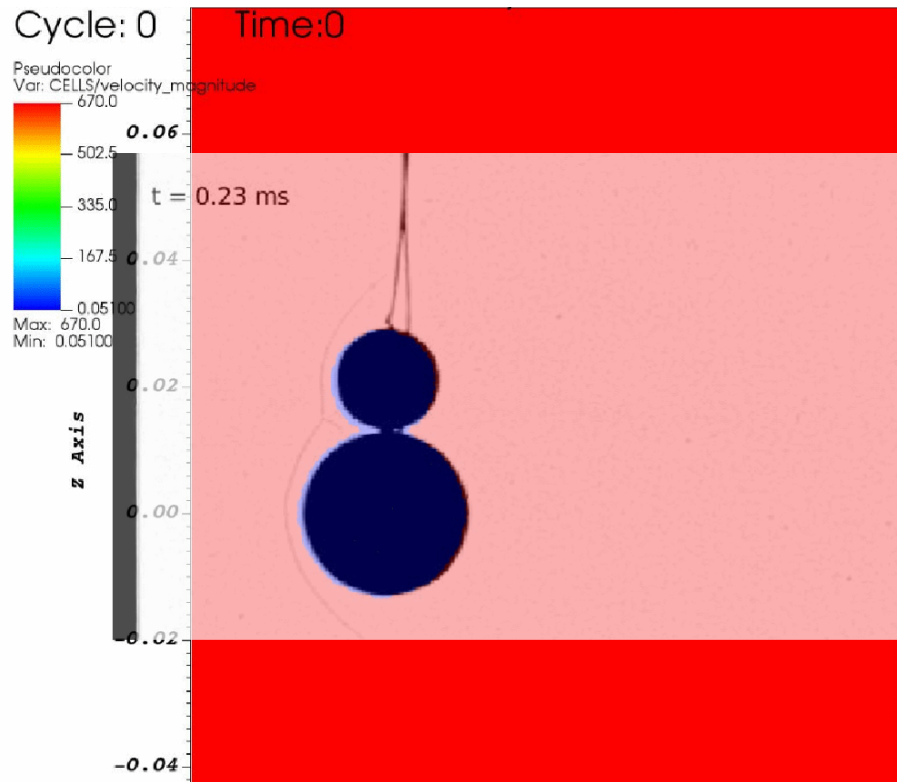
Interfaces decouple if:

- Pairwise tensile force
- Particles separating
- Different materials or pairwise interaction is fully damaged

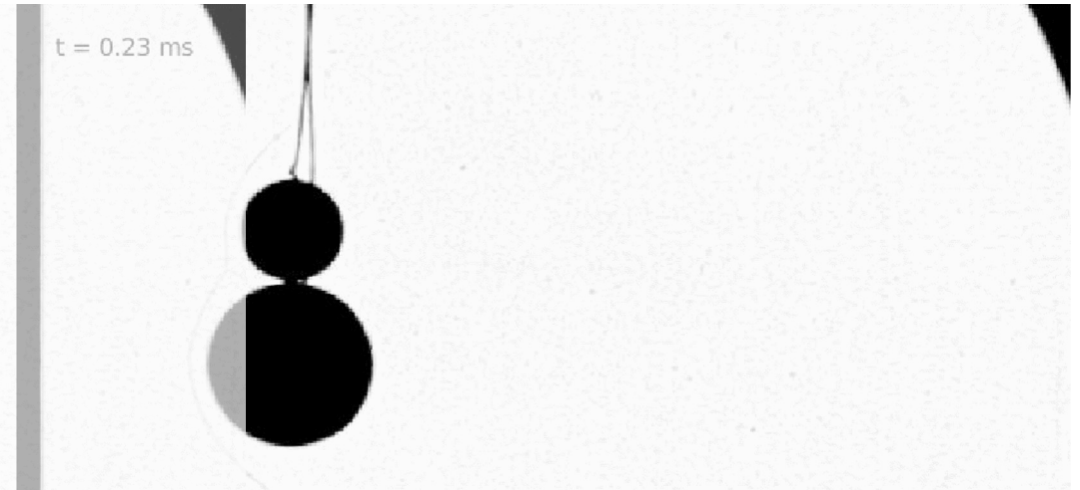




FSISPH performs well modeling the separation of spheres in experimental wind tunnel tests¹.



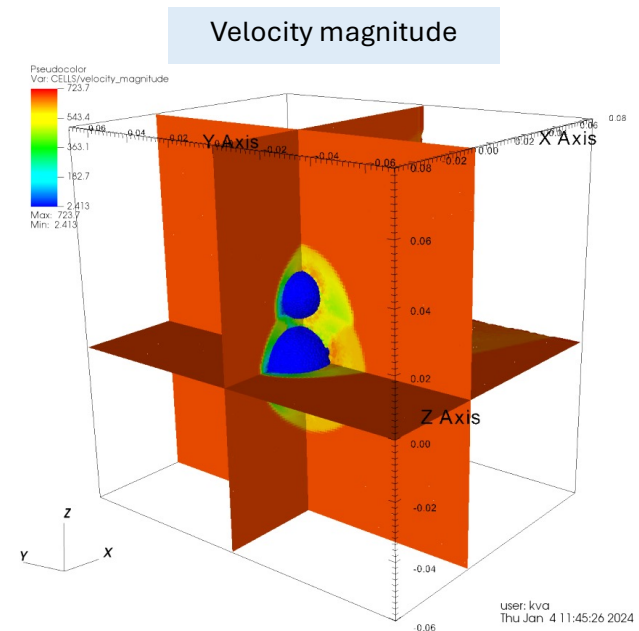
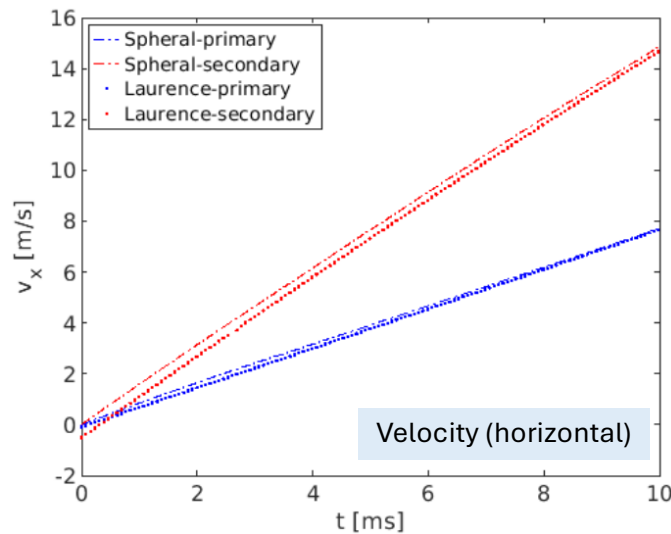
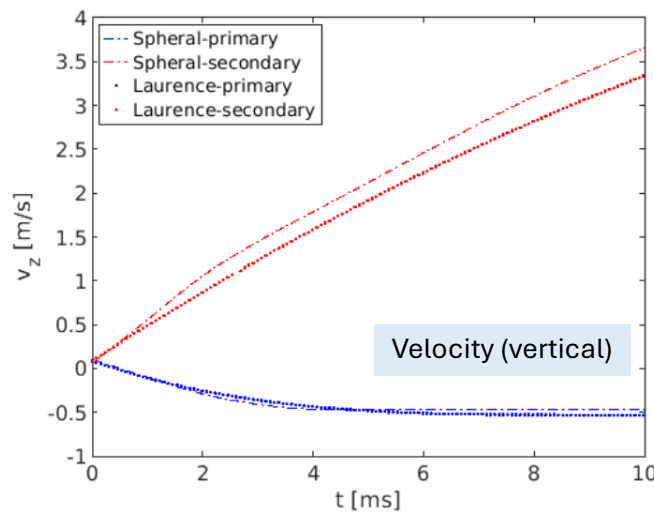
Simulation



