

MULTIPHYSICS ENGINEERING PROBLEMS IN MARINE RENEWABLE ENERGY

Challenges and Opportunities with SPH

Bonaventura Tagliafiero – June 16, 2025

btagliafiero@gmail.com

This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No: 101109440.

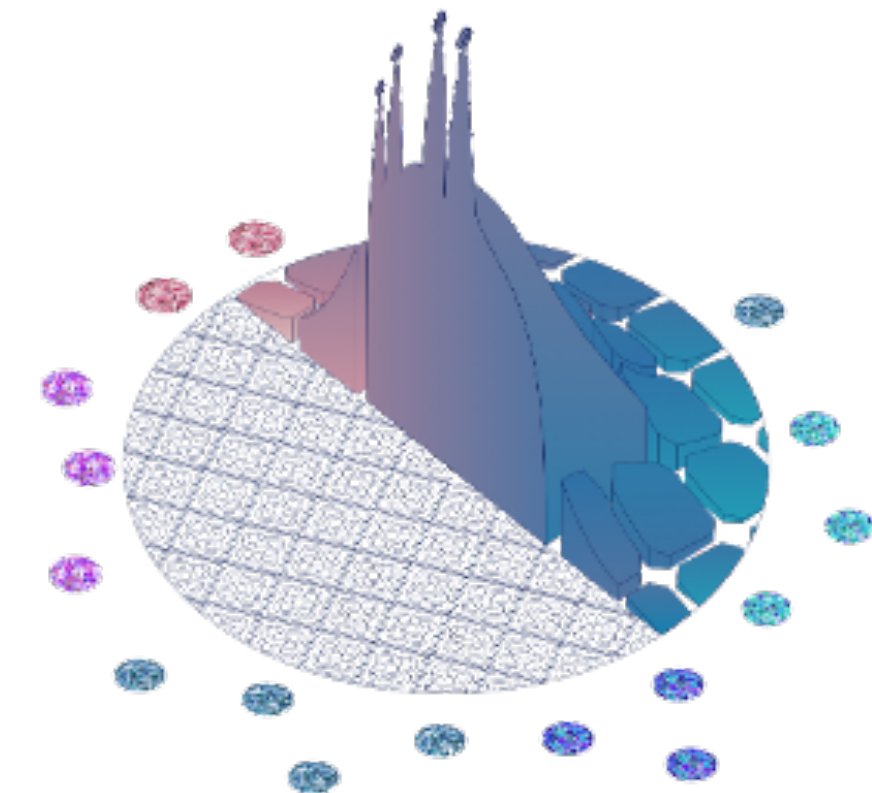


MARIE SKŁODOWSKA-CURIE ACTIONS
Research Fellowship Programme



UPPSALA
UNIVERSITET

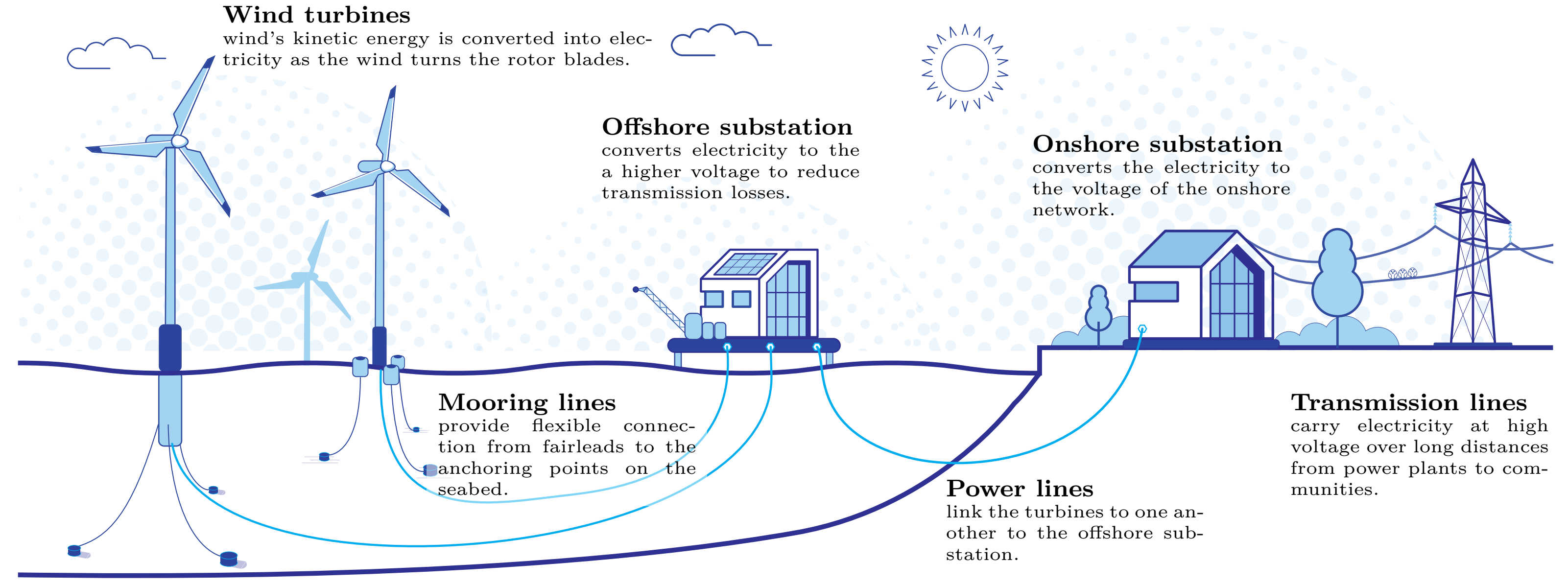
hexicon



The IM-POWER project

Primary goal:
Power output of a floating wind farm under storm conditions

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Our team

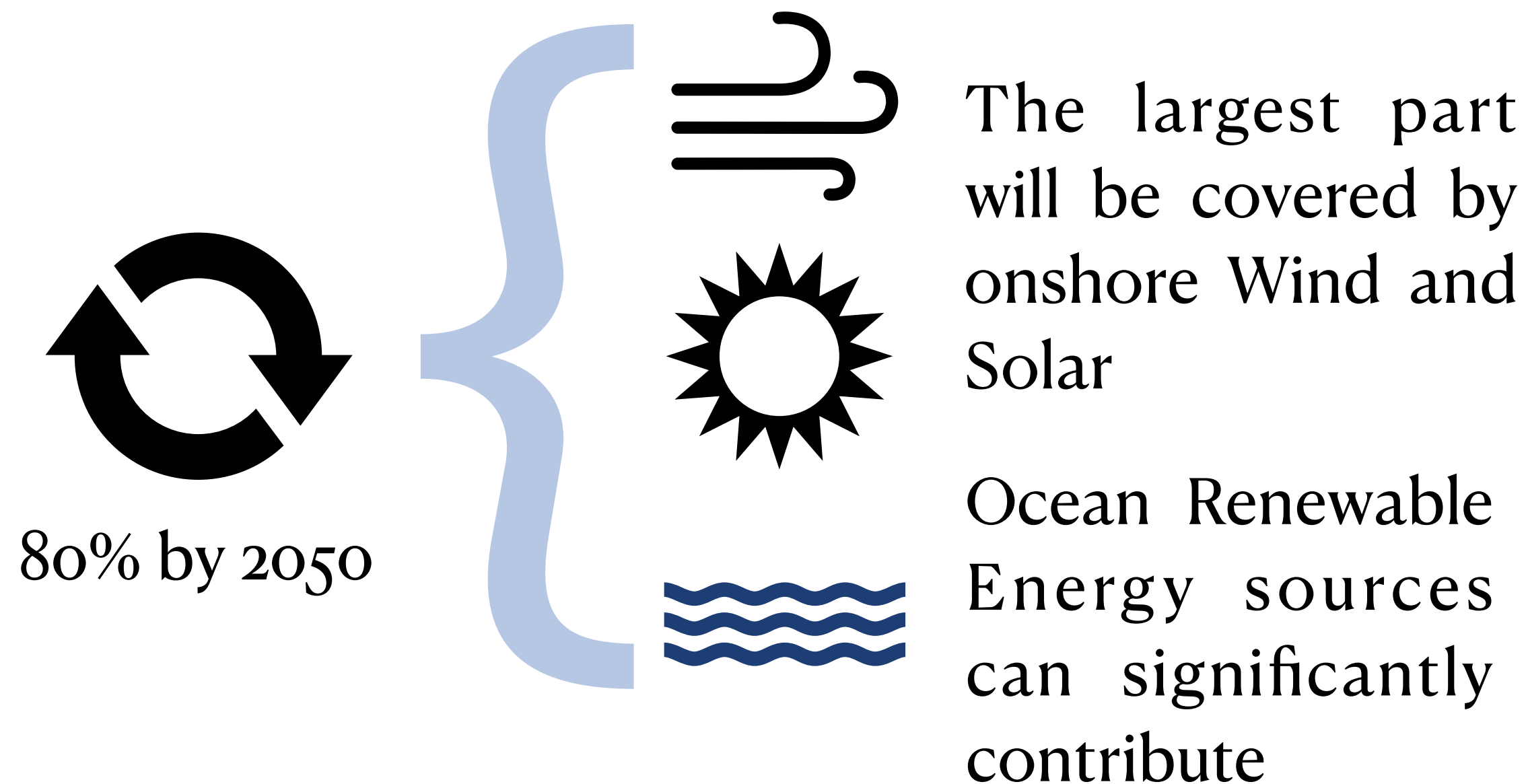
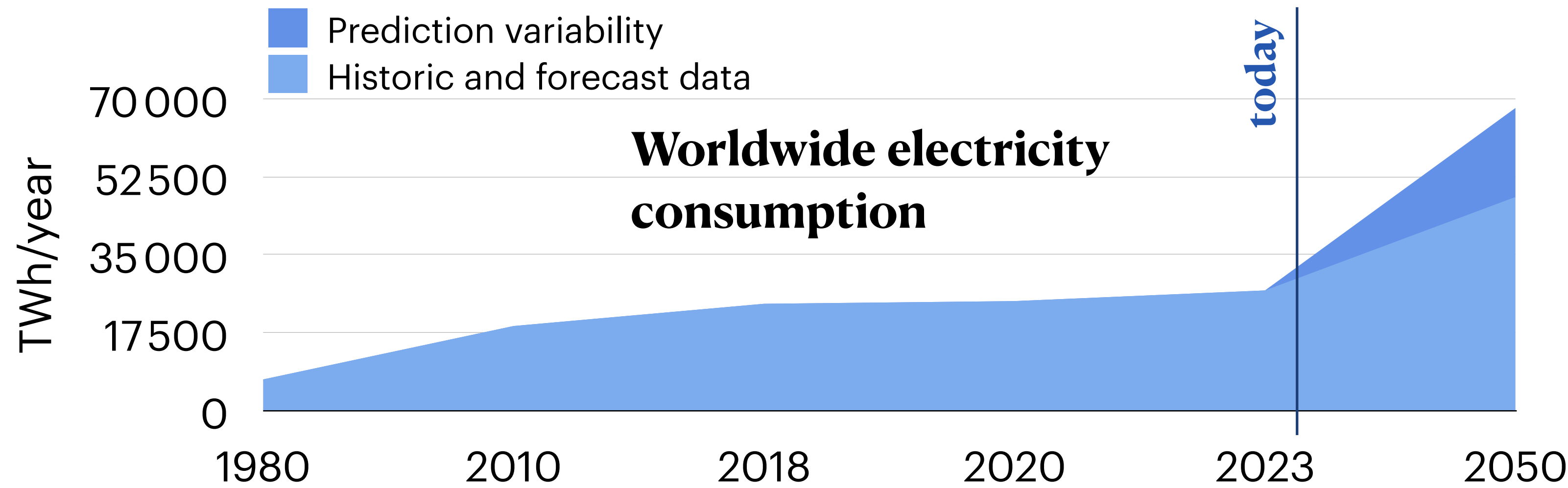
Prof Malin Göteman
Prof Hans Bernhoff

Dr Victor Mendoza
Guilherme Nunes



Outlook on Offshore Renewable Energy (ORE)

The Renewable Contribution?



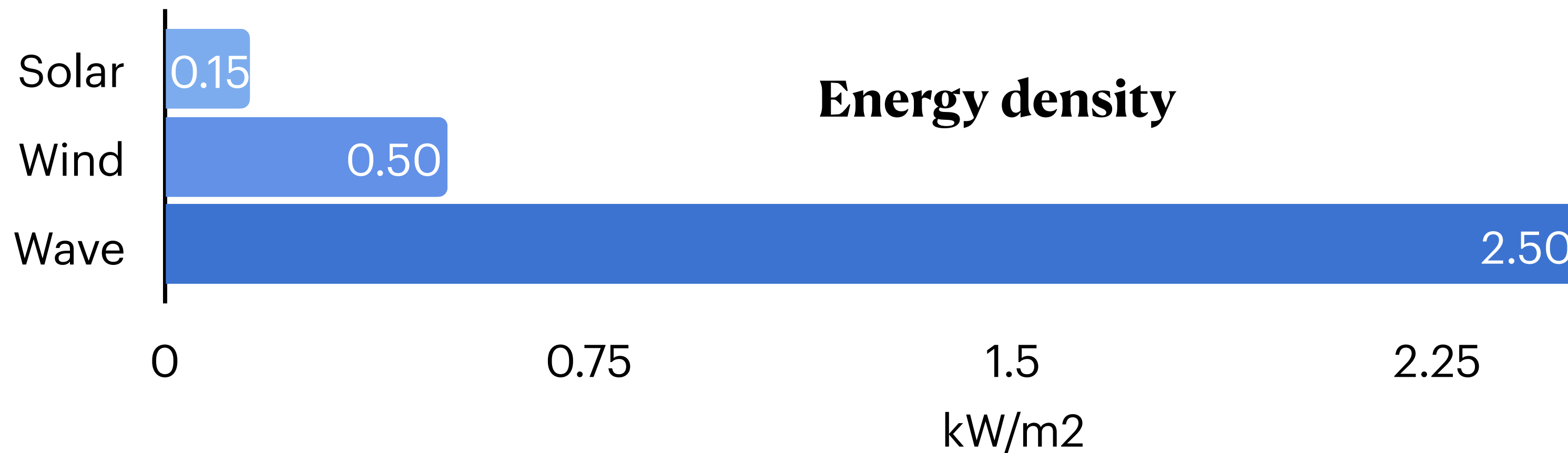
- **Diversification potential**
- **Grid stability**
- **Limit social challenges**
- **Off-grid distribution**

Outlook on Offshore Renewable Energy (ORE)

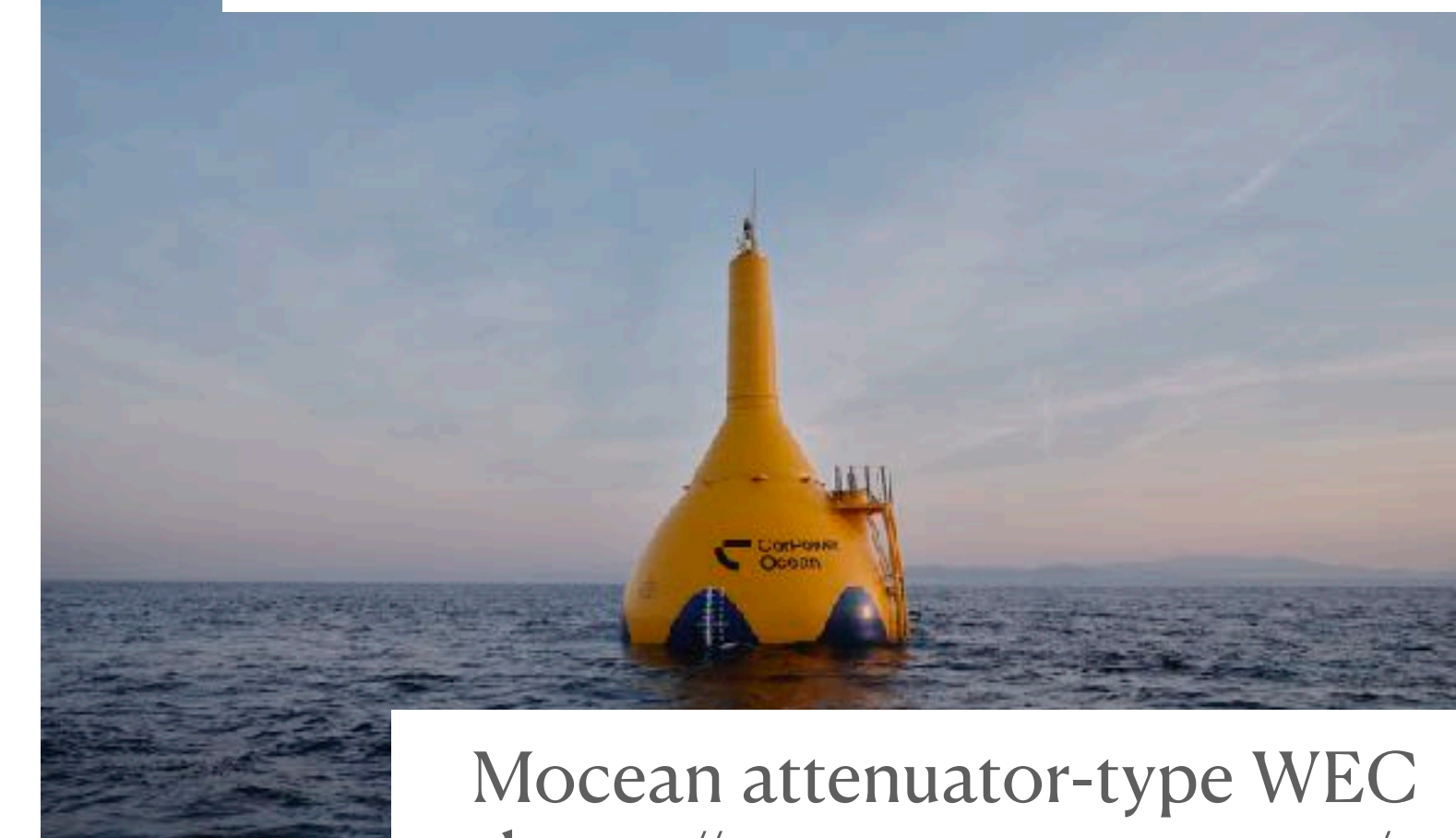
ORE devices:

- Tidal Current turbines
- Floating Photovoltaic panels
- **Floating Offshore Wind Turbines (FOWTs)**
- **Wave Energy Converters (WECs)**

- Abundant resource
- Low variability
- High predictability



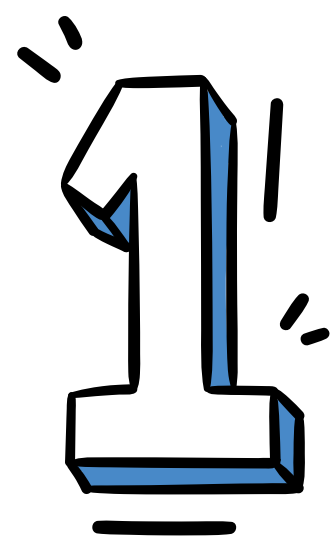
CorPower point absorber-type WEC
<https://corpowersocean.com/wave-energy/>



Mocean attenuator-type WEC
<https://www.mocean.energy/>



Modeling dilemma

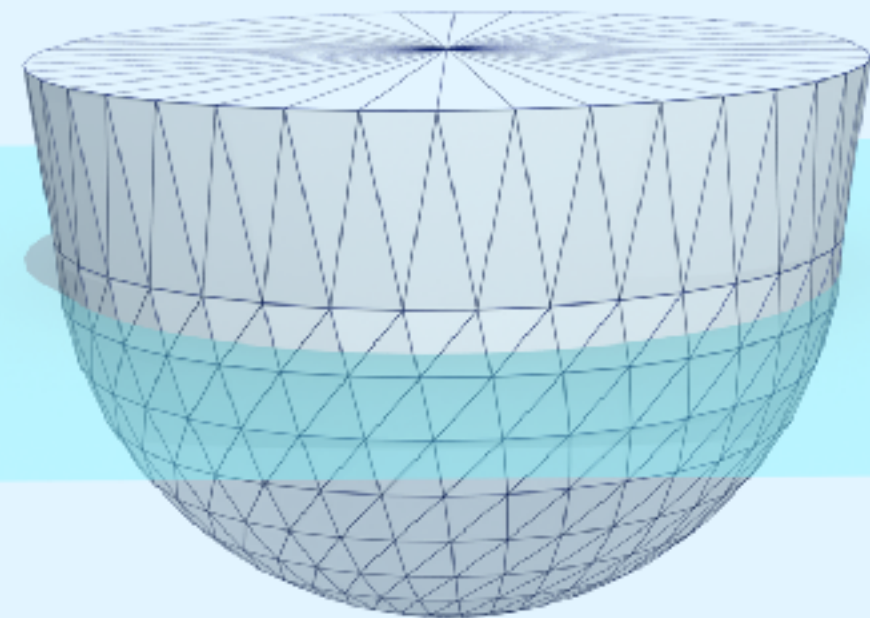


$$\mathbf{M} \ddot{\mathbf{x}}(t) = \mathbf{f}_{hydro}(t) + \mathbf{f}_{PTO}(t) + \mathbf{f}_{mooring}(t)$$

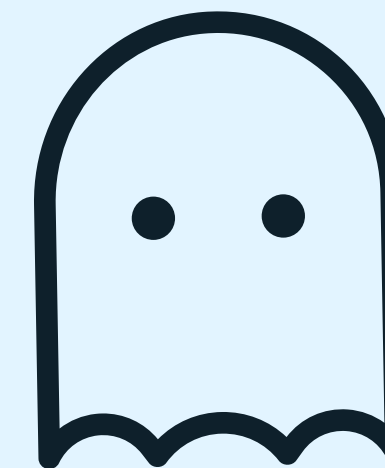
Equation of motion for a rigid body

$$[\mathbf{M} + \mathbf{M}_a] \ddot{\mathbf{x}}(t) + \int_0^t \mathbf{K}(t - \tau) \dot{\mathbf{x}}(\tau) d\tau + \mathbf{R} \mathbf{x}(t) = \mathbf{f}_{exc}(t) + \mathbf{f}_{PTO}(t) + \mathbf{f}_{mooring}(t)$$

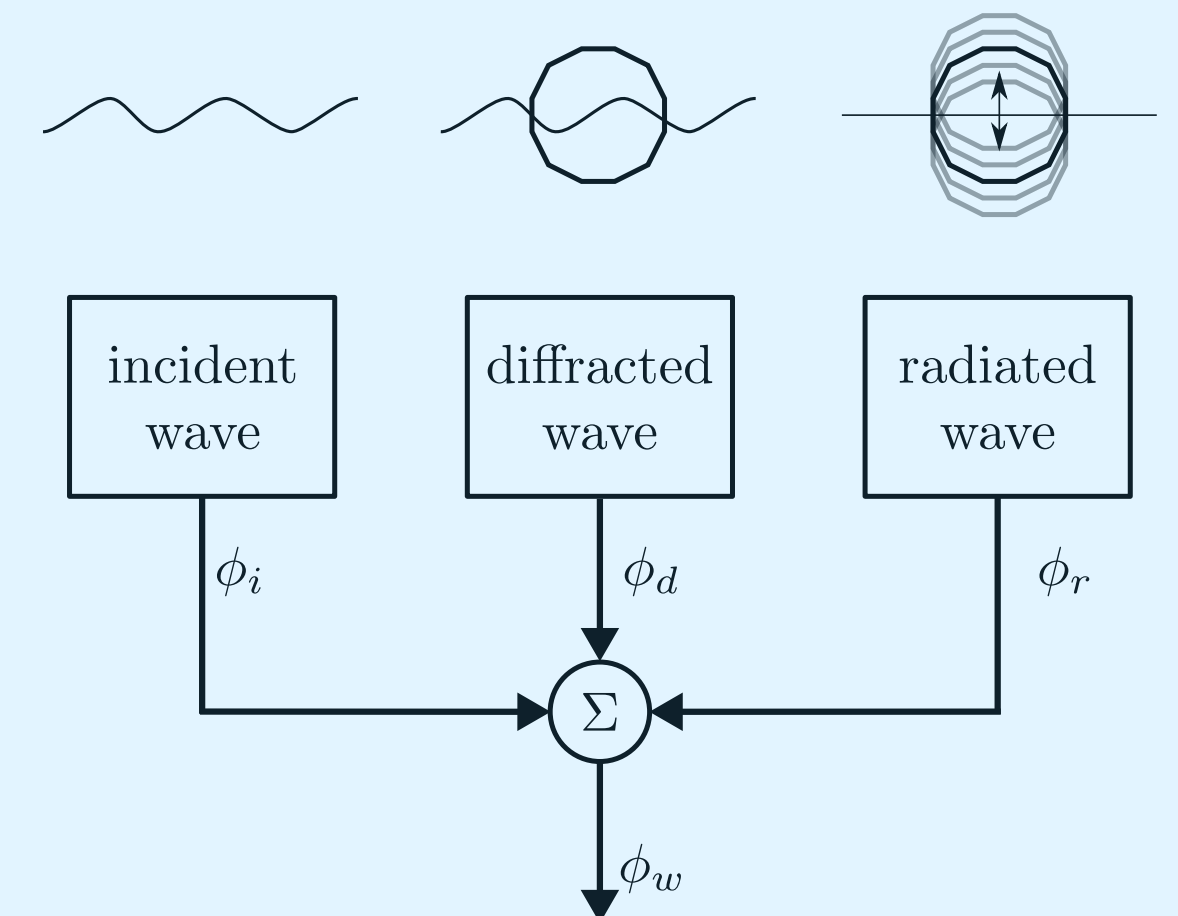
Cummins equation



Software that could be used, for example:



Courtesy Dr. Bruno Paduano @ Polito (Italy)



- Linear wave theory applies (small-amplitude waves)
- Fluid is inviscid, incompressible, and irrotational
- Small oscillations (linearized kinematics)

Cummins, W. E. (1962). *The impulse response function and ship motions* (DTMB Report No. 1661). David Taylor Model Basin, Department of the Navy, Washington, D.C.

Modeling dilemma

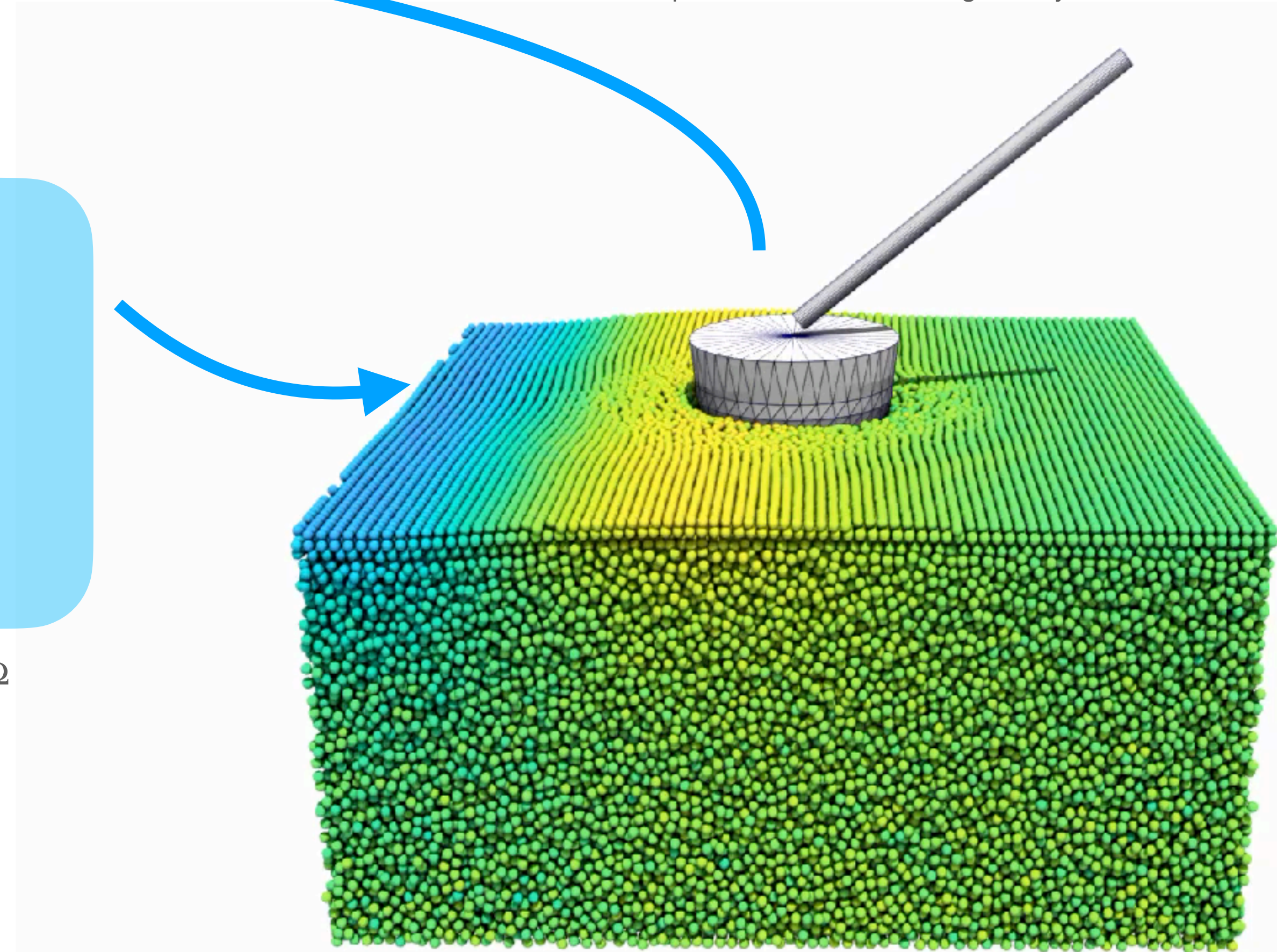
2

$$\mathbf{M} \ddot{\mathbf{x}}(t) = \mathbf{f}_{hydro}(t) + \mathbf{f}_{PTO}(t) + \mathbf{f}_{mooring}(t)$$

Equation of motion for a rigid body

$$\begin{cases} \frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{u} = 0 \\ \frac{D\mathbf{u}}{Dt} = -\frac{1}{\rho} \nabla p + \nabla \cdot \boldsymbol{\tau} + \mathbf{f} \end{cases}$$

Navier–Stokes equations in the Lagrangian formalism on a fluid domain Ω



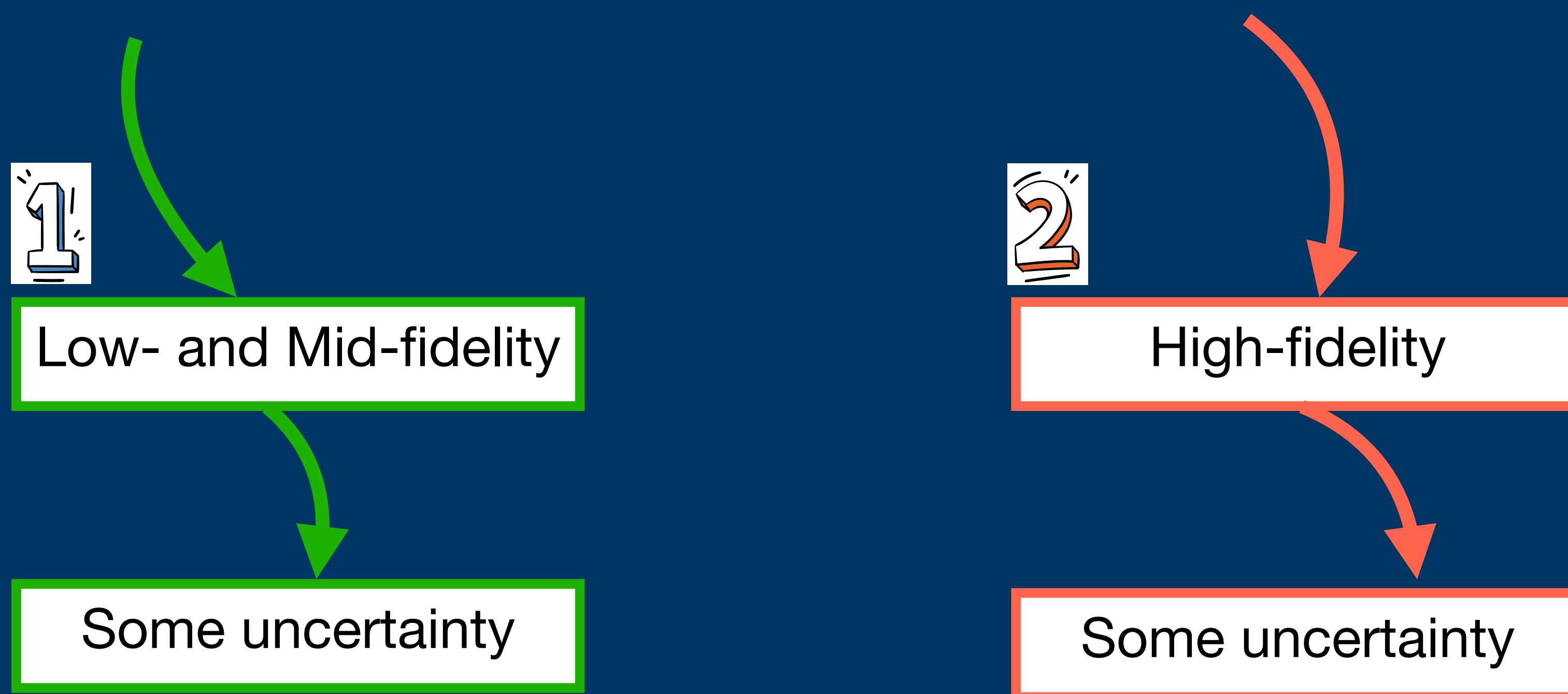
Fluid simulation with SPH of a Wavestar WEC under regular wave.

- Captures viscous and nonlinear effects
- Solved in time
- **High computational cost**

Design dilemma

Operational vs. Extreme (Ultimate) conditions

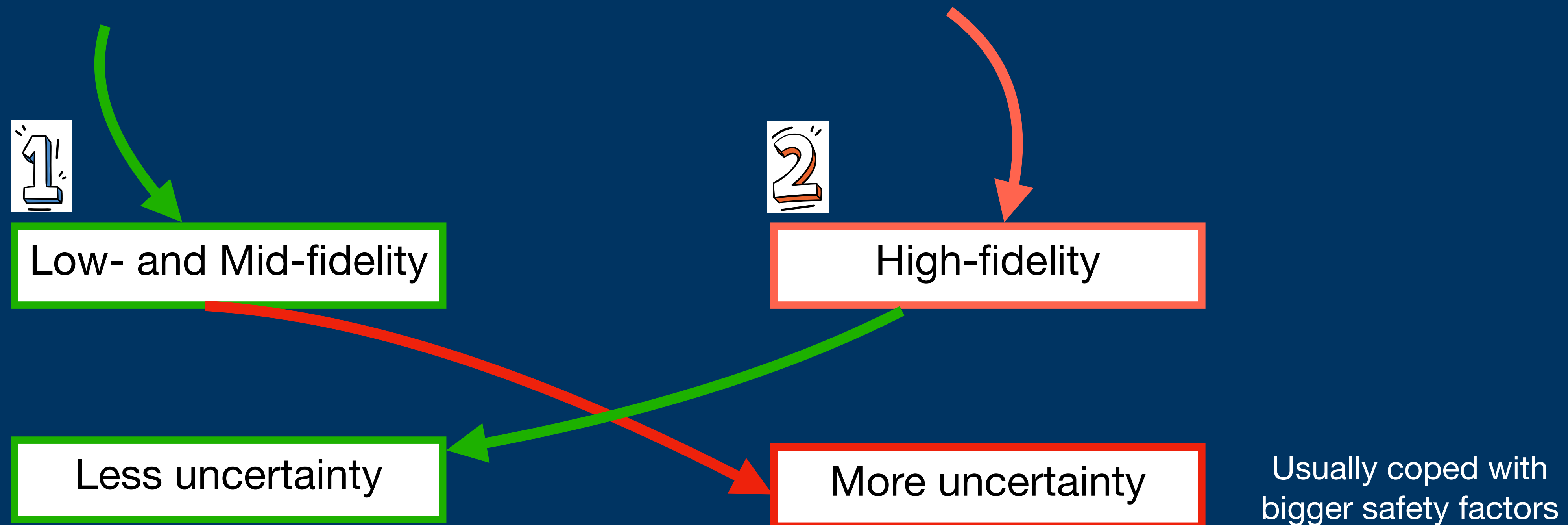
Basics on Semi-Probabilistic methods for structural design



Design dilemma

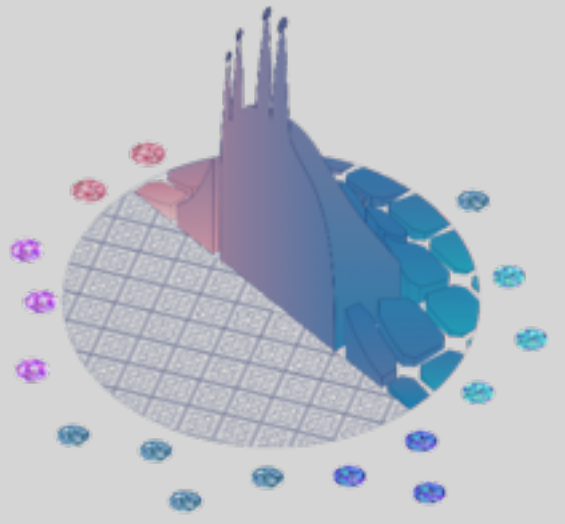
Operational vs. Extreme (Ultimate) conditions

Basics on Semi-Probabilistic methods for structural design



There are conditions where high-fidelity may be the only way forward

Global variable



- The response amplitude operator RAO is computed as:

$$RAO(\omega) = \frac{S_{\xi\eta}^*(\omega)}{S_{\xi\xi}(\omega)}$$

→ complex conjugate of the cross-spectral density between the wave elevation and the heave motion

→ auto-spectral density of the wave elevation

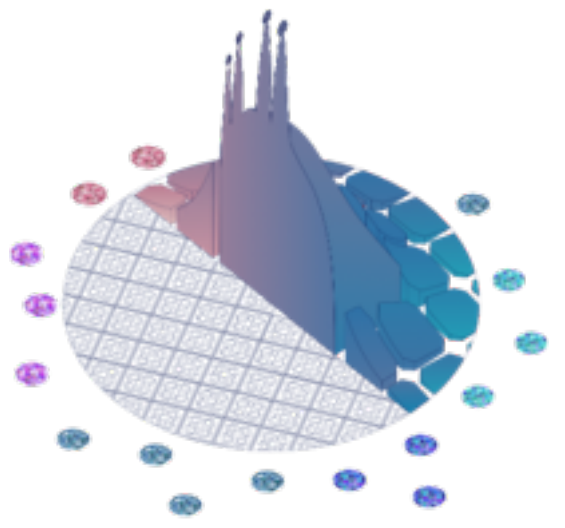
- All the simulations are run using “NVIDIA H100” hardware.