Experiment

This experiment provides a nice test of capturing supersonic flow around solid bodies.

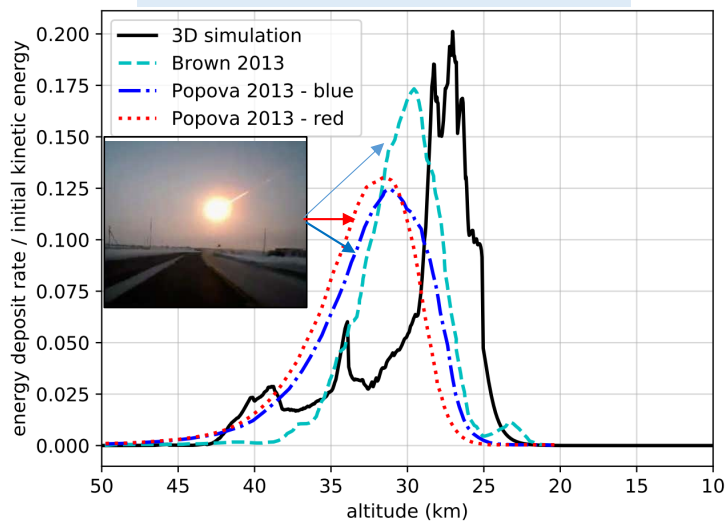
- Interacting solid bodies in high-speed flow, Laurence et al (2012)¹
 - Align two Nylon spheres along the lateral axis
 - Flow air ($\gamma = 1.4$) at $M \sim 4$ along the longitudinal axis for approx. 10 [ms]
 - Features: Bow-shock ‘riding’ and shock-shock interaction
 - Analogous to the physics of an asteroid body breaking apart in atmosphere



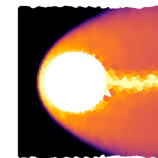
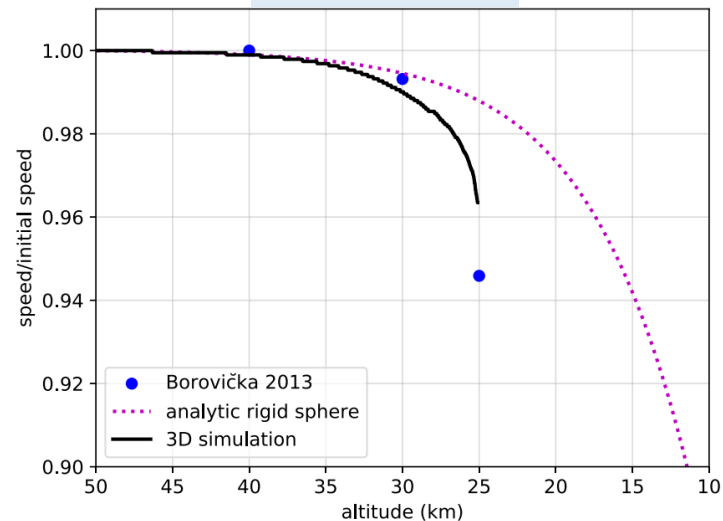
The airburst over Chelyabinsk in 2013 is a real-world example of the events we're working to understand.

- FSISPH simulations of this event match observations for velocity and energy deposition.
 - Simulated peak luminosity 26-27km, slightly lower than observed peak luminosity of 29-32km based on reconstructions of Brown² and Popova¹.
 - Leading fragment speeds match observations of Borovička³ 2013

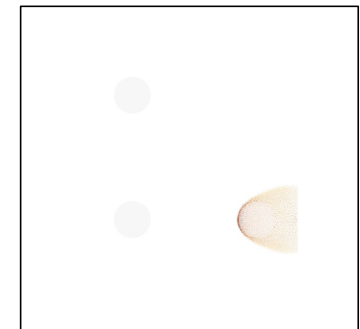
Atmospheric energy deposition rate



Bolide velocity



2D model



3D model

¹O. Popova, et al., Chelyabinsk airburst, damage assessment, meteorite recovery and characterization, Science 342 (2013).
²Brown, P.G et al., A 500-kiloton airburst over Chelyabinsk and an enhanced hazard from small impactors, Nature 503 (7475), 238–241, (2013).
³Borovička, J., et al., The trajectory, structure and origin of the Chelyabinsk asteroidal impactor, Nature 503, 235–237, (2013).
⁴Pearl, J.M., et al., 2023. Insights into the failure mode of the Chelyabinsk meteor from high-fidelity simulation. Icarus 404.