The same you'll be using this afternoon



I acknowledge EuroHPC JU for awarding the project ID EHPC-REG-2024R02-084 (POW – Power from Offshore Wind) access to MareNostrum5 ACC hosted by the Barcelona Supercomputing Center (Spain)

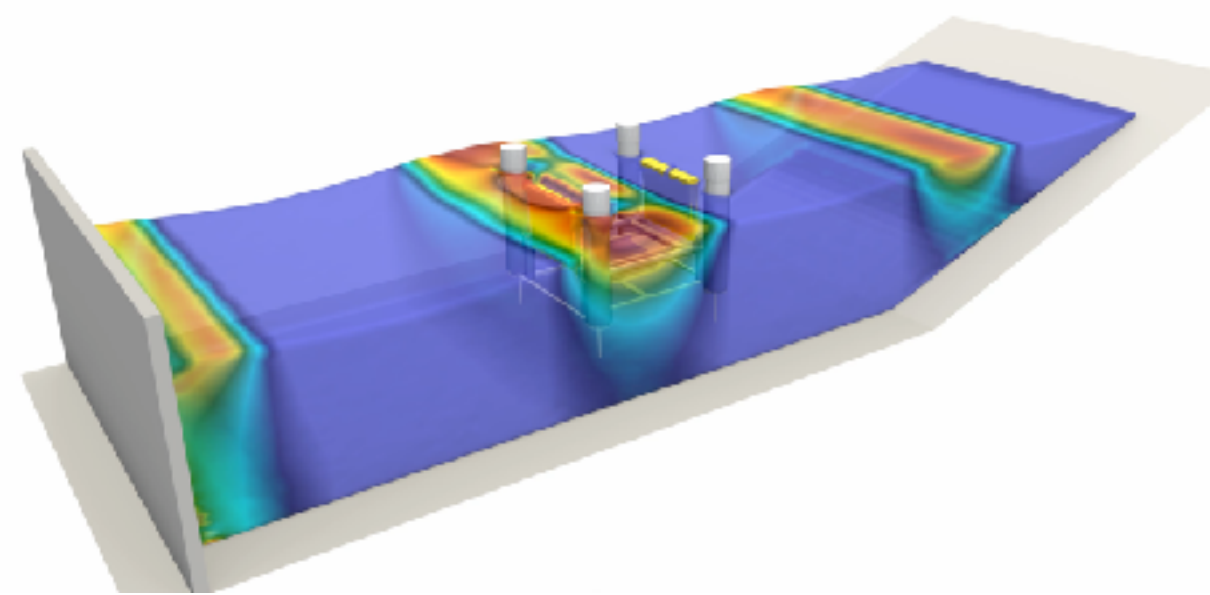
Agenda



1. Software stack

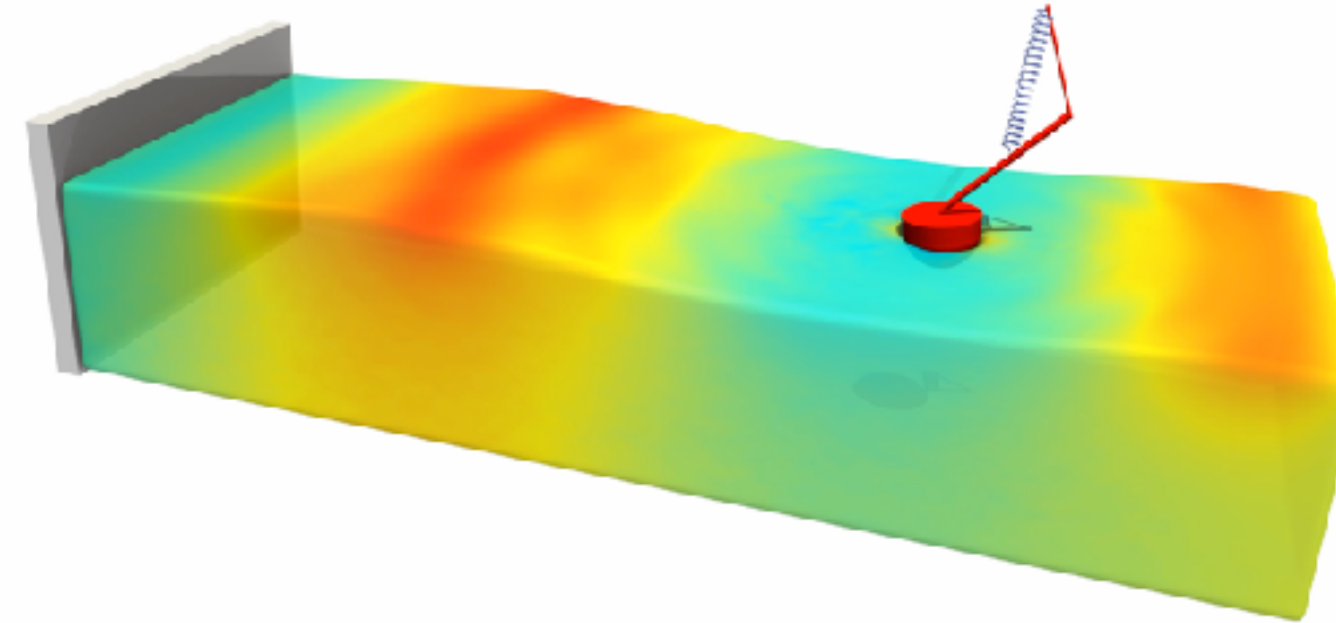


2. FOSWEC

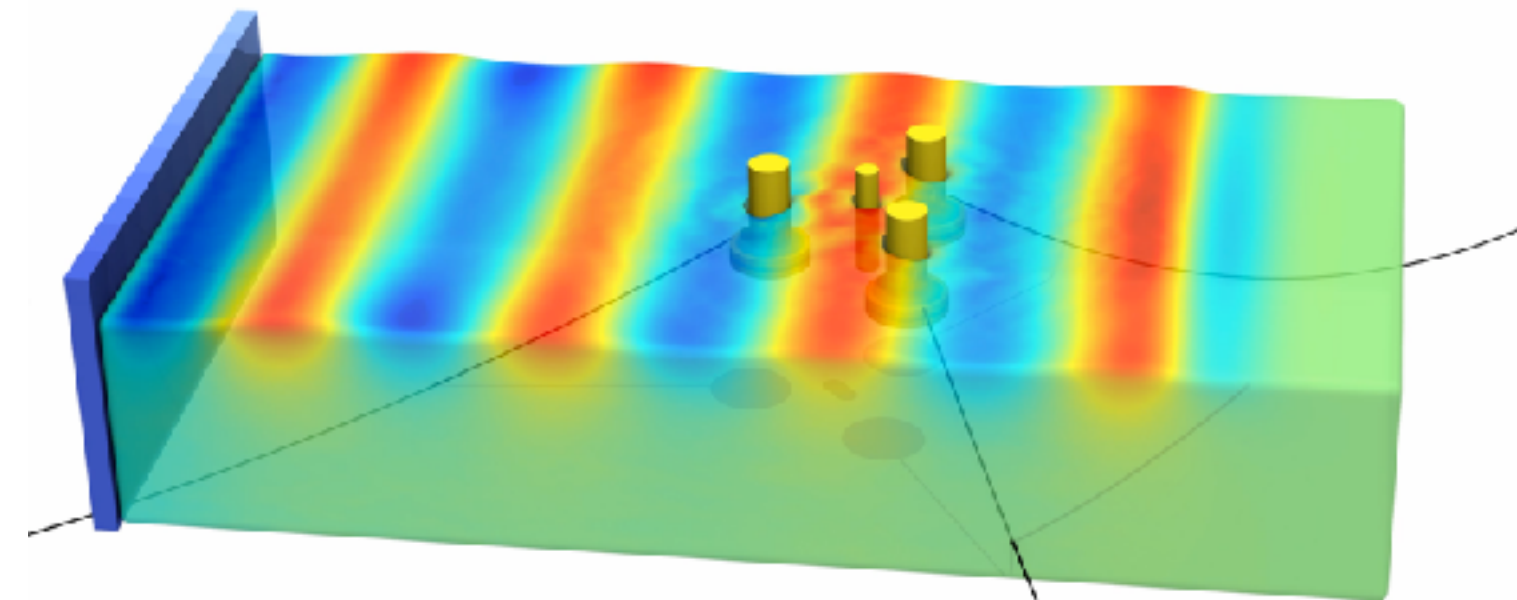


Floating Oscillating Surge WEC – a platform for wave energy.

3. Hybrid Wind–Wave platform



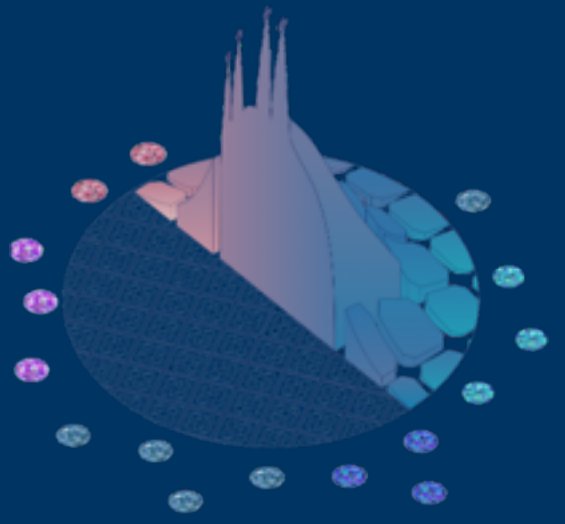
Wavestar wave energy converter



DeepCwind OC4 platform

Validation

- Hydrodynamics
- Wave-induced motion



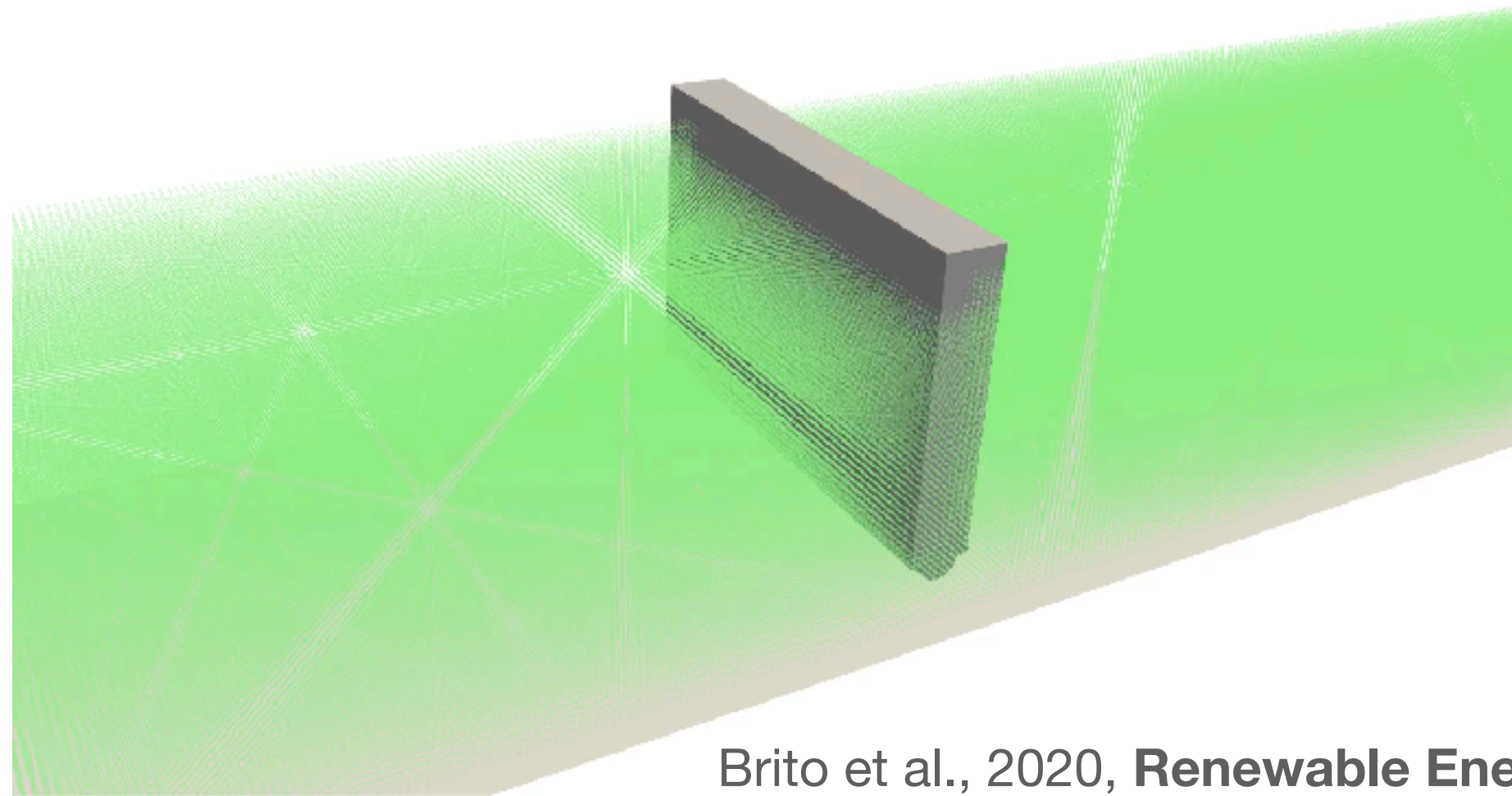
1. Software stack



Wave energy

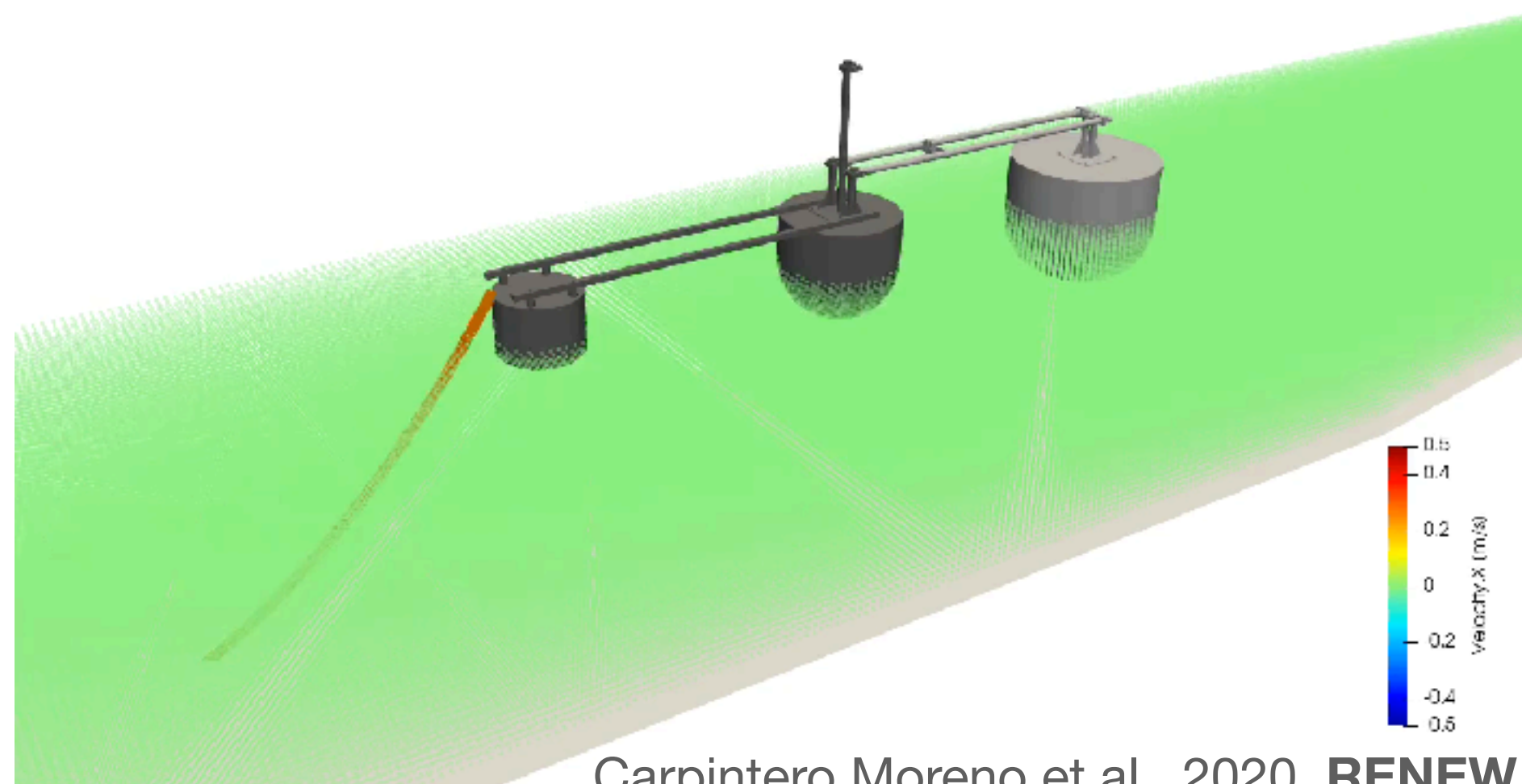
Overview on SPH

Time: 0.00 s



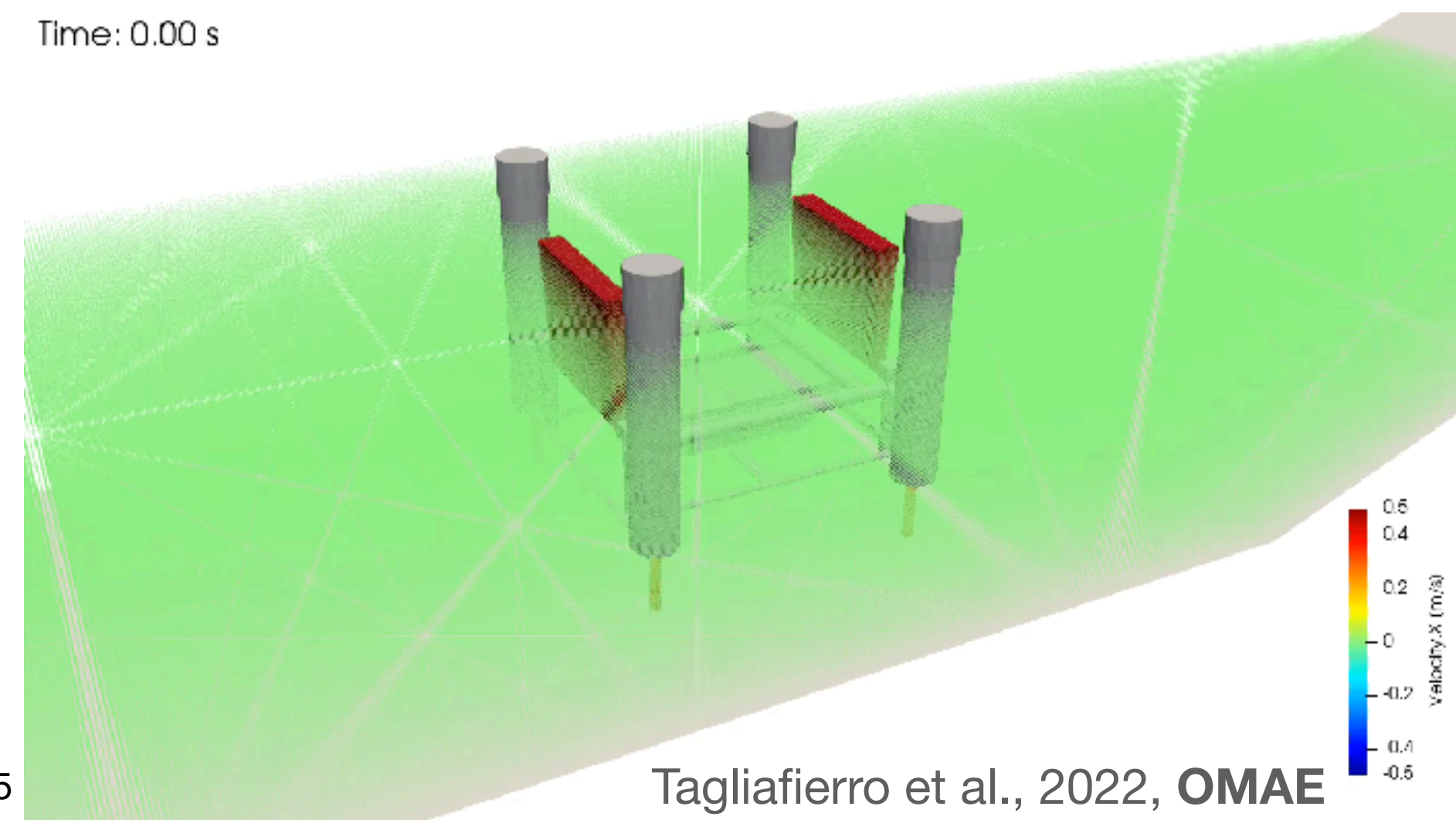
Brito et al., 2020, **Renewable Energy**

Time: 0.00 s

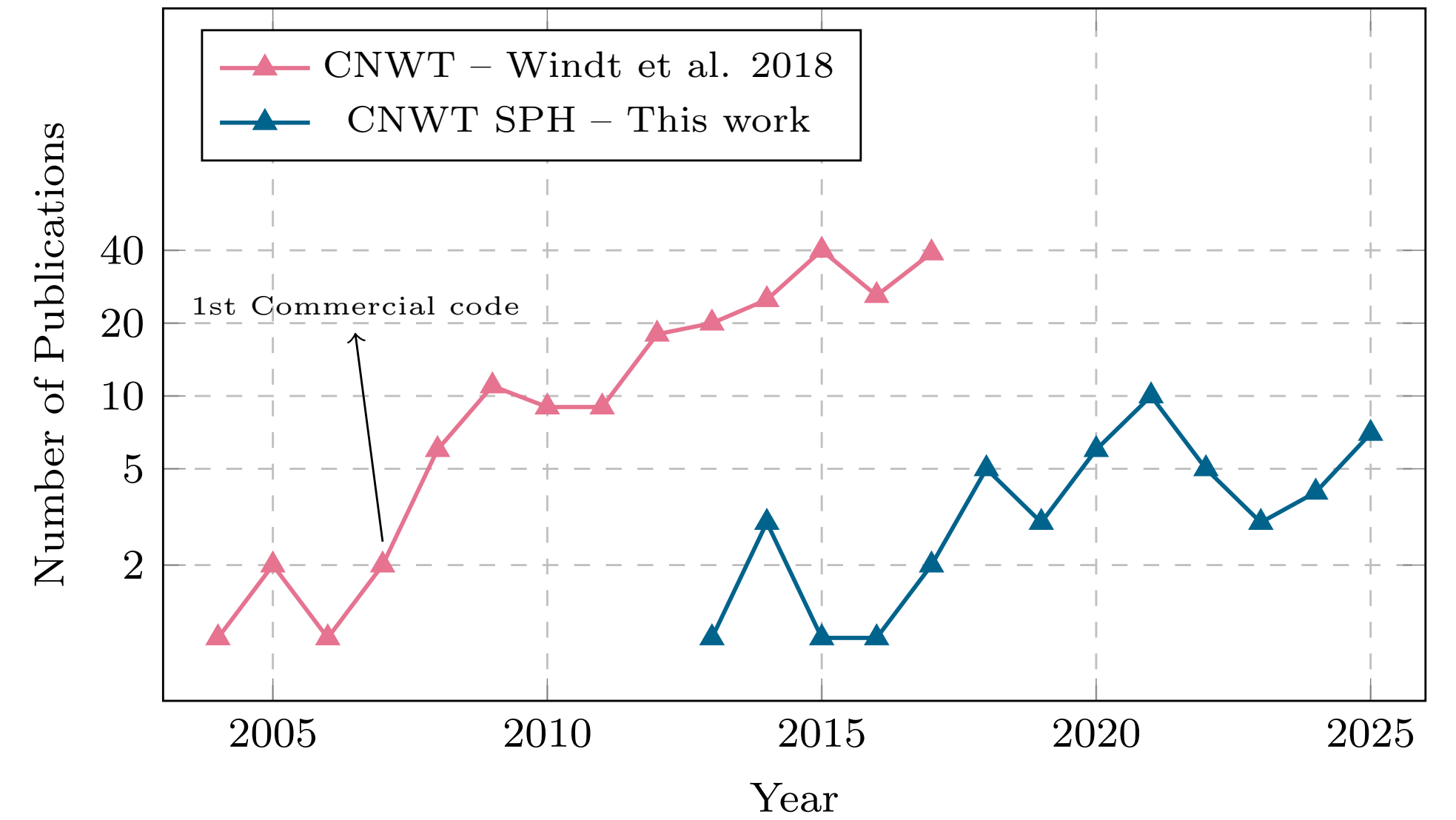


Carpintero Moreno et al., 2020, **RENEW**

Time: 0.00 s



Tagliafierro et al., 2022, **OMAE**

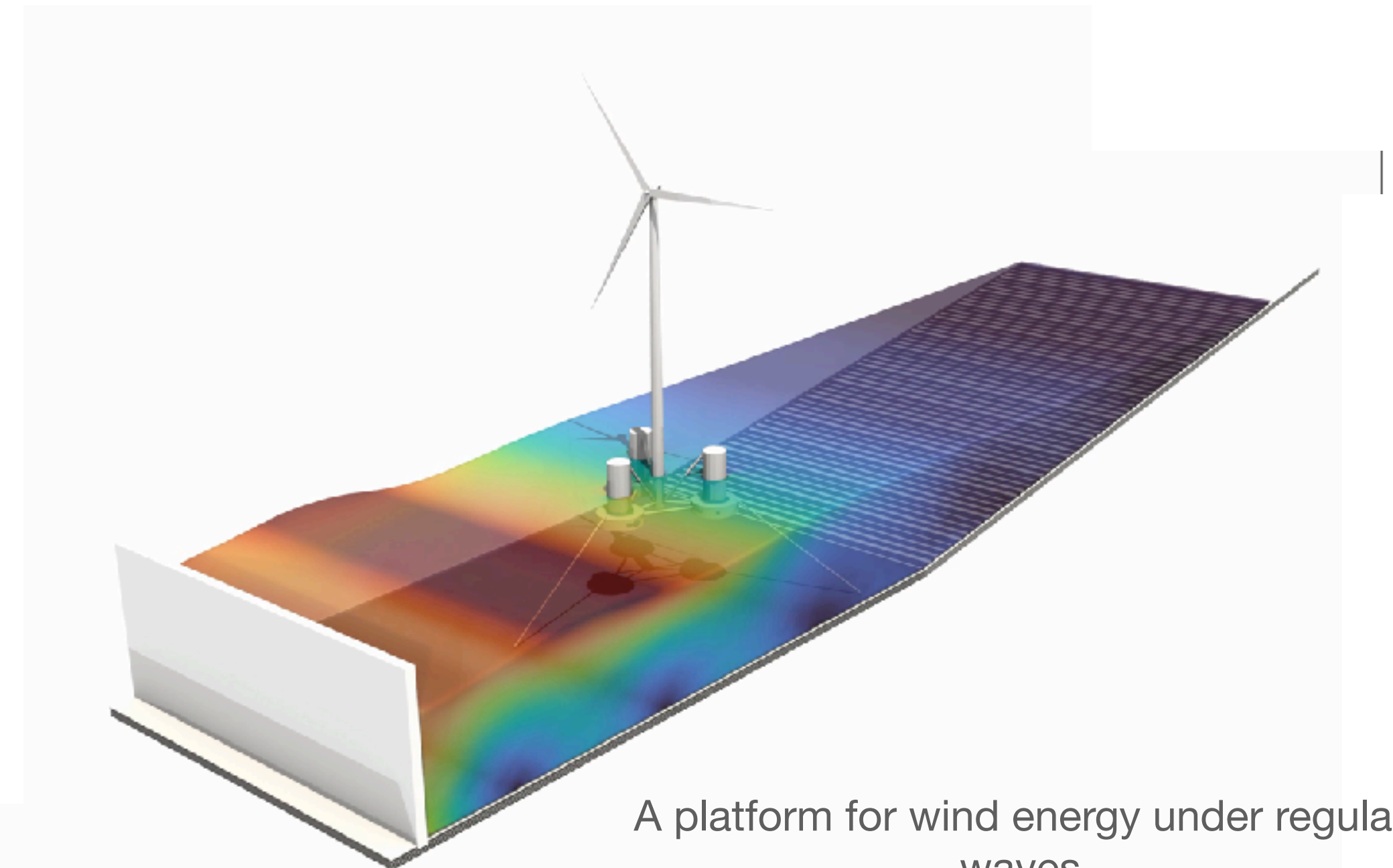


The chart illustrates the extent of research where the SPH method is employed in simulating Wave Energy Converters WECs.

The DualSPHysics code

Open-source SPH solver

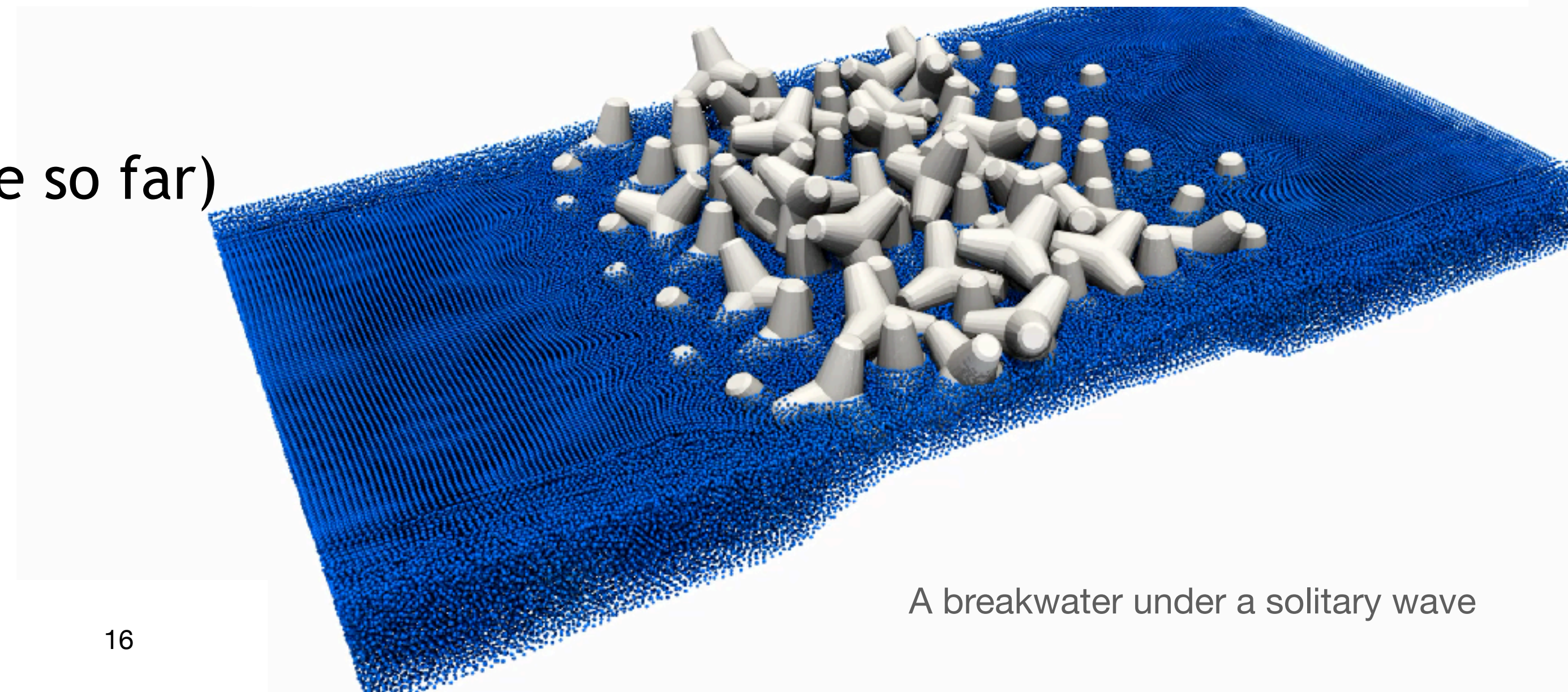
- Mono-dispersed SPH implementation
- Coupling to improve the physics
- Single phase



A platform for wind energy under regular waves

Features:

- CPU/GPU Implementation (C++/Cuda)
- Highly parallelized for GPU units (only one so far)
- Pre- and Post-processing tools
- Open source



A breakwater under a solitary wave

MoorDynPlus

Anchoring system solver

Based upon the original implementation “MoorDyn” by Dr. Matthew Hall

This lumped mass mooring line model is able to account for:

- Any sea-floor geometry
- Wave loads (also from CFD fluid)
- Solve interconnected floating bodies
- Assign different depths for catenary-like connections.

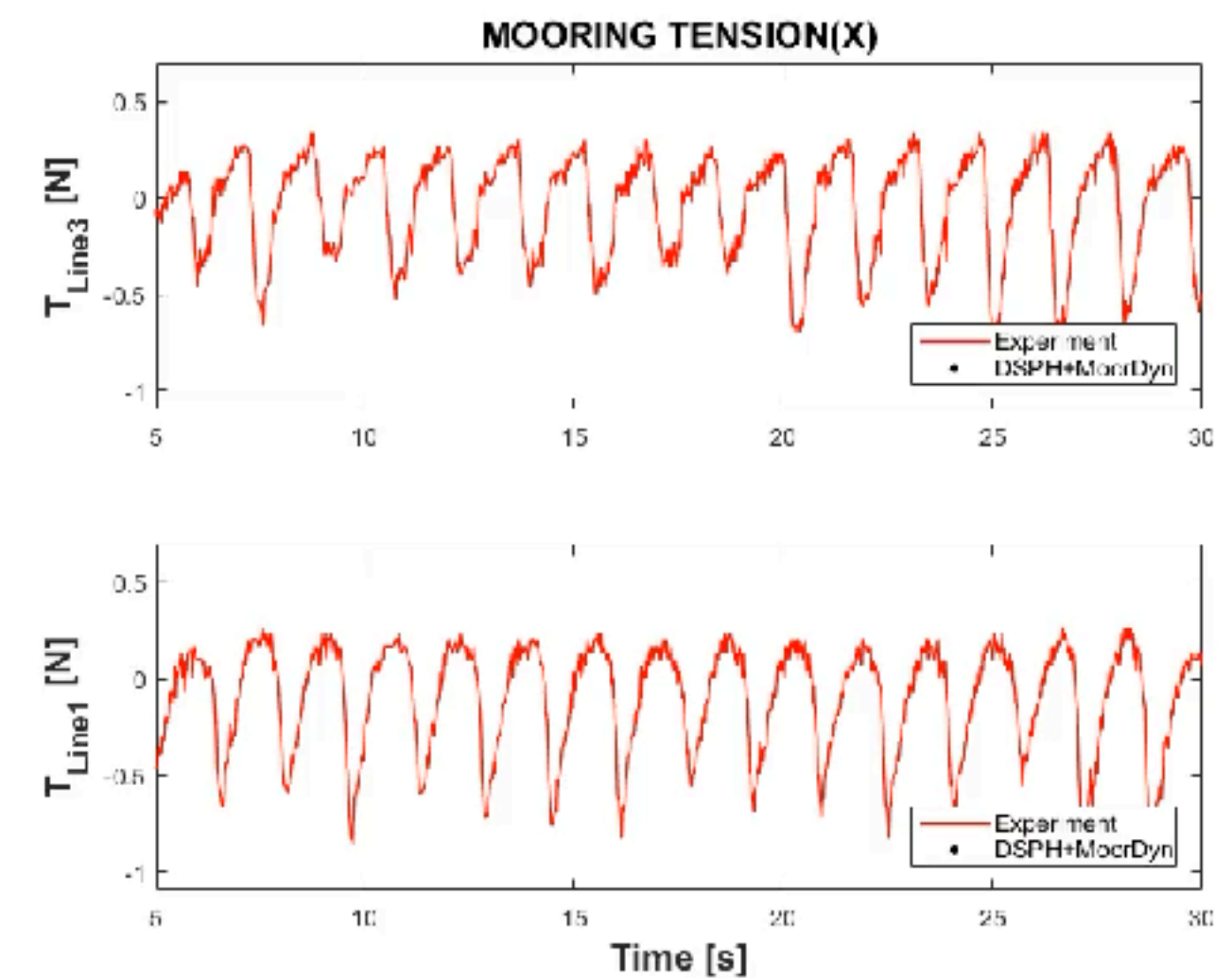
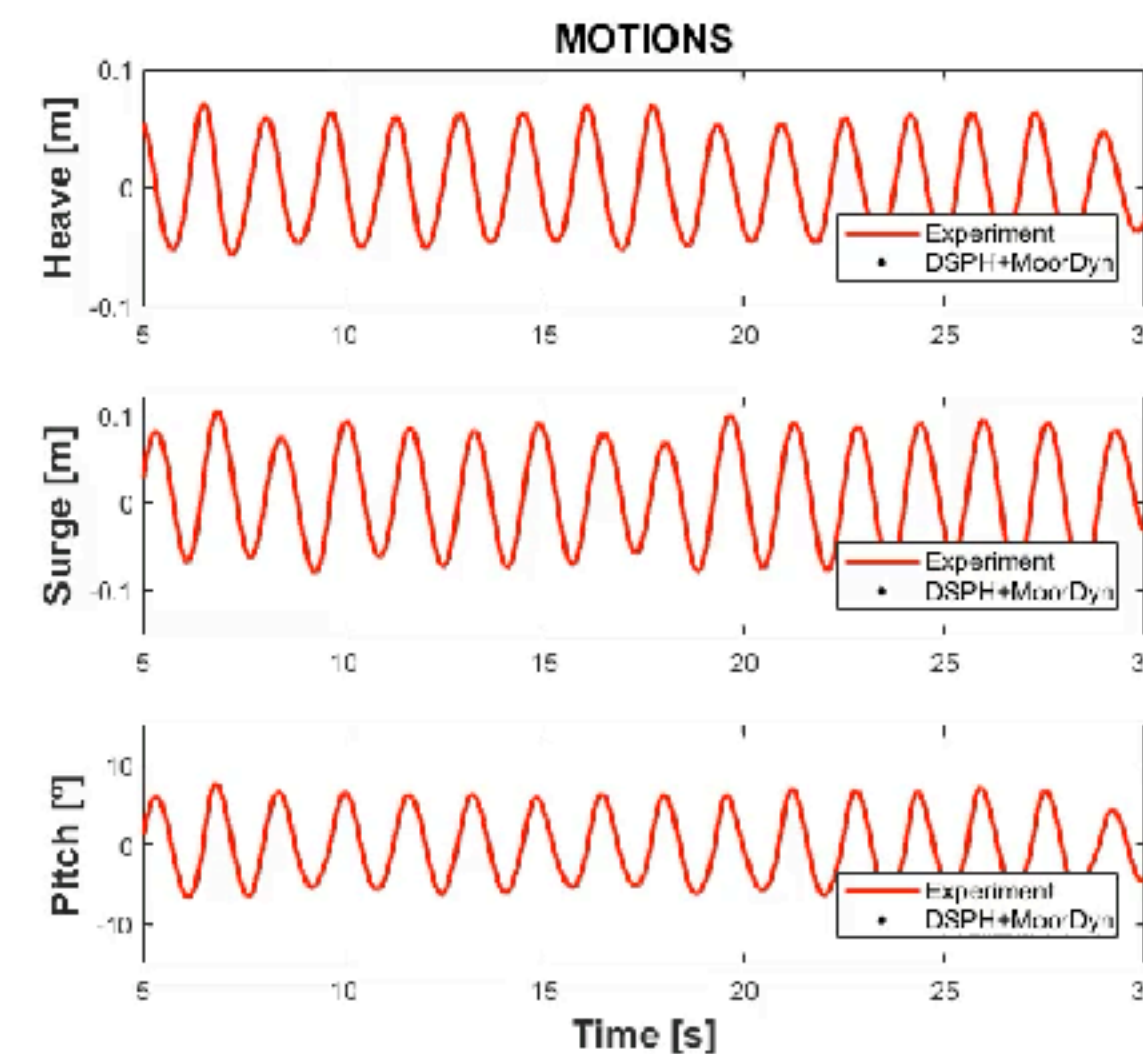
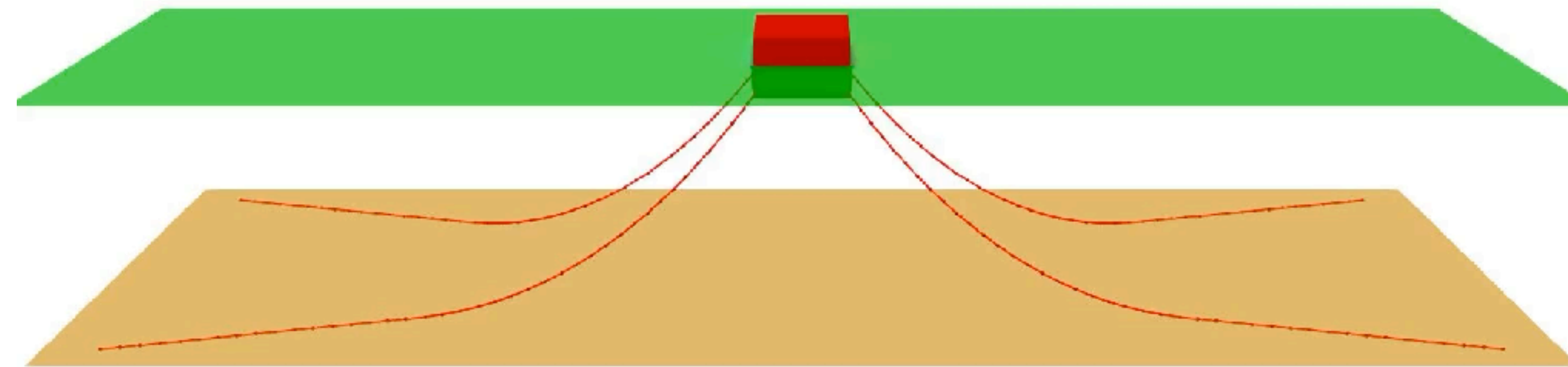
Development: Dr. Iván Martínez-Estévez