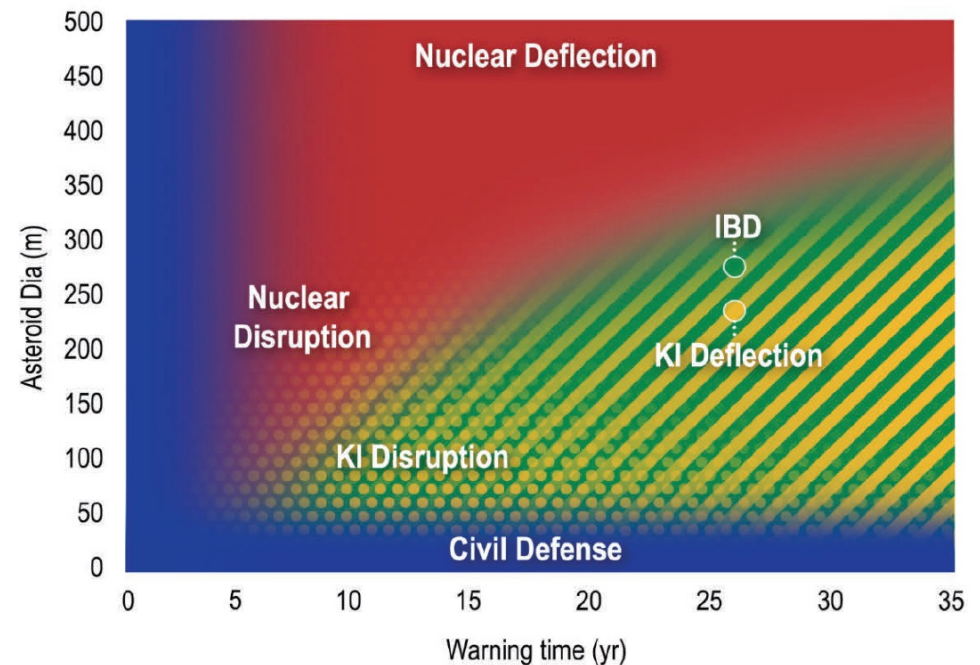


Planetary Defense: diverting hazardous asteroids

Work with Kathryn Kumamoto, Jason Pearl, Veronika Korneyeva, Megan Bruck Syal, Mary Burkey, Rob Managan, and others

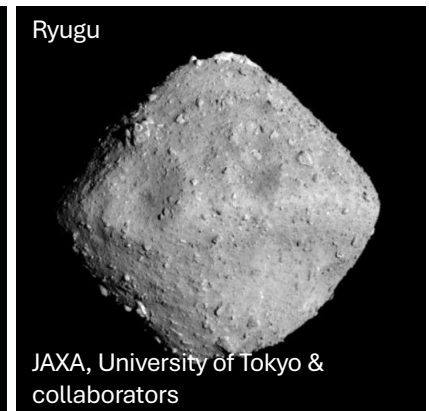
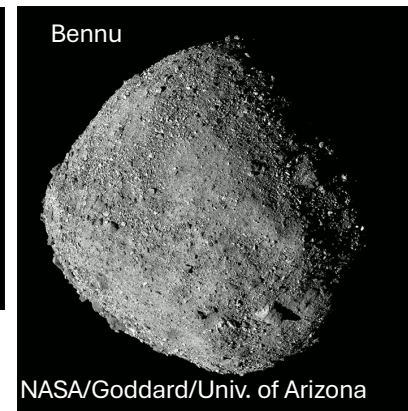
We are researching methods to mitigate (or better understand) the risks from asteroids impacting the Earth.

- FSISPH was developed to study the risk of airburst from bolides as part of this overall research.
- The best response depends on the warning time and size of the object.
 - Small object: civil defense preparation
 - For progressively larger objects (or shorter warning times) we have to escalate our response:
 - Ion-beam/gravity tractor (“slow push”)
 - Kinetic impactor (KI) deflection
 - Nuclear Explosive Device (NED) deflection
 - KI or NED disruption for short warning times



Asteroids are not simple objects: most in the hazardous size range are most likely “rubble-piles”.

- Recent missions such as DART (Dimorphos), Osiris-REx (Bennu), and Hayabusa I and II (Itokawa and Ryugu) have found rubble-pile structures to be the norm.



- Much of the risk is due to objects ~100's of m in diameter.
 - Self-gravitation is very low
 - Escape velocities are typically ~10's cm/sec
 - Loosely bound, highly porous ($\phi \sim 20\%-80\%$) objects
 - Porosity probably a mixture of micro- and macro-porosity: i.e., porous boulders with voids between them.
- Rule of thumb: imparting $\Delta v > 10\%$ escape velocity risks disruption of the body!

Kinetic impactors or nuclear explosives are the best understood options for deflecting an asteroid.

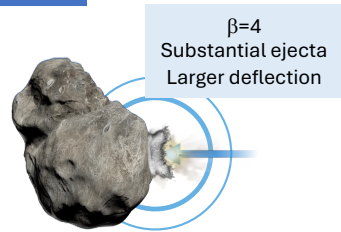


Kinetic Impactor

- Kinetic impactor momentum transfer enhanced by ejecta

$$\beta \equiv 1 + \frac{m_{\text{ejecta}} v_{\text{ejecta}}}{m_{\text{spacecraft}} v_{\text{spacecraft}}}$$

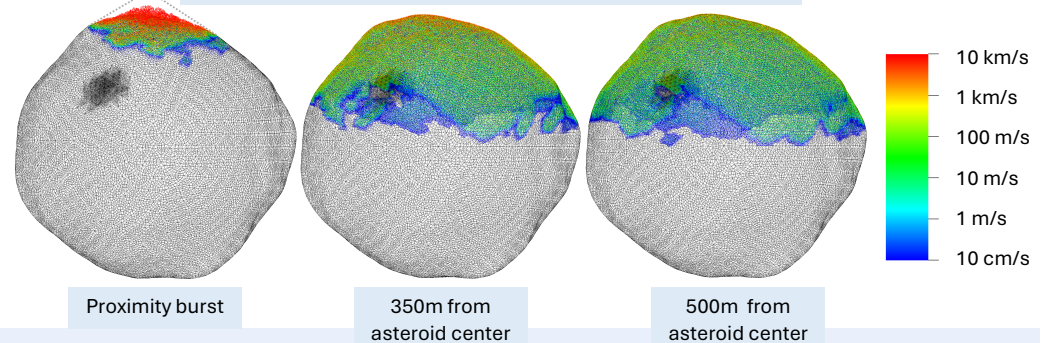
Filed Boundary
 Via: MANTIS/LLNLM230
 -1 Asteroid model
 -2 Impactor A1
 -3 Impactor S1
 -4 Impactor S1
 -5 Impactor 16A1



Nuclear Explosives

- Nuclear deflection uses energy deposited by a standoff explosion (via X-rays) to heat and ablate material from asteroid surface.
- Ablated material (and material ejected by the subsequent shock) imparts momentum to the asteroid.
- The effective push applied is adjustable by changing standoff distance.

1 Mt NED, 2 keV blackbody spectrum, 65% energy reradiated





Damage, fracture, and ejecta modeling are key challenges in understanding asteroid mitigation.