EPhysLab – Spain



Floating moored BOX
Regular waves; $H=0.12$ m, $T=1.6$ s, $d=0.5$ m

Time: 0.02 s

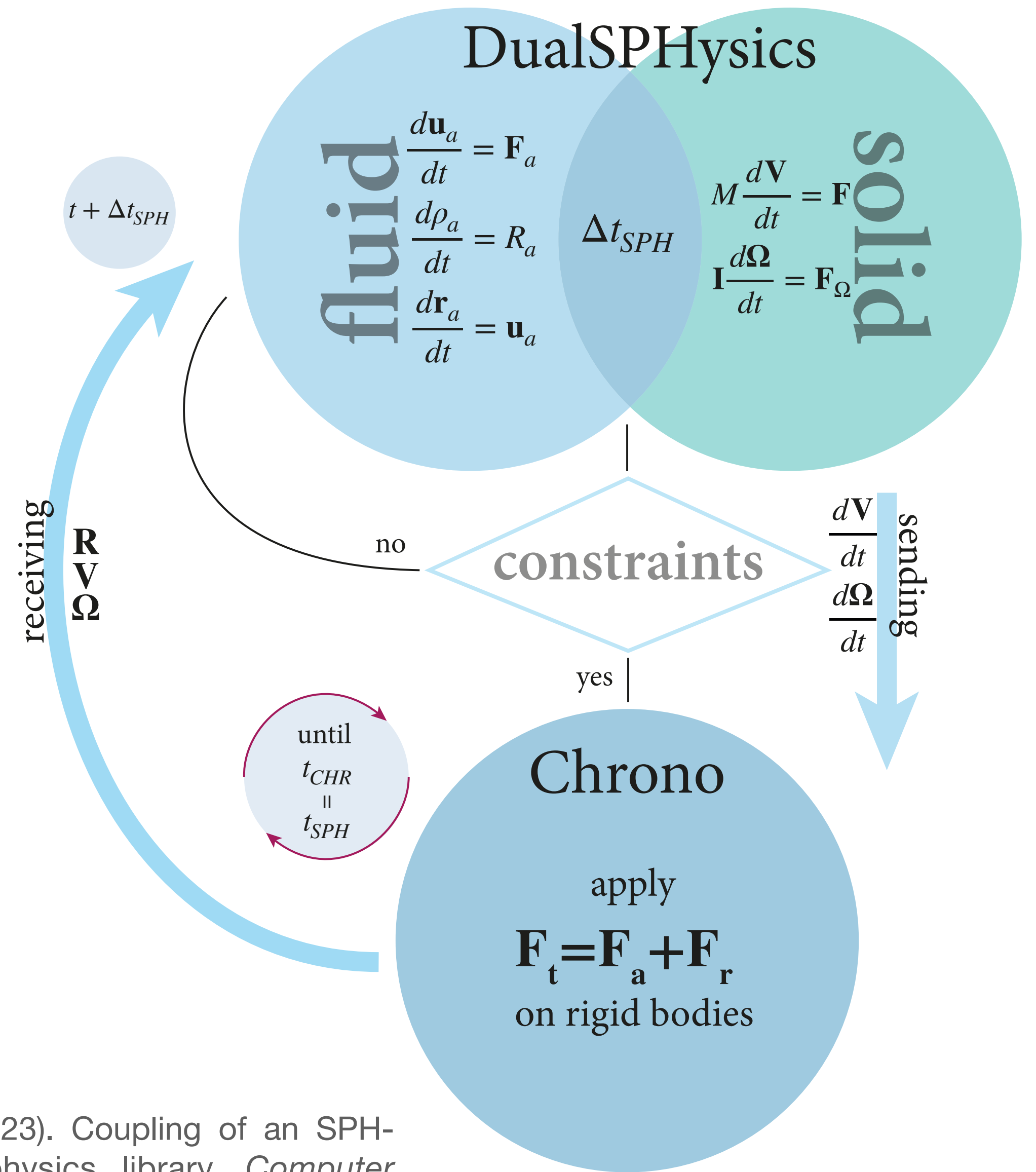
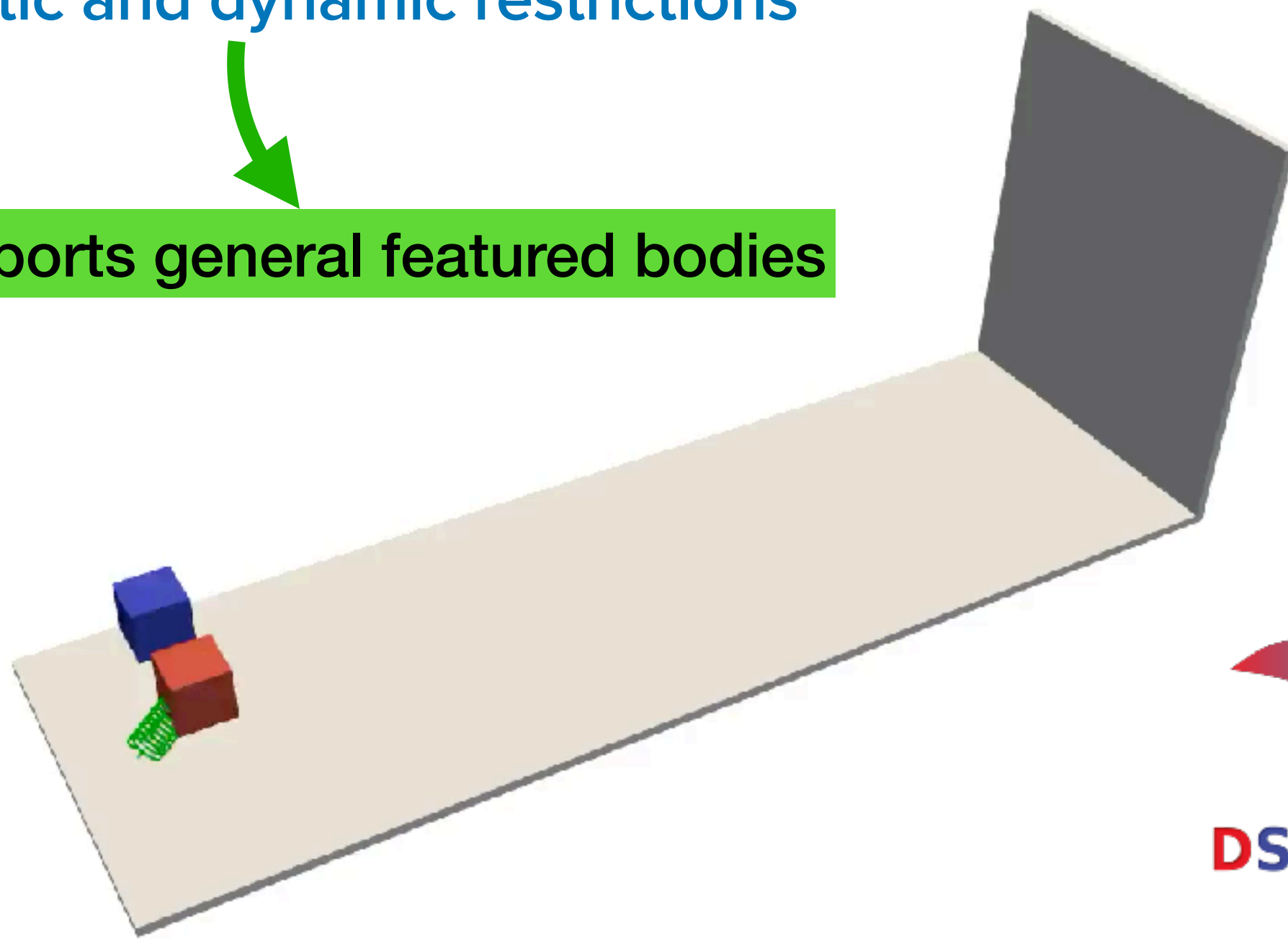


Chrono library

Open source multiphysics solver

- Multi-body support
- Smooth and non-smooth contacts
- Kinematic and dynamic restrictions

Supports general featured bodies



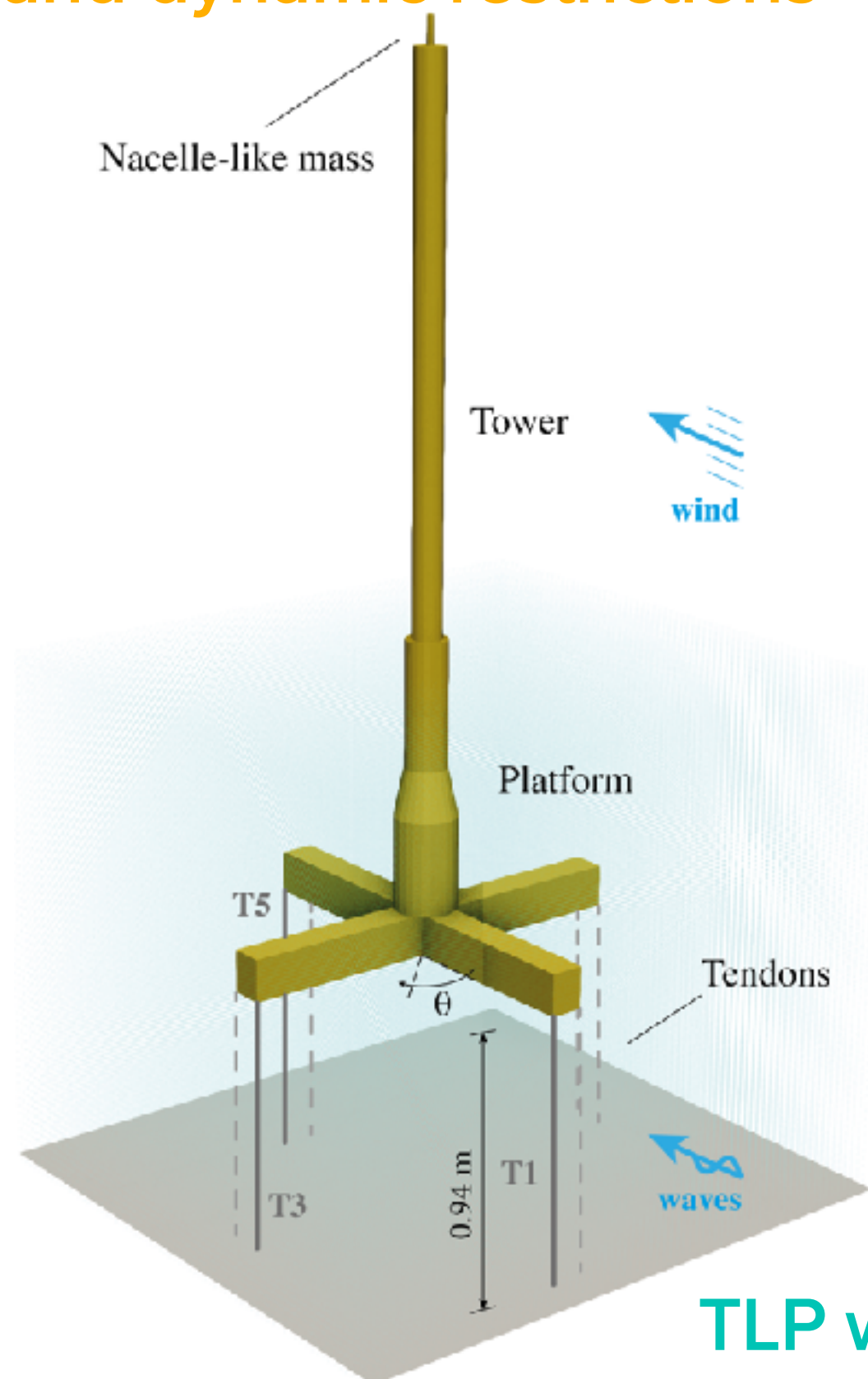
Martínez-Estévez, I. et al. (2023). Coupling of an SPH-based solver with a multiphysics library. *Computer Physics Communications*, 283, 108581. <https://doi.org/10.1016/j.cpc.2022.108581>

Courtesy of Salvatore Capasso

Rigid body

Usage

Open source multiphysics library
multi-body support
smooth and non-smooth contacts
kinematic and dynamic restrictions

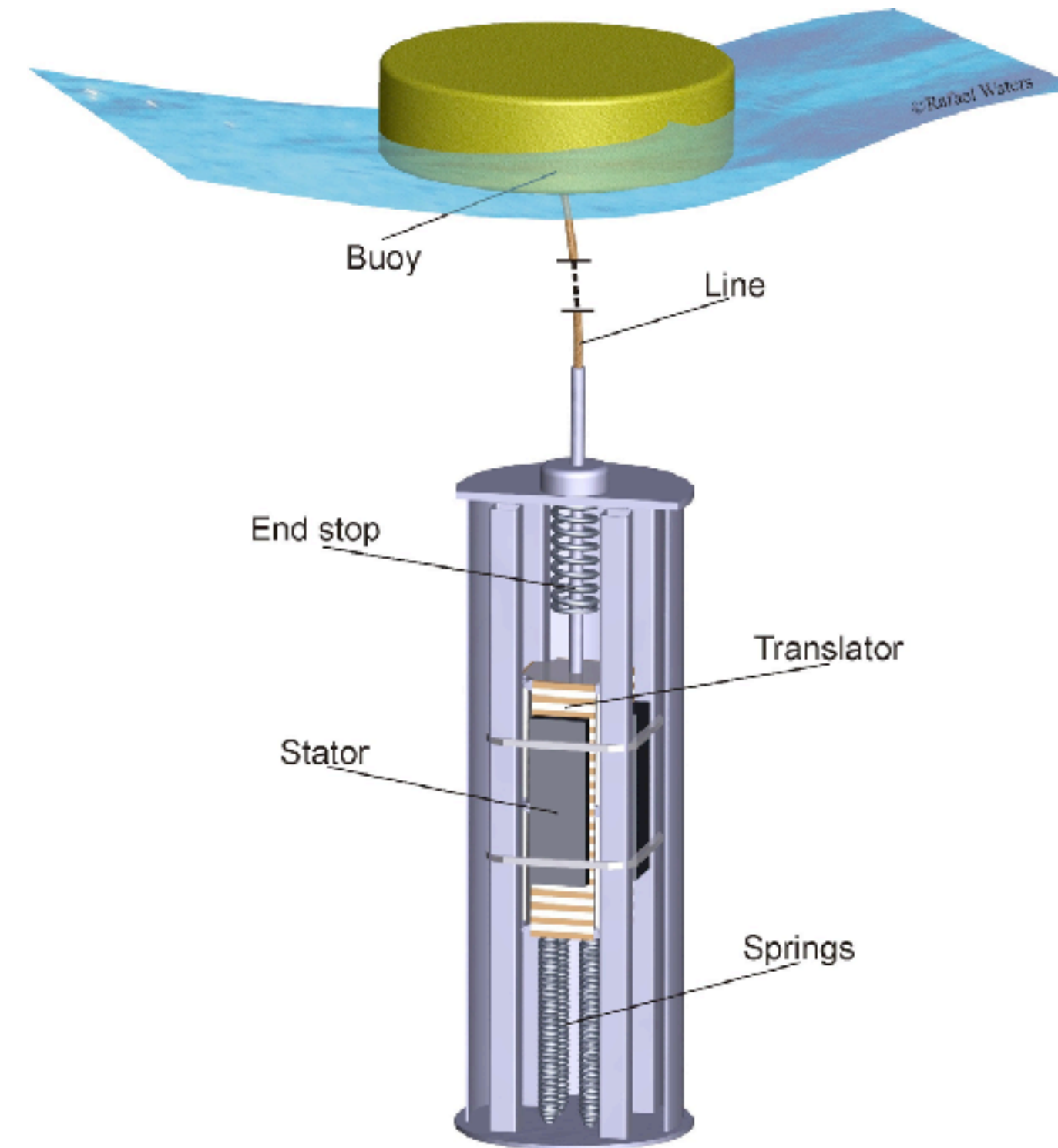


TLP with 8 tendons

Tension legs

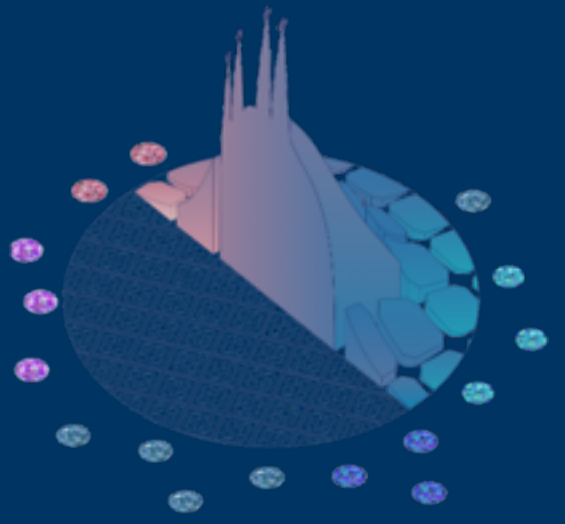


Martínez-Estévez et al., 2023, **CPC**



Point-absorber WEC

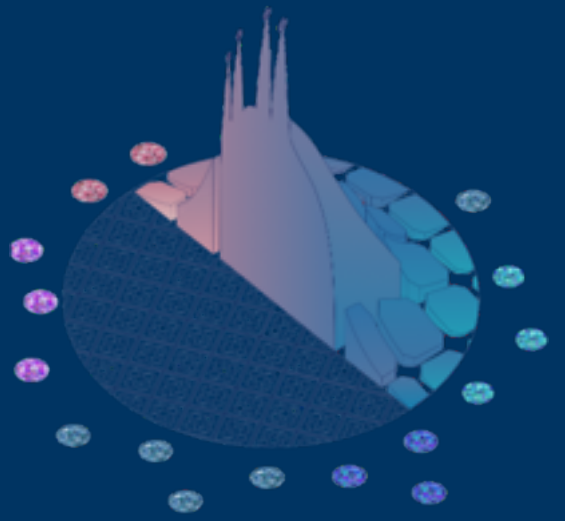
End-stoppers systems



2. Wave energy converters

FOSWEC

Challenges



- 1. Non-linear wave representation**
- 2. Power Take-off systems**
- 3. Mooring systems**
- 4. Simulation of fairly large domains**

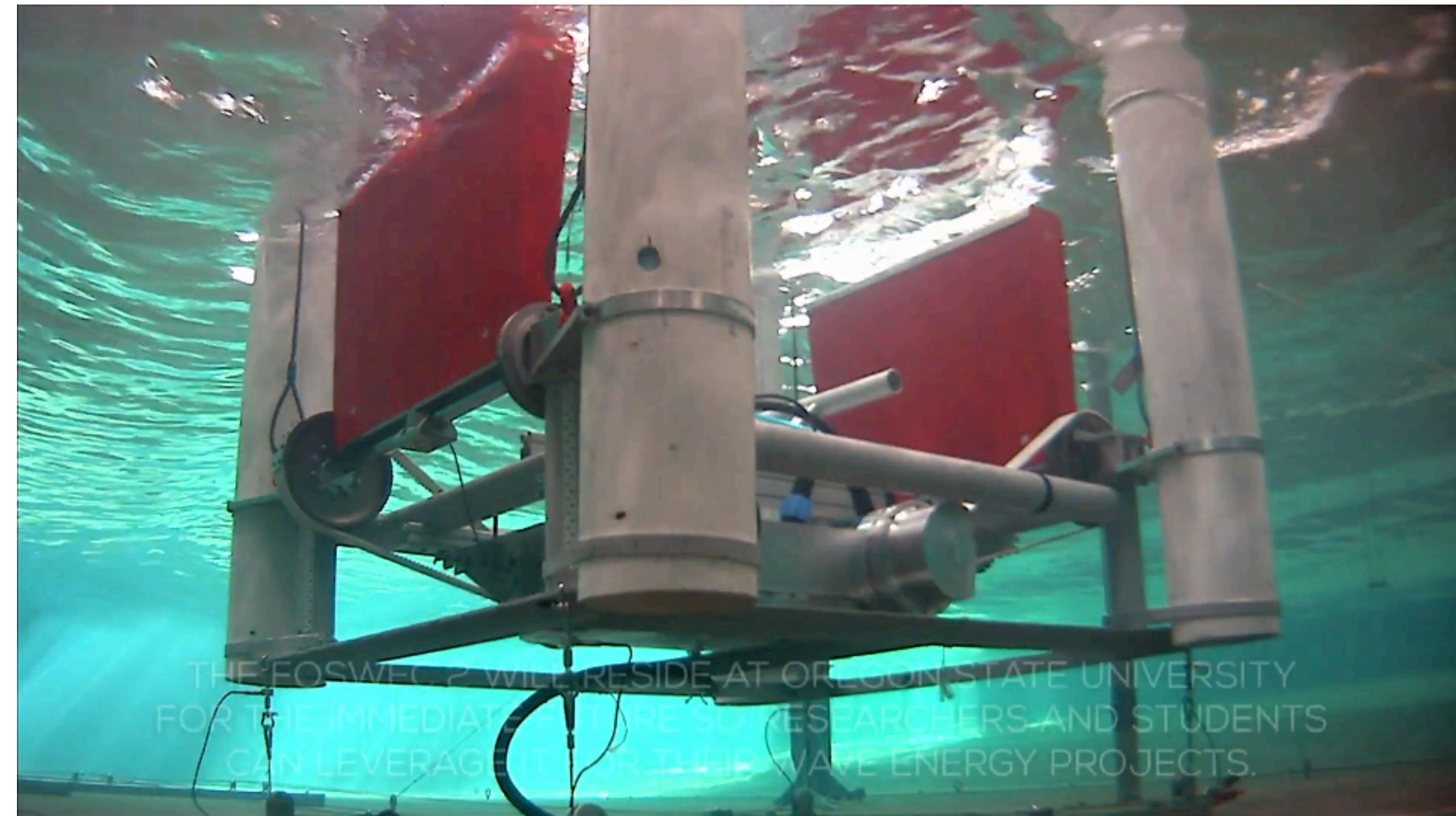
FOSWEC2

Experimental setup



- Floating Oscillating Surge WEC
- FOSWEC has two flaps attached to a submerged moored platform
- Platform includes a Power Take-Off (PTO) box
-

FOSWEC was engineered by Sandia National Labs as a tool to provide consistent and controlled data for software validation. It is represent a challenging device to simulate as it comprises a platform that hosts 2 flaps. Its multibody nature calls for the use of specific library for multibody dynamics.

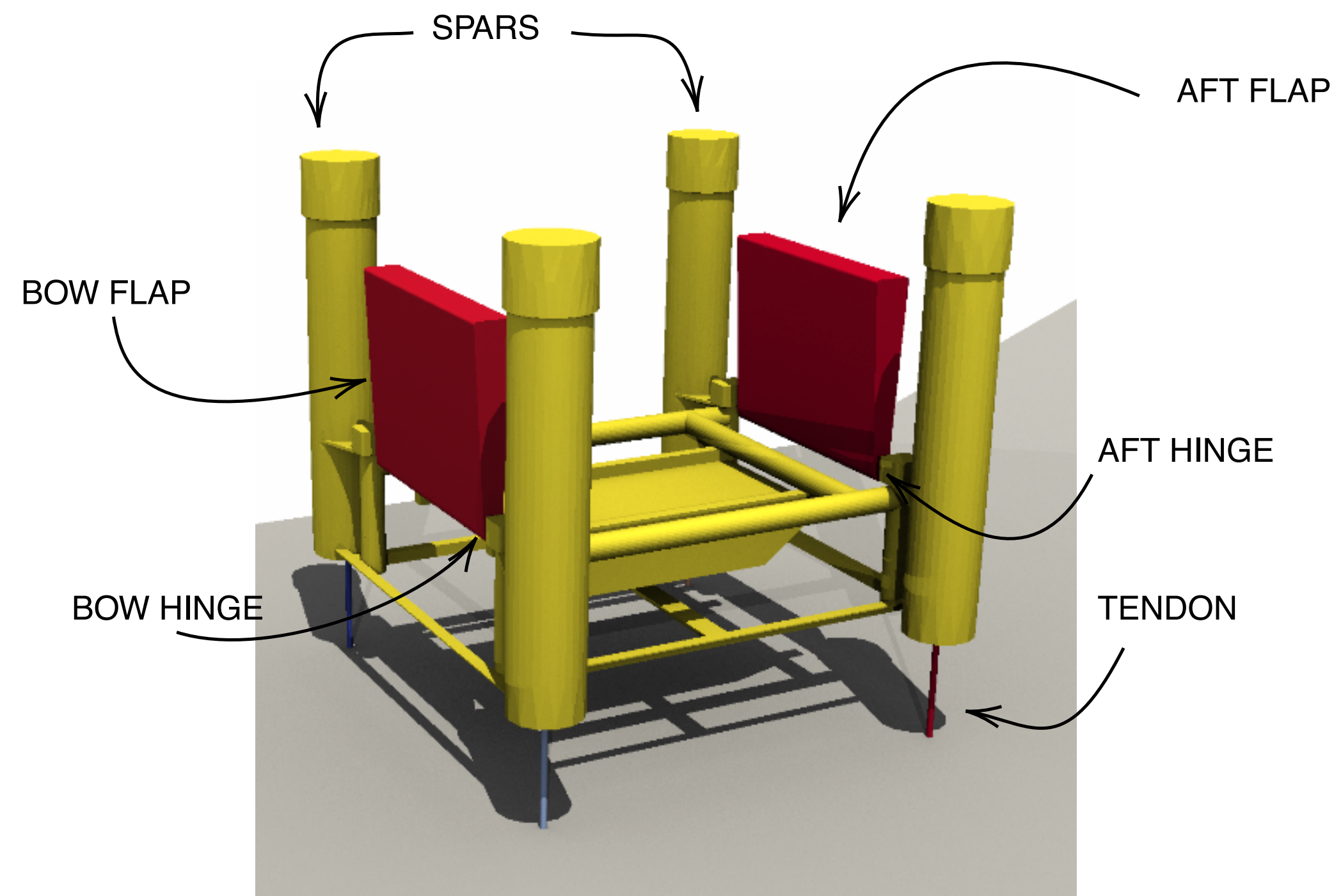


FOSWEC2

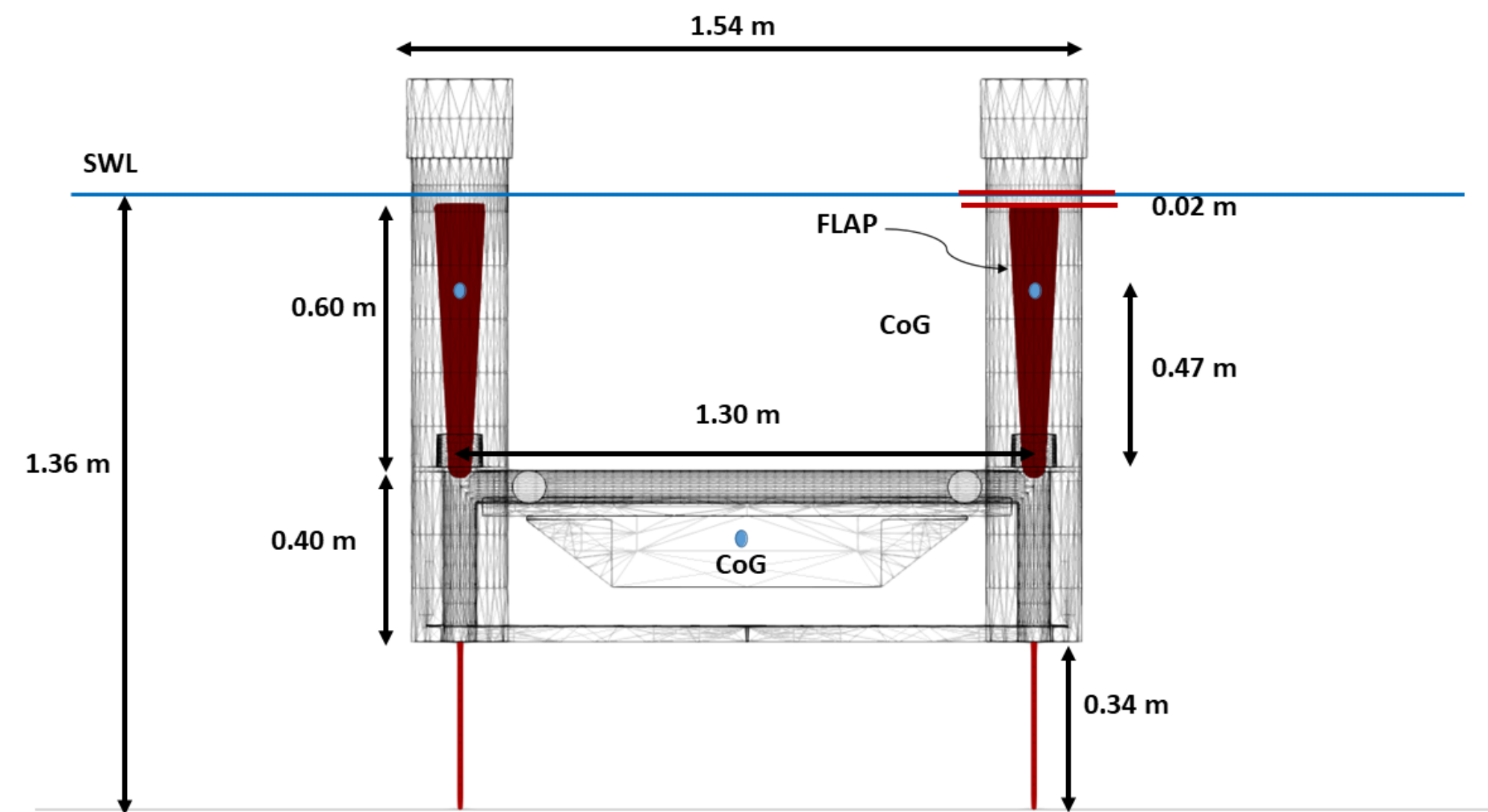
Experimental setup

2

$$\mathbf{M} \ddot{\mathbf{x}}(t) = \mathbf{f}_{hydro}(t) + \mathbf{f}_{PTO}(t) + \mathbf{f}_{mooring}(t)$$



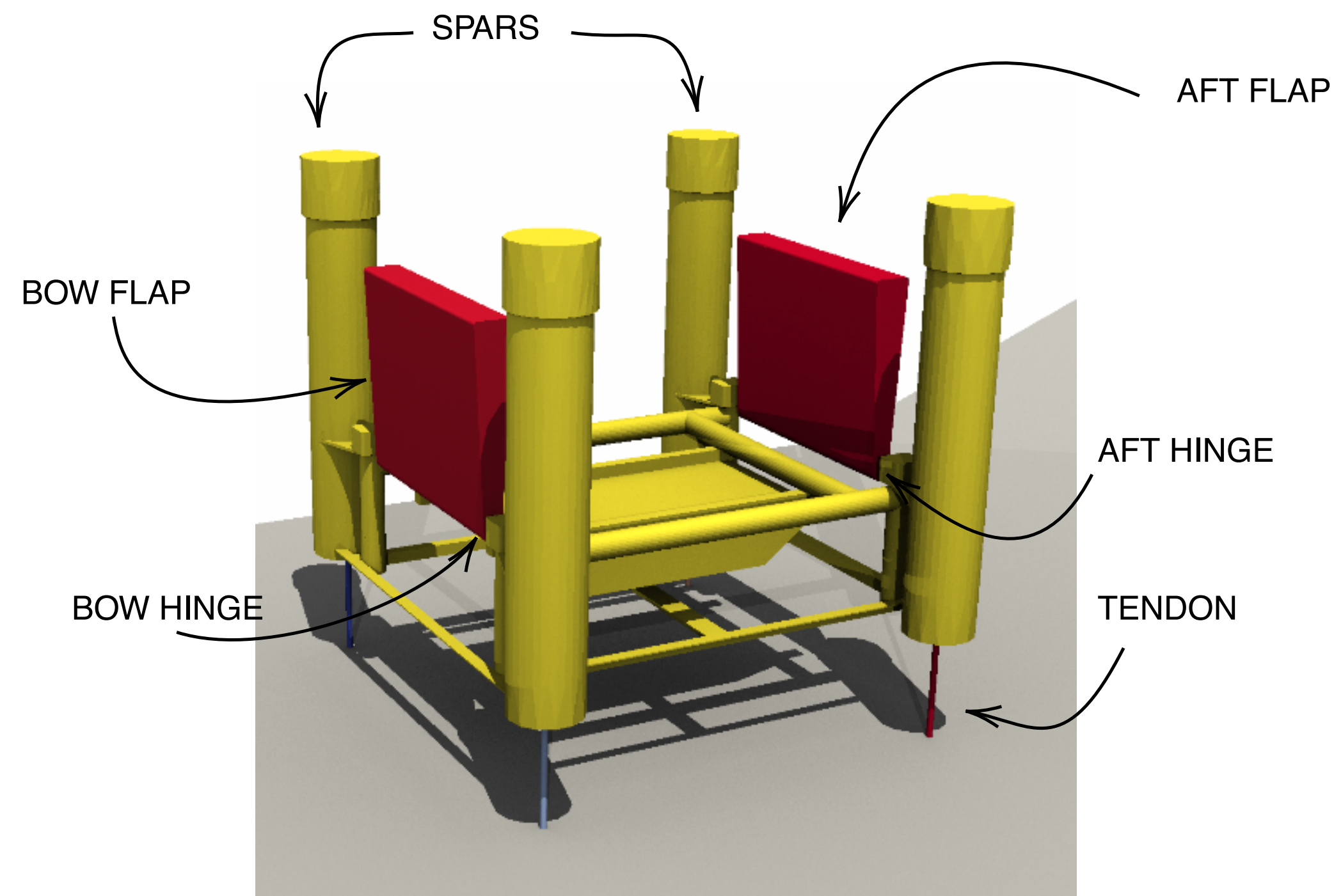
Three dimensional view of the device.



Lateral view with reference dimensions.

FOSWEC2

Experimental setup



Three dimensional view of the device.

Characteristics of the PTO system

Location	Parameter	Symbol	Quantity	Unit
Bow flap	Stiffness	$k_{p.b}$	-3.561	N·m/rad
Bow flap	Damping	$k_{d.b}$	1.762	N·m·s/rad
Aft flap	Stiffness	$k_{p.a}$	-2.800	N·m/rad
Aft flap	Damping	$k_{d.a}$	0.465	N·m·s/rad



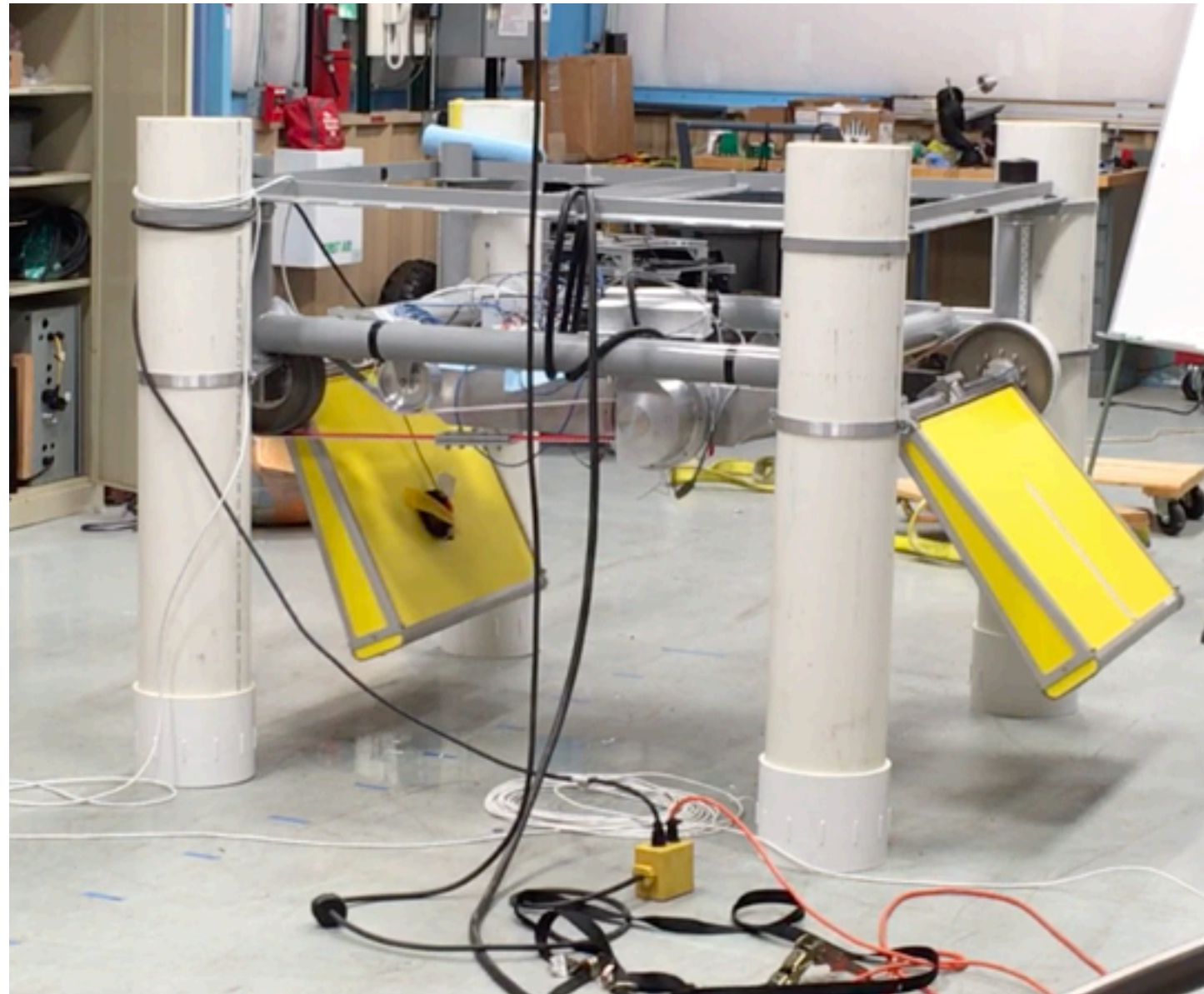
Characteristics of the tendons

Element	Symbol	Quantity	Unit
Cross sectional stiffness	EA_l	183	kN
Nominal diameter	D_N	3.50	mm
Segments	N	10	-
Density in air (steel)	ρ_s	7500	kg/m ³
Weight in fluid	W_l	0.40	N
Natural frequency	f_n	20.0	MHz
Model time step	dt_M	5e-07	s



FOSWEC2

Dry tests - flap decay



Platform total dimension

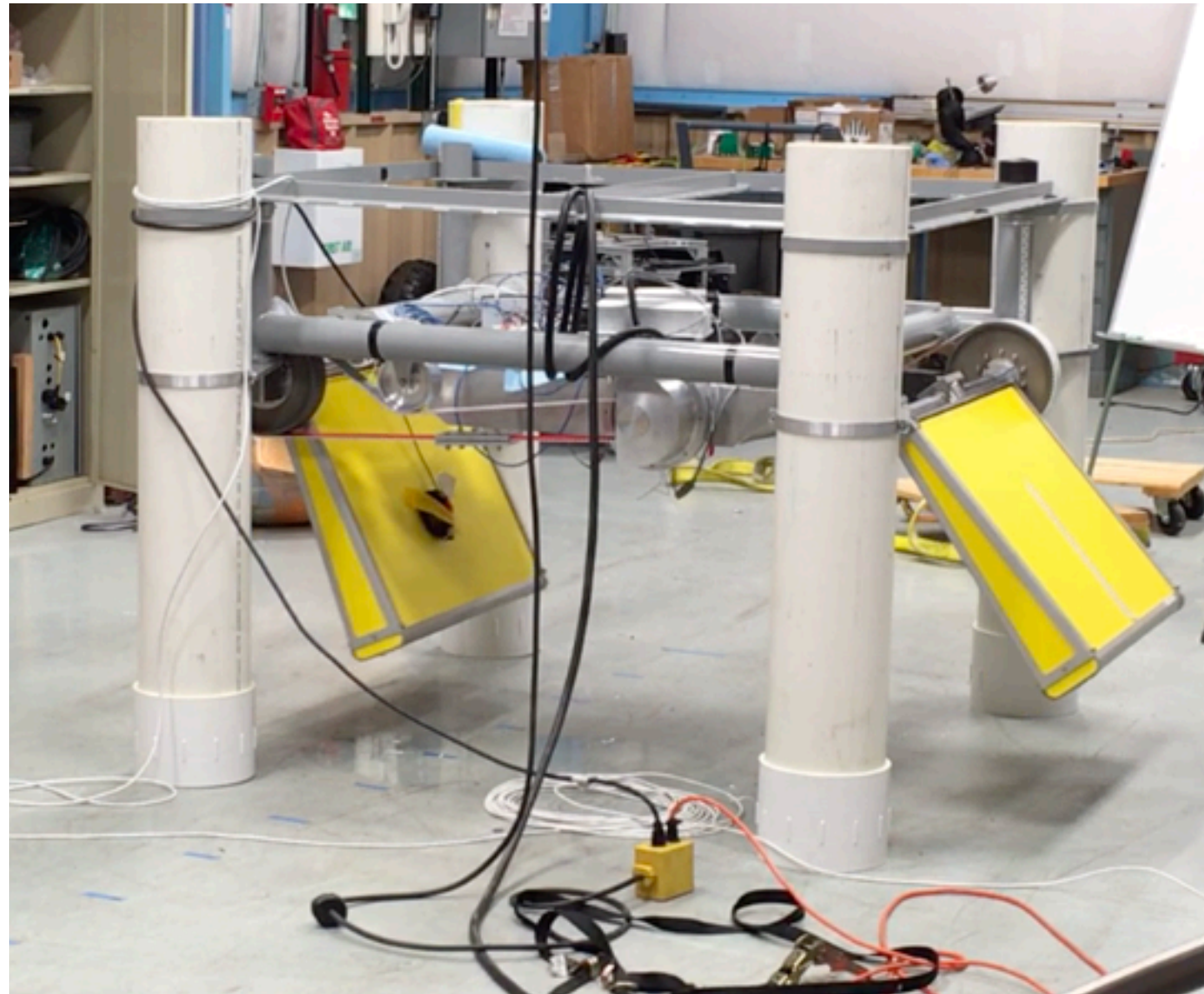
Element	Symbol	Quantity	Unit
Mass	m	263	kg
Length	L_{WEC}	1.44	m
Beam	W_{WEC}	1.63	m
Draft	D_{WEC}	1.24	m