- This requirement is a big reason meshfree methods are useful for this problem – robust Lagrangian discretizations are very well-suited for following damage, fracture, and ejecta.
- We also have extreme resolution requirements:
 - Overall objects are 100's of meters to a few kilometers in size
 - KI impact modeling typically requires on the order of cm's resolution
 - Resolving ablation from X-rays is even worse: we require microns at the ablating surface
- For impact problems we typically feather the resolution from fine at the impact site to coarser with distance.
 - Requires generalizing standard damage modeling algorithms (like Benz-Asphaug model) to properly allow varying resolution.
- The nuclear ablation surface additionally requires ASPH (Adaptive SPH with elliptical smoothing volumes) with fine resolution aligned with depth at the surface.
 - Aspect ratios for some cases are $\sim 10^4$ - 10^5 , which required new ASPH development as well.

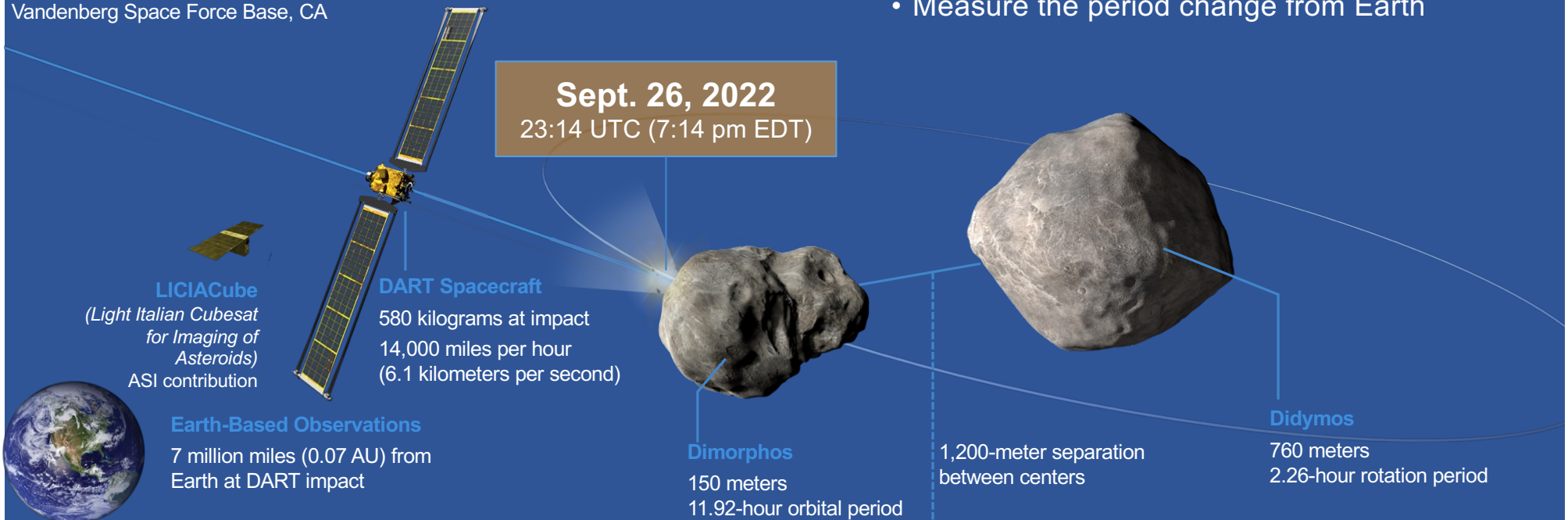


NASA's DART mission was humanity's first planetary defense test mission and demonstrated a kinetic impact

Launch

Nov. 23, 2021, 10:21 pm PST
Vandenberg Space Force Base, CA

- Target the binary asteroid Didymos system
- Impact Dimorphos and change its orbital period
- Measure the period change from Earth

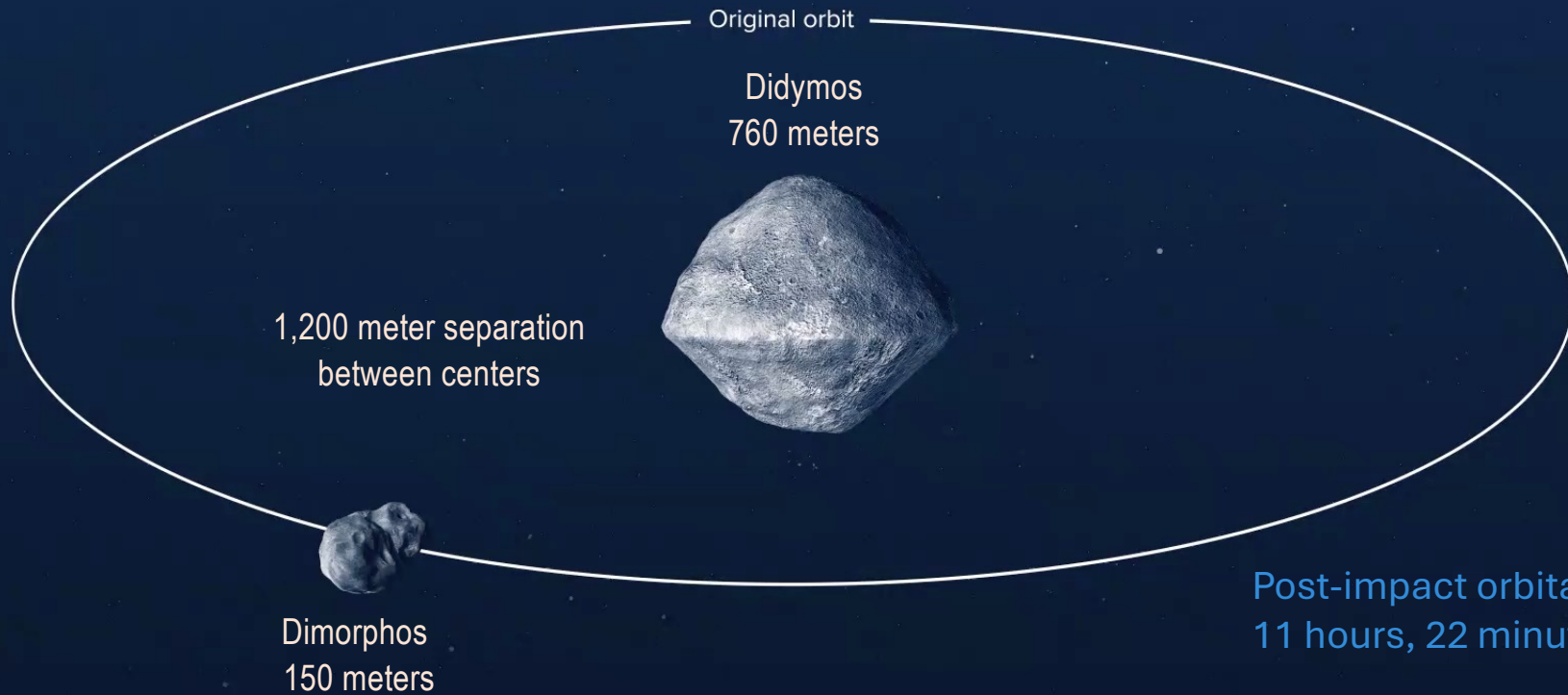




DART

Double Asteroid Redirection Test

Pre-impact orbital period:
11 hours, 55 minutes



Post-impact orbital period:
11 hours, 22 minutes



Earth-based
observations

DART camera feed on final approach to Dimorphos



**Sept 26 7:10 - 7:15 pm
EST**
DRACO images
streamed to Earth from
7 million miles away
10x speed

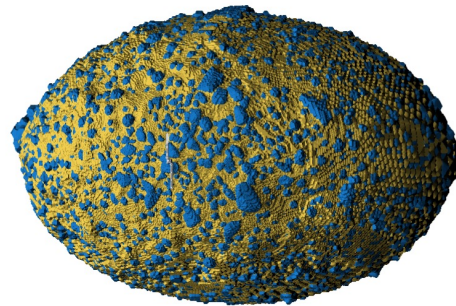
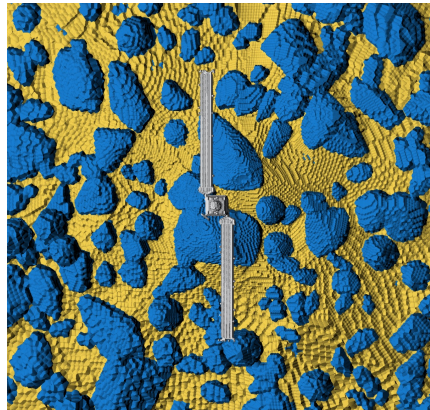




Reproducing all aspects of the DART impact requires modeling the complex geometry and materials of the system.

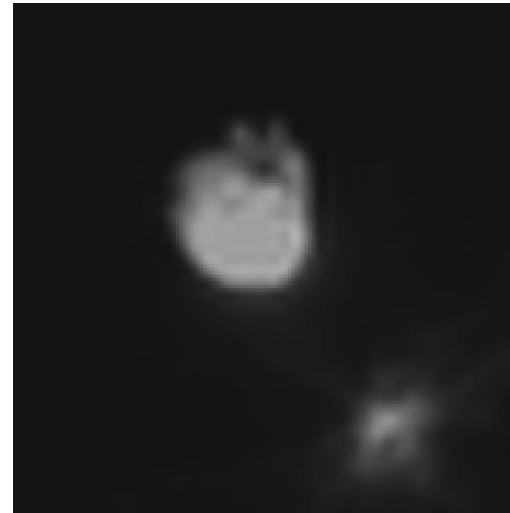


Image credit: NASA/JHUAPL

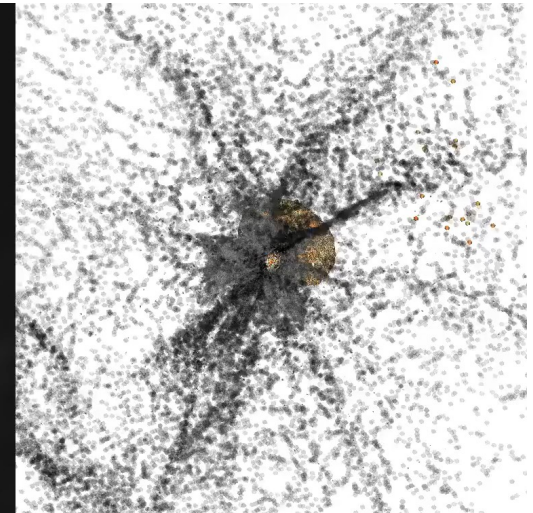


Yellow = matrix
Blue = boulders

LICIACube images



Spherical simulation

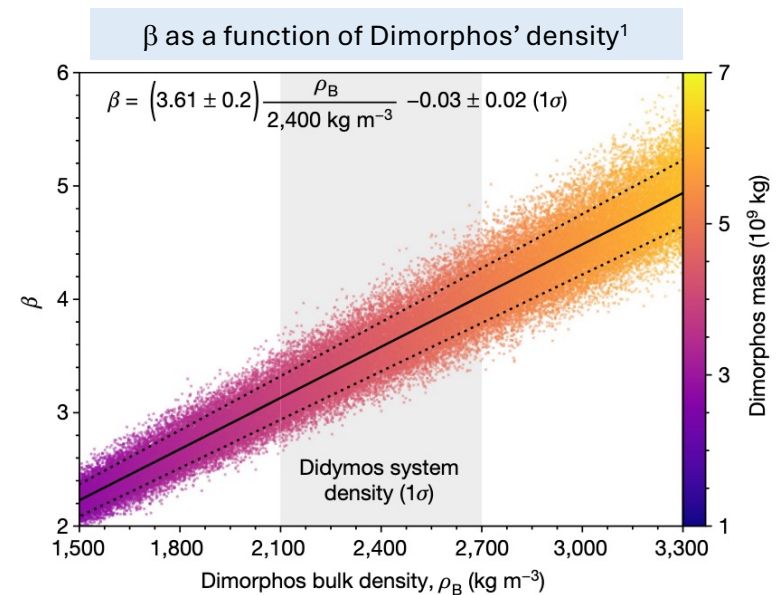


Simulations to match the outcome require:

- Multiple materials: Matrix, boulders, spacecraft (Al, SS, Ti, Si)
- Precisely recreating local topography and spacecraft geometry
- High resolution at the impact site
- Analyzing a degenerate, multi-dimensional space

Modeling is essential to understanding the full outcome of the DART mission, but is challenging.