Estimation of the flap CoG

$$\text{CoG}_{Flap} = \frac{gT^2}{4\pi^2} = 0.466 \text{ m}$$

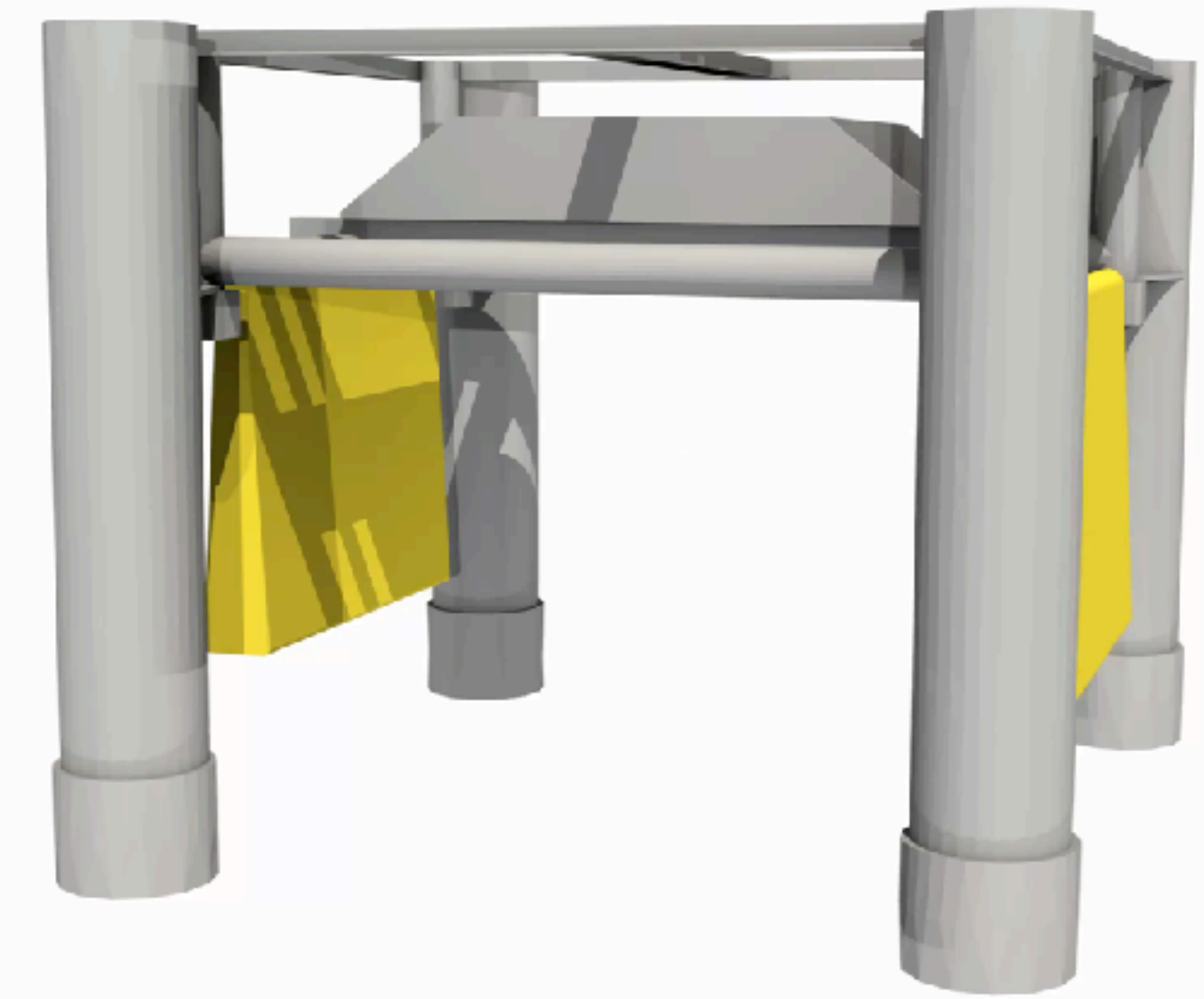
FOSWEC2

Dry tests - flap decay



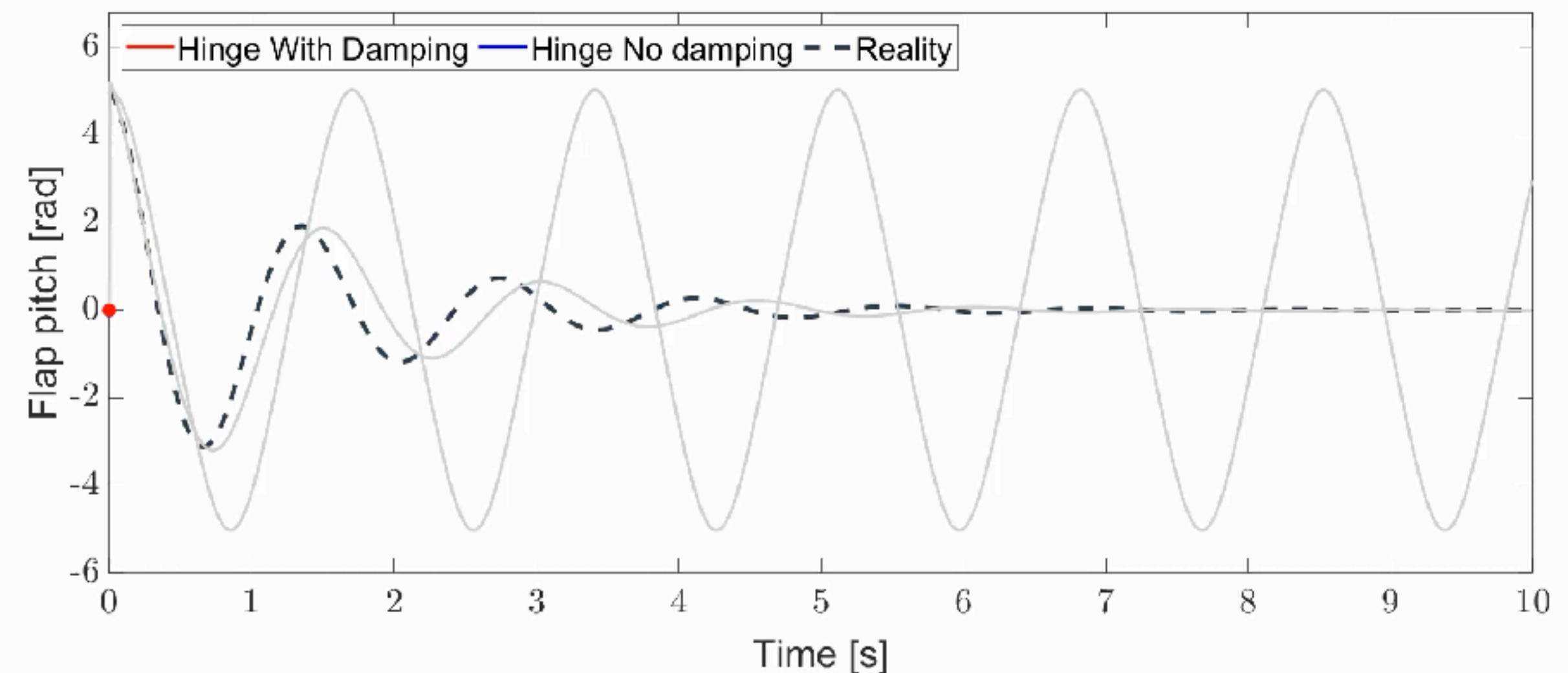
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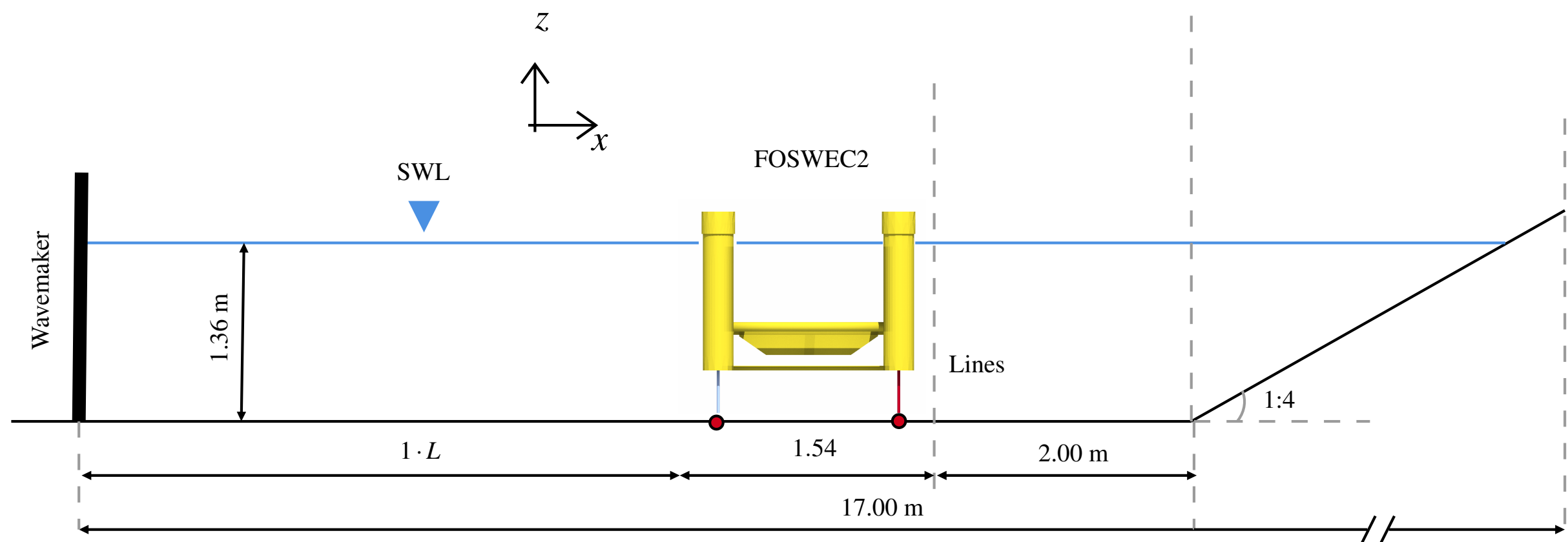
$$\text{CoG}_{Flap} = \frac{gT^2}{4\pi^2} = 0.466 \text{ m}$$



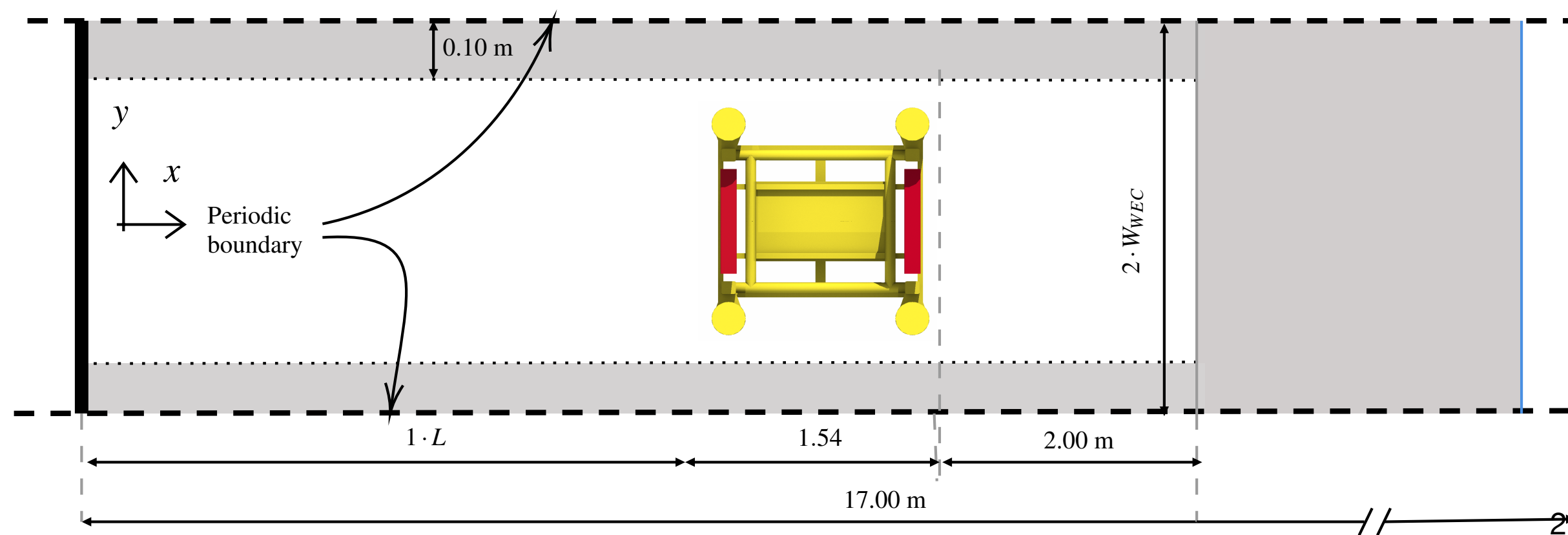
FOSWEC2

Regular wave validation

$$\mathbf{M} \ddot{\mathbf{x}}(t) = \mathbf{f}_{hydro}(t) + \mathbf{f}_{PTO}(t) + \mathbf{f}_{mooring}(t)$$



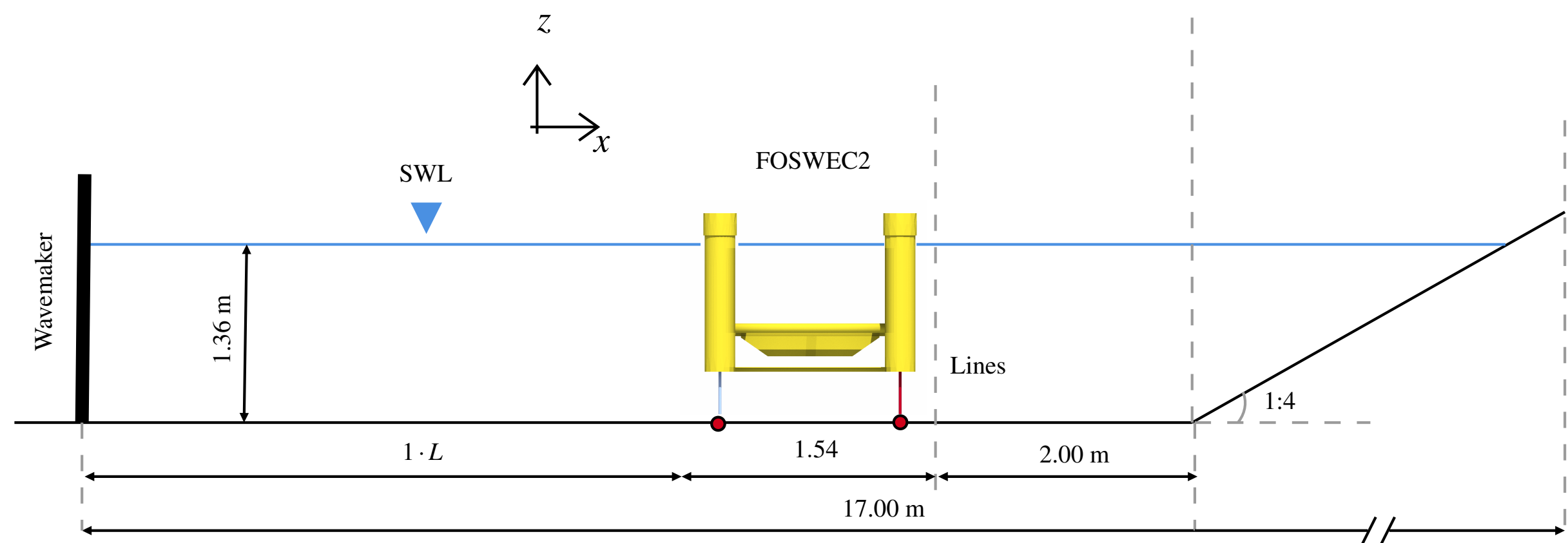
Parameter	Symbol	Quantity	Unit
Wave period	T	1.56	s
Wave height	H	0.136	m
Water depth	d	1.36	m
Wave length	L	3.73	m



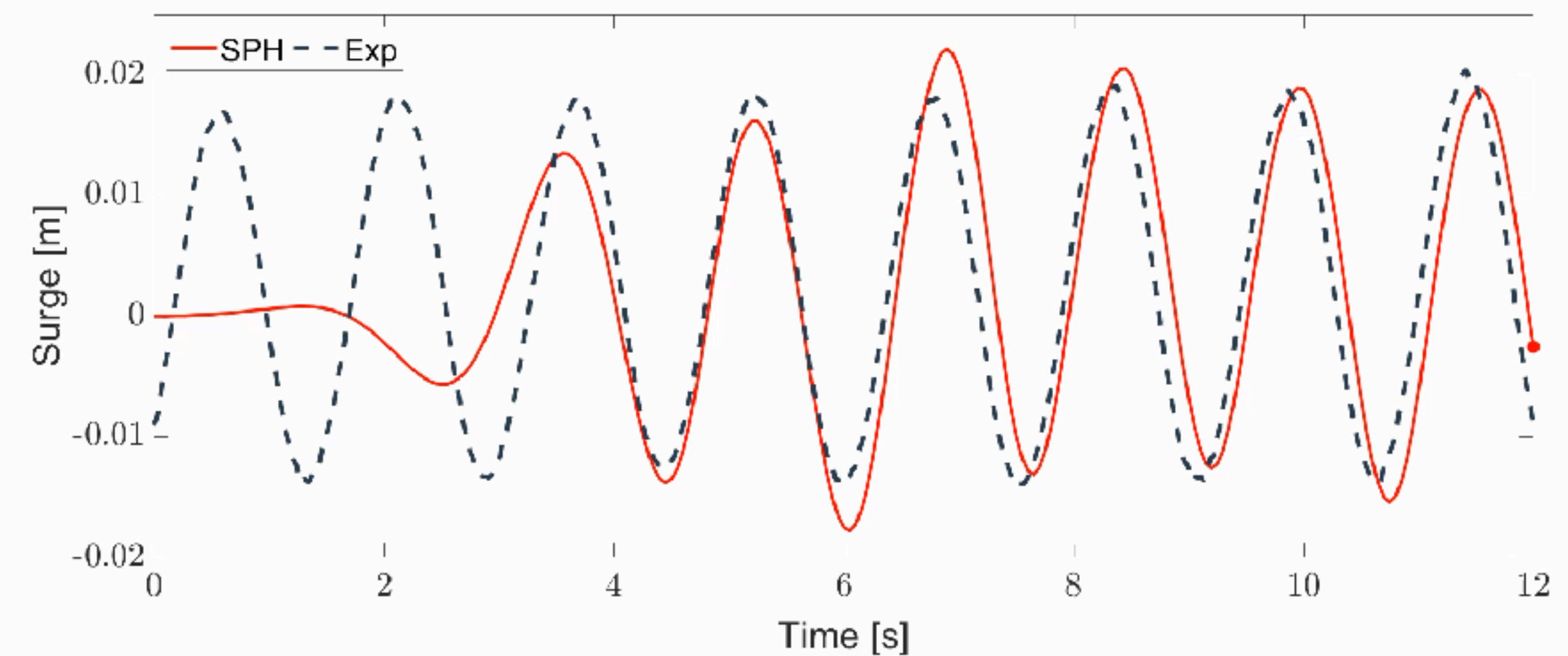
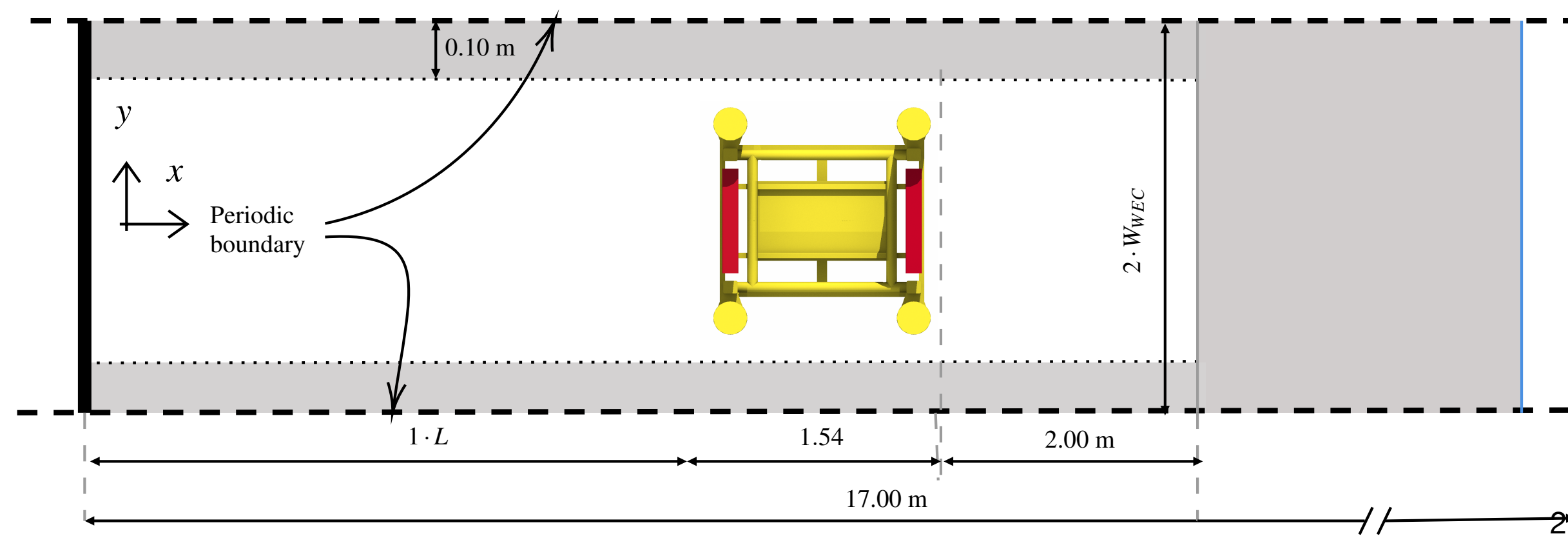
FOSWEC2