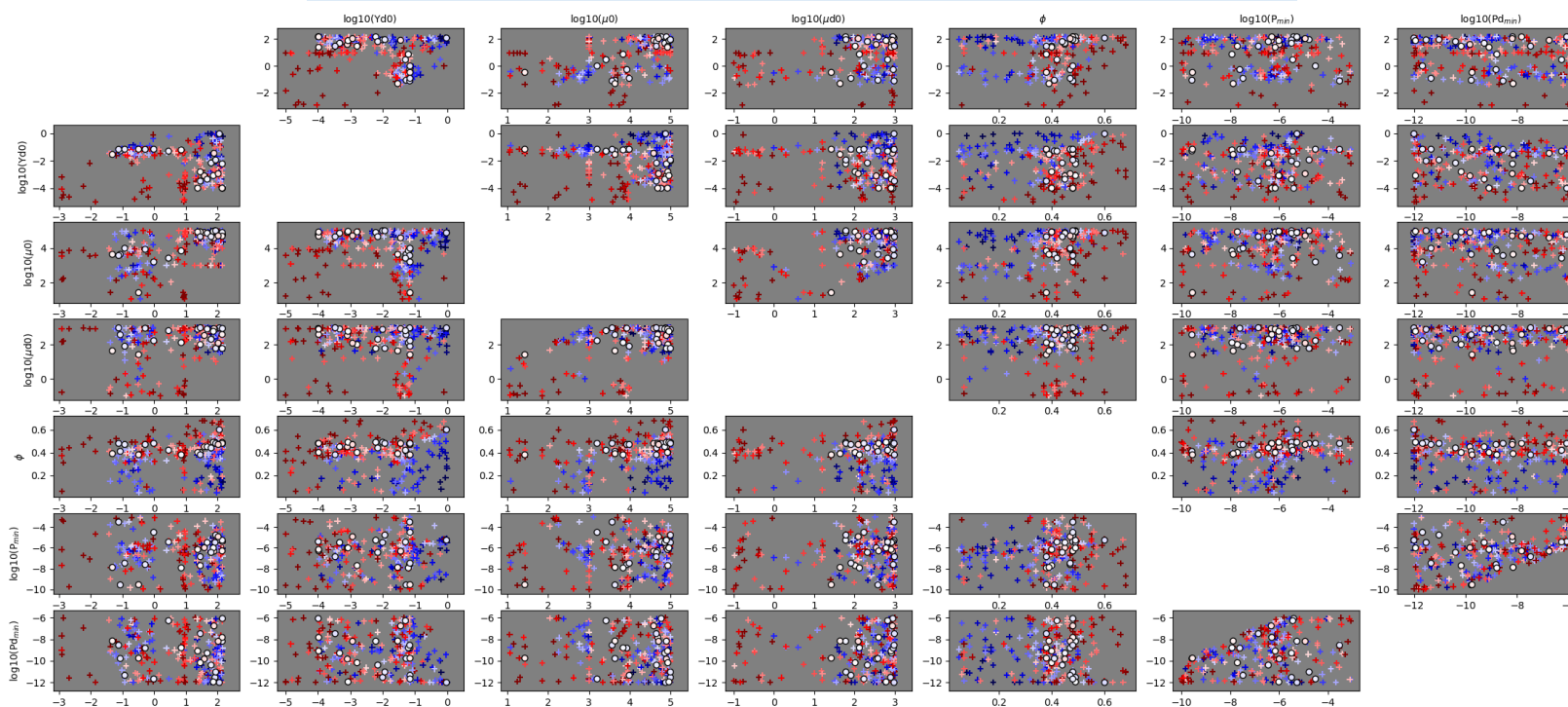
- Much comes down to material modeling (cohesion, porosity, yield strength intact and damaged, damage parameters, etc.)
 - These are all unknown to various degrees for asteroids and so involve multi-dimensional parameter sweeps.
 - Incredibly weak objects with low-gravity, so ejecta production goes on for many minutes
 - Simulating to such late times with explicit time-steps in the μs adds to the challenge.
- Our primary concern for planetary defense (PD) is the momentum enhancement (β).
 - Unfortunately this measurement is degenerate until we get a measurement of Dimorphos' density.
 - $\Delta v \sim 2.7$ mm/sec from orbital period change
 - ESA Hera mission should tell us more!



Testing the phase space of possible material parameters requires many hundreds of 3D models.

- The robustness of meshfree models is key – no babysitting calculations that need to be launched automatically.

Parameter sweep of material properties to match observed deflection¹

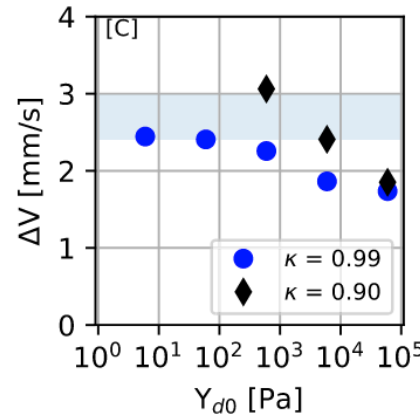




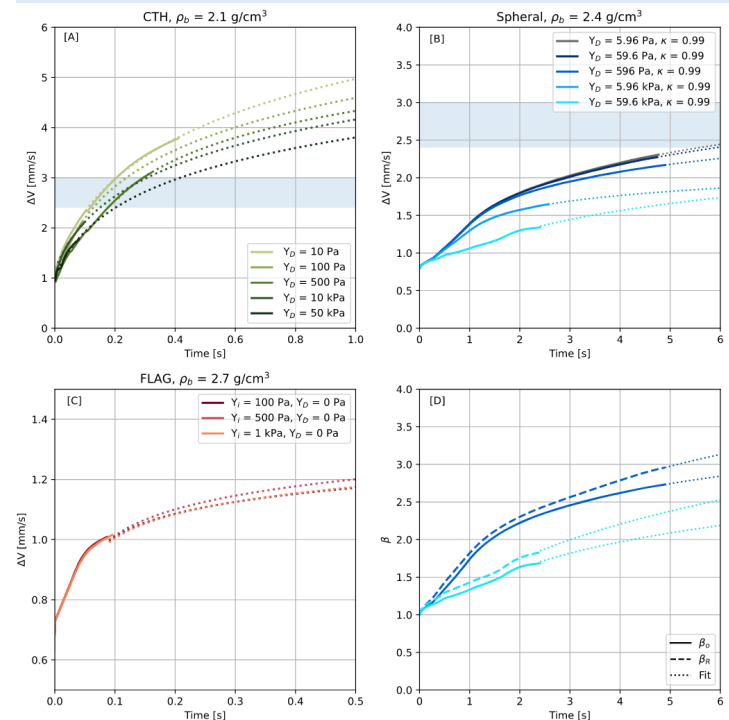
Varying material properties we can match the observed deflection velocity from DART.

- However, we must also match all properties we know of
 - The observed duration of ejecta production and overall total mass ejected
 - The final crater size and shape (TBD by Hera?)
- Our overall goal is to understand the implications for planetary defense.
- It appears $\beta \approx [2, 3]$, but this is only one data point!
 - Asteroid properties have large variations between different populations.
 - One point is better than none!

Extrapolated Δv for different porosity compaction laws¹



Δv time histories for different material strengths¹



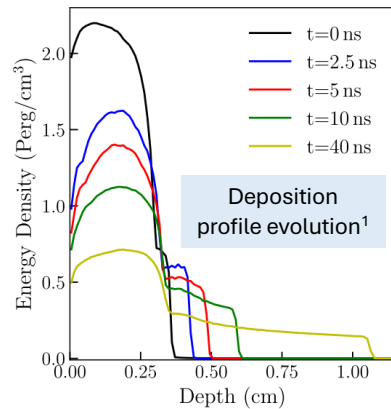
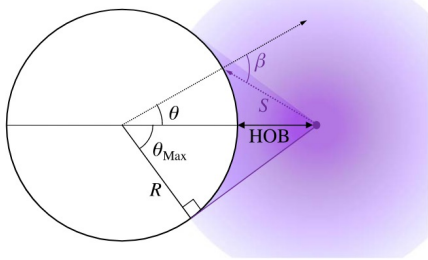


Nuclear deflection involves two phases dominated by different physics on very different timescales.

X-Ray Energy Deposition

- X rays penetrate 1 μm – 1 cm into the material, causing heating and ionization. Some energy re-radiates away.
- Only a full radiation-hydrodynamics code can cover all the physics that is happening in this process.
- Timescales in the nanosec – μsec range

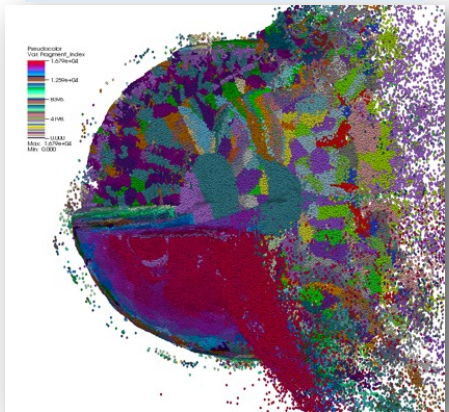
Geometry for deposition surface¹



Hydrodynamics

- Everything that happens after the energy deposition.
- The deposited energy causes material to begin moving and expanding
- At this point, a standard hydrocode can follow the material's movement and energy.
- Shock physics, fracture, failure, and ejecta dominate evolution.
- Timescales from seconds -- hours

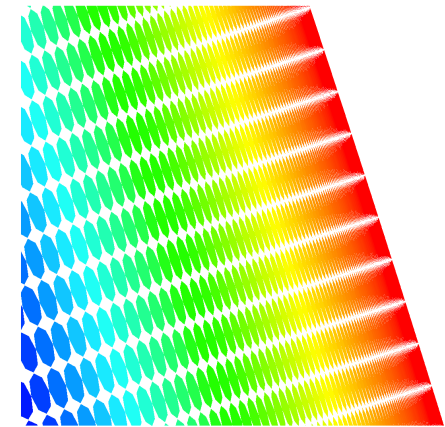
Robust disruption and dispersal of fragments due to shock from ablation physics



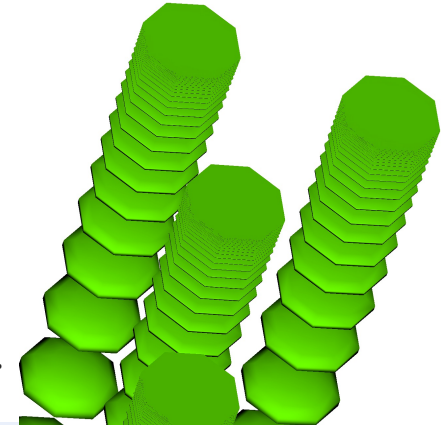


The major challenge with following the ablation driven shock and subsequent evolution is the required resolution.

- In order to resolve the energy deposition profile with depth we need resolutions $\sim \mu\text{m}$.
- The overall asteroid shapes are typically 100's m across, so uniform resolution is unobtainable.
- Fortunately the ablation driven shock rapidly relaxes these resolution constraints away from the surface.
- Adaptive SPH^{1,2} with arbitrary ellipsoidal kernel shapes makes this possible.
- Even with ASPH is this an extremely challenging problem, and we are still developing improvements to handle this problem.
 - Compatible SPH, FSISPH, and CRKSPH are all effective for this problem.