Regular wave validation

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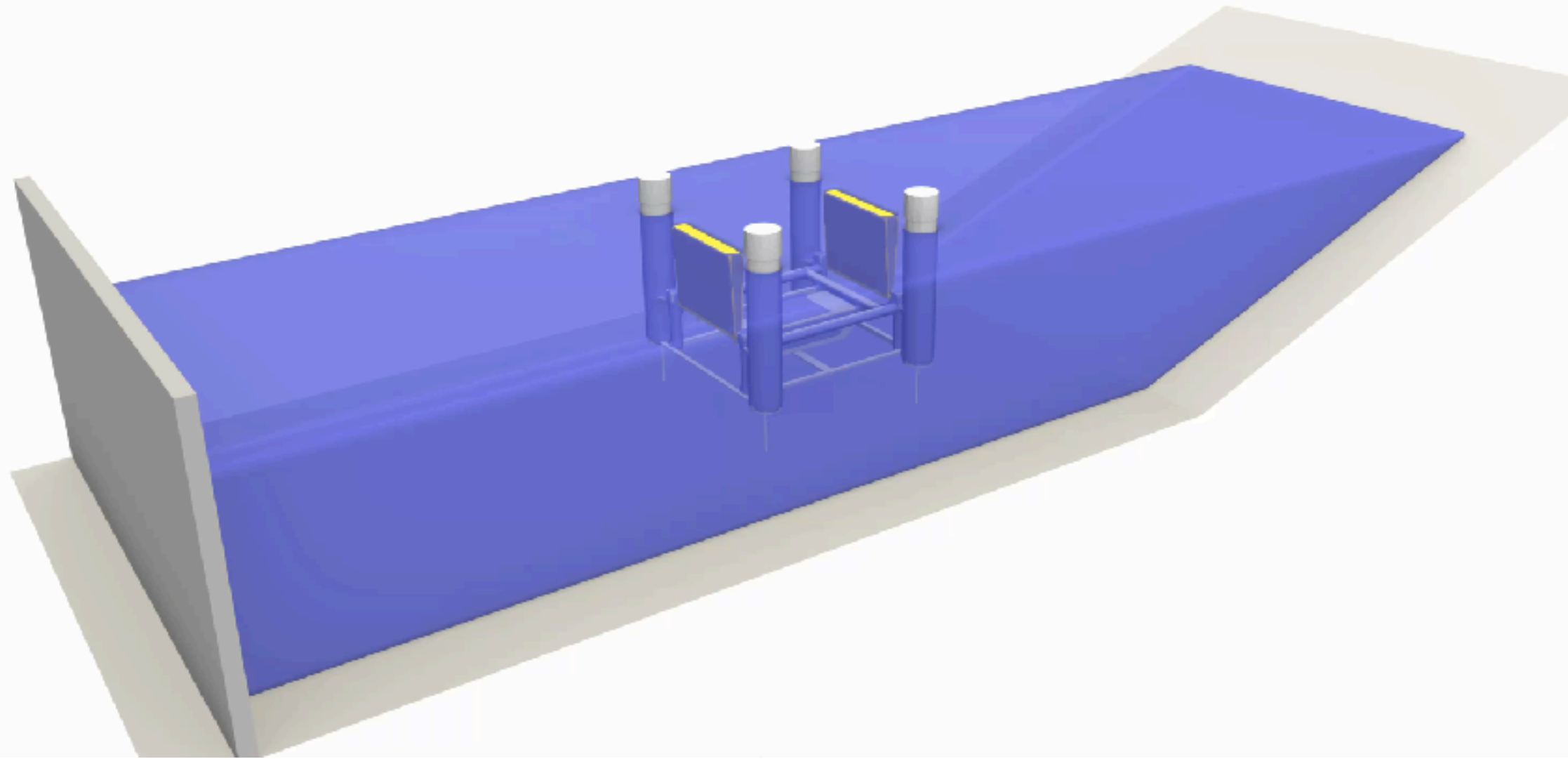
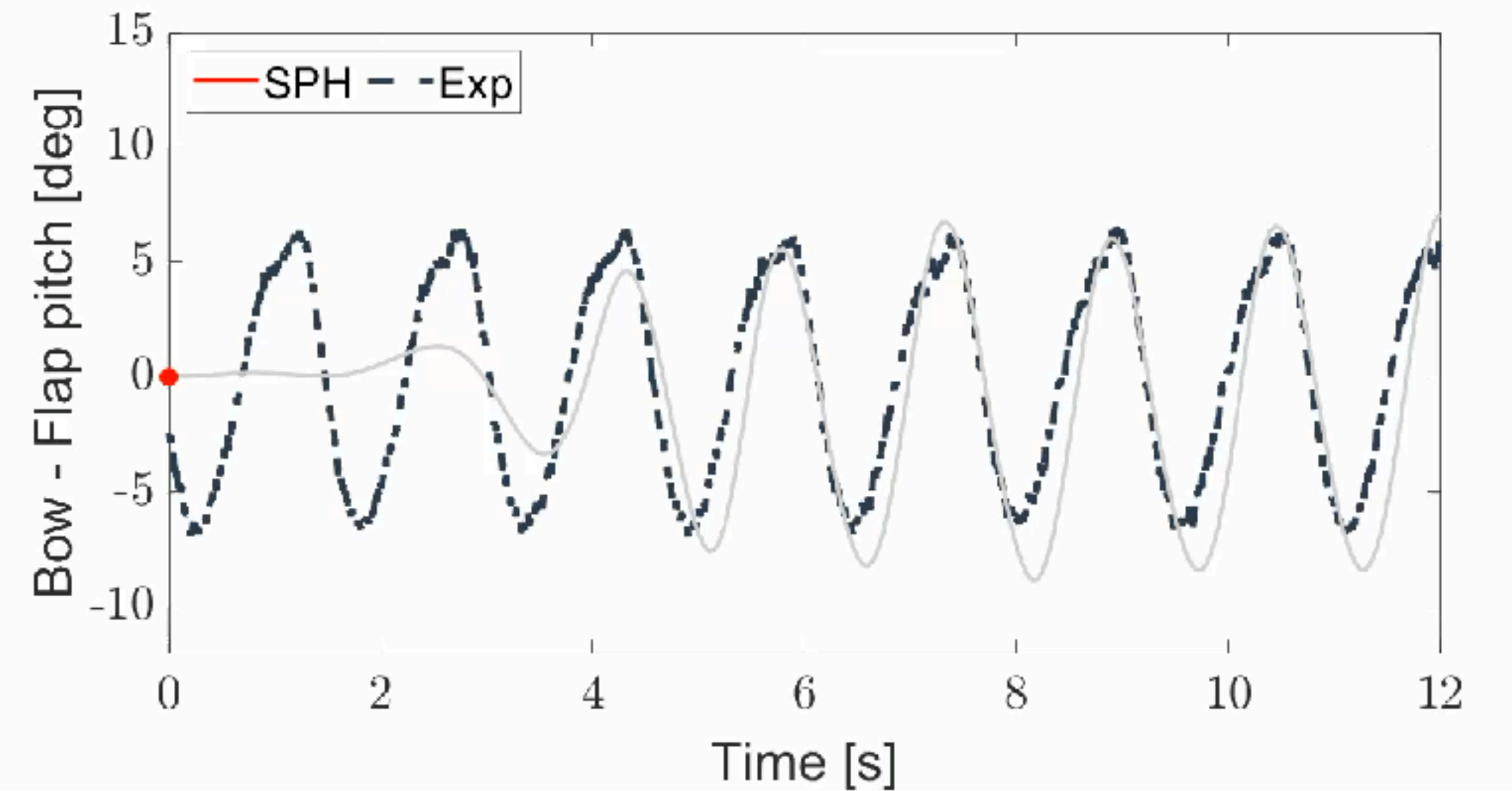
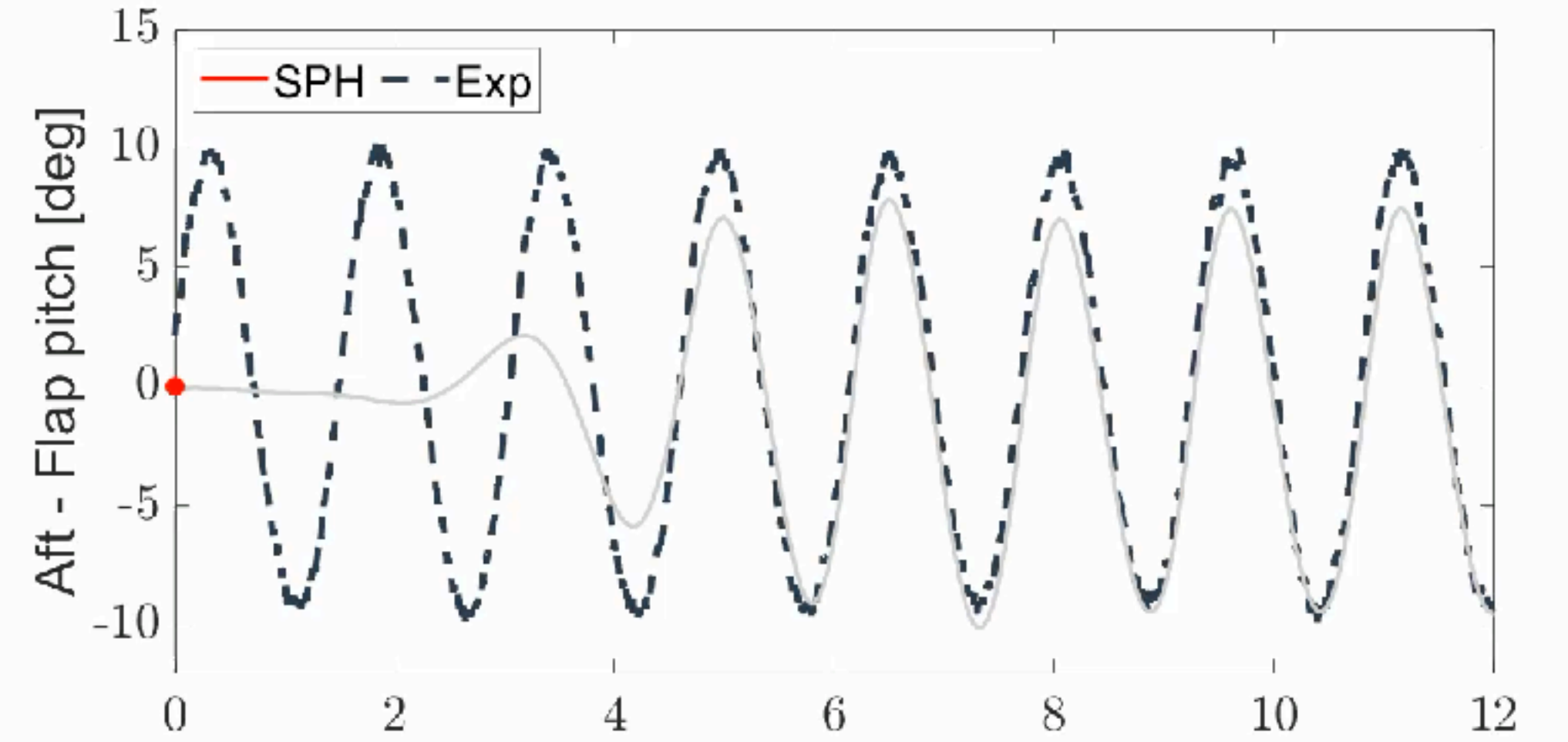
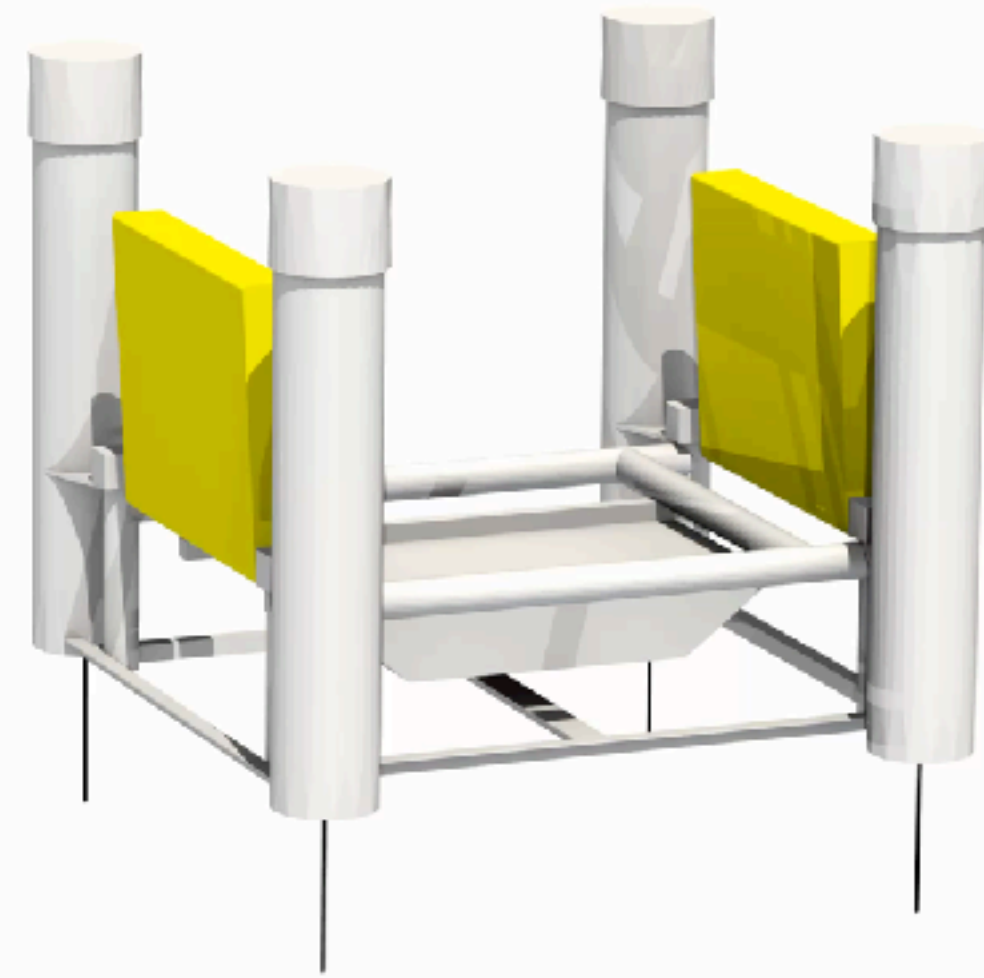


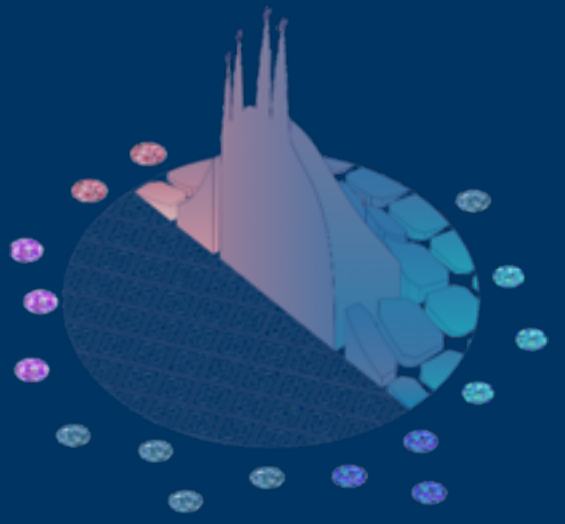
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Wave period	T	1.56	s
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Water depth	d	1.36	m
Wave length	L	3.73	m



FOSWEC2

Regular wave validation





3. Hybrid platform configuration

Wave–wind power units

Hybrid Wind-wave platforms



Rendered view of a wave-wind farm and a 1/40 experimental model of a wind-wave power system.

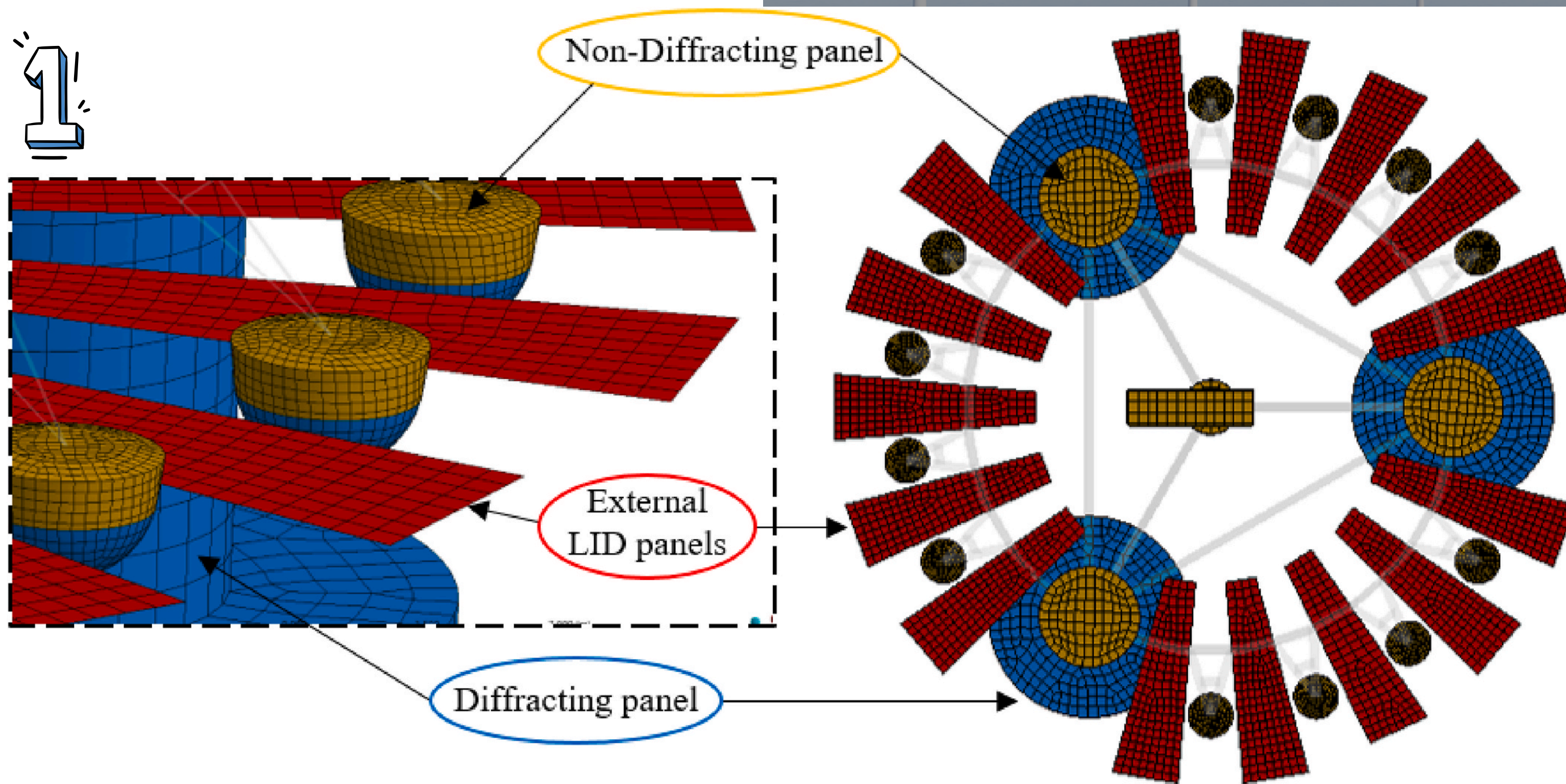