2D ASPH elliptical kernels

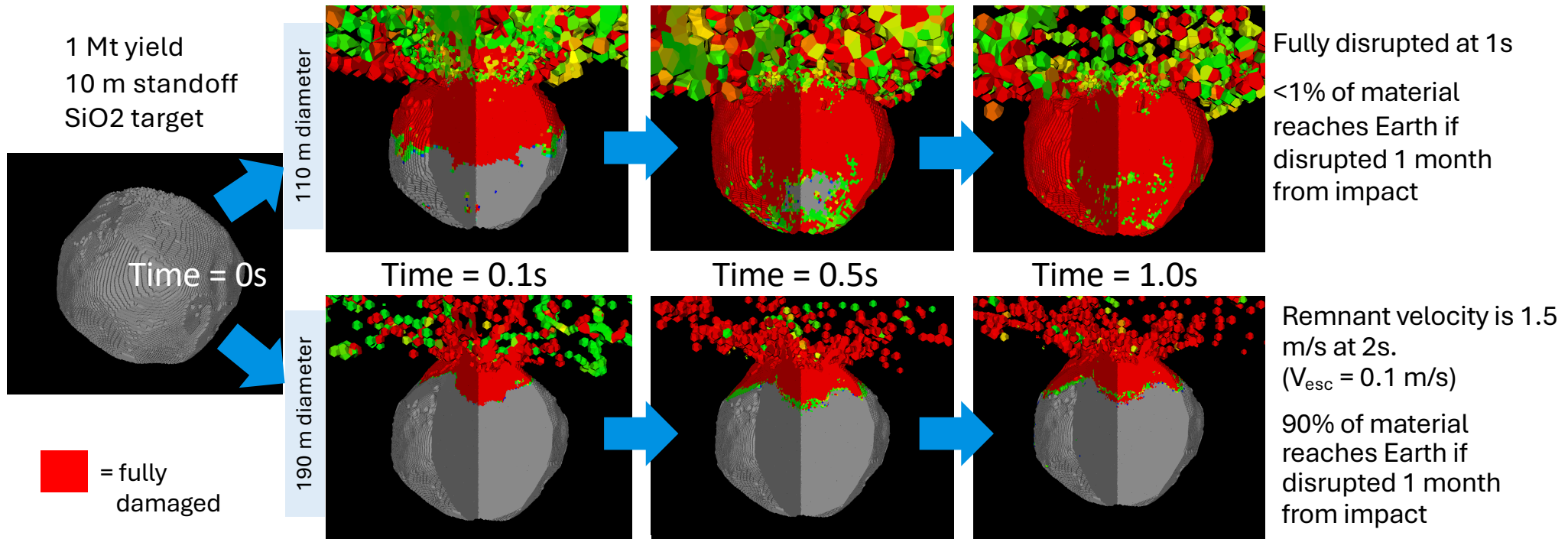


3D ASPH ellipsoidal kernels



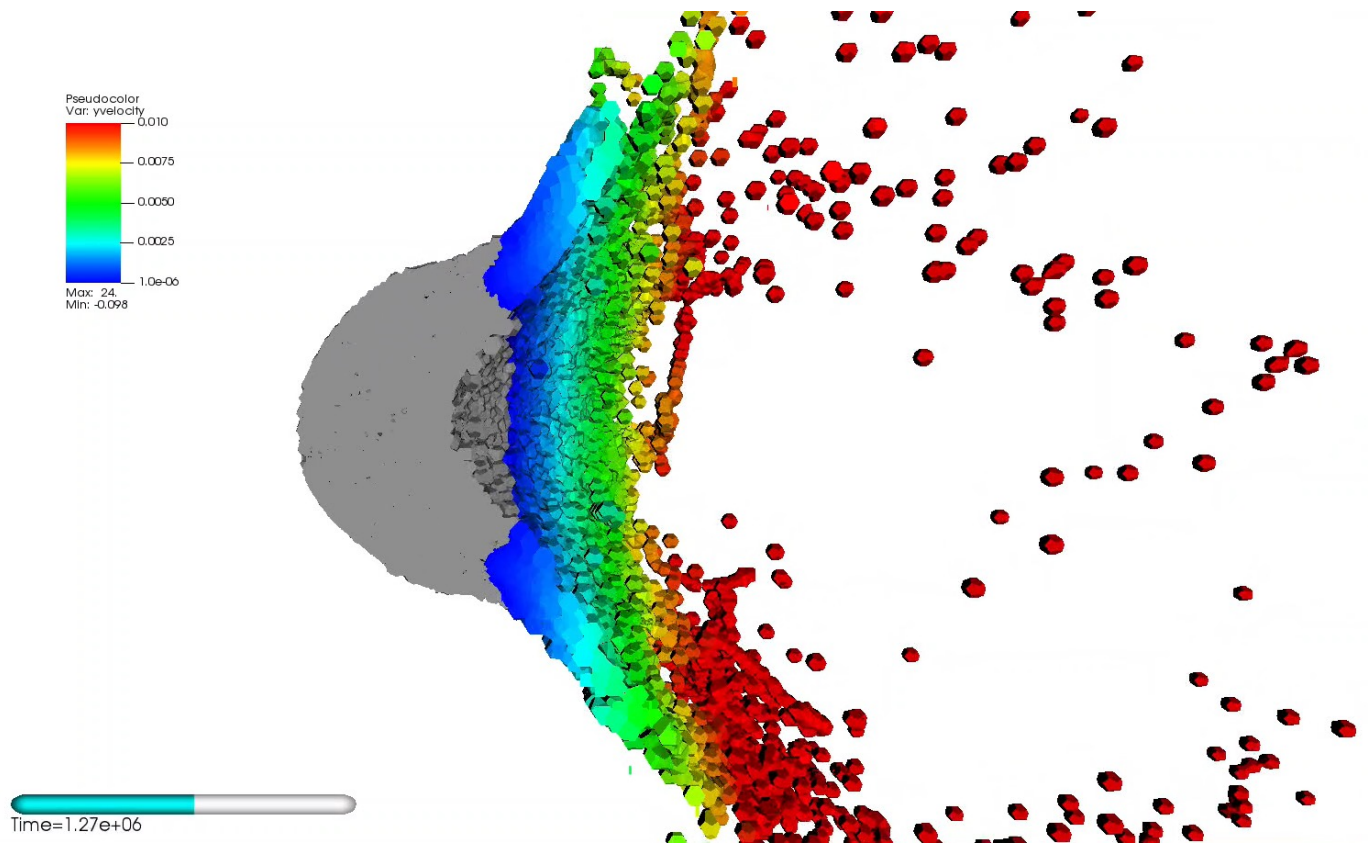
Whether we deflect or disrupt an asteroid depends on both standoff distance and asteroid size.

- We may not know all the properties of the asteroid before encounter!





When in doubt or the timeline is short, disrupting the target asteroid robustly may be the best option.



Designing the best discretization is not a one solution fits all proposition.



- Broadly speaking meshfree methods can indeed be applied to many sorts of problems.
 - For the cases I've focused on having a robust Lagrangian reference frame is a key advantage.
- Writing the discrete form of the PDE's involved to reproduce the most important properties of the continuum equations is often central to successful models.
 - The long history of mimetic methods is well worth studying for such principles.
- Tradeoffs are necessary – we generally can't have everything.
 - Consistency/accuracy vs. conservation (RK vs. CRKSPH)
 - Robustness vs. higher-order accuracy (SPH variations vs. Reproducing Kernel variants)
 - Robustness to wild differences in materials and densities (FSISPH and the choices therein)
- It seems obvious but is worth repeating, know your problem!
 - What are the important aspects to maintain in your discretization?

Flexibility in your code base is useful to support such varied applications.



- Our code (Spheral¹) is designed to make developing, maintaining, and applying a variety of methods such as we've talked about today natural.
 - Hybrid C++/Python environment – methods can be implemented in either just as easily.
 - Python scriptable interface allows the choice of just the methods you want for the problem at hand.
 - Each of the methods discussed today are available in Spheral (with the exception of the radiation diffusion).
 - The user simply constructs the packages they want to use which can be added to an arbitrary choice of time advancement algorithms.
- New methods are being developed and tested all the time.
 - Discrete Element Method recently added.
 - Riemann SPH (GSPH as well as particular variants like MFM² and MFV²)
 - SVPH (a hybrid which uses a Voronoi tessellation to construct the differencing method)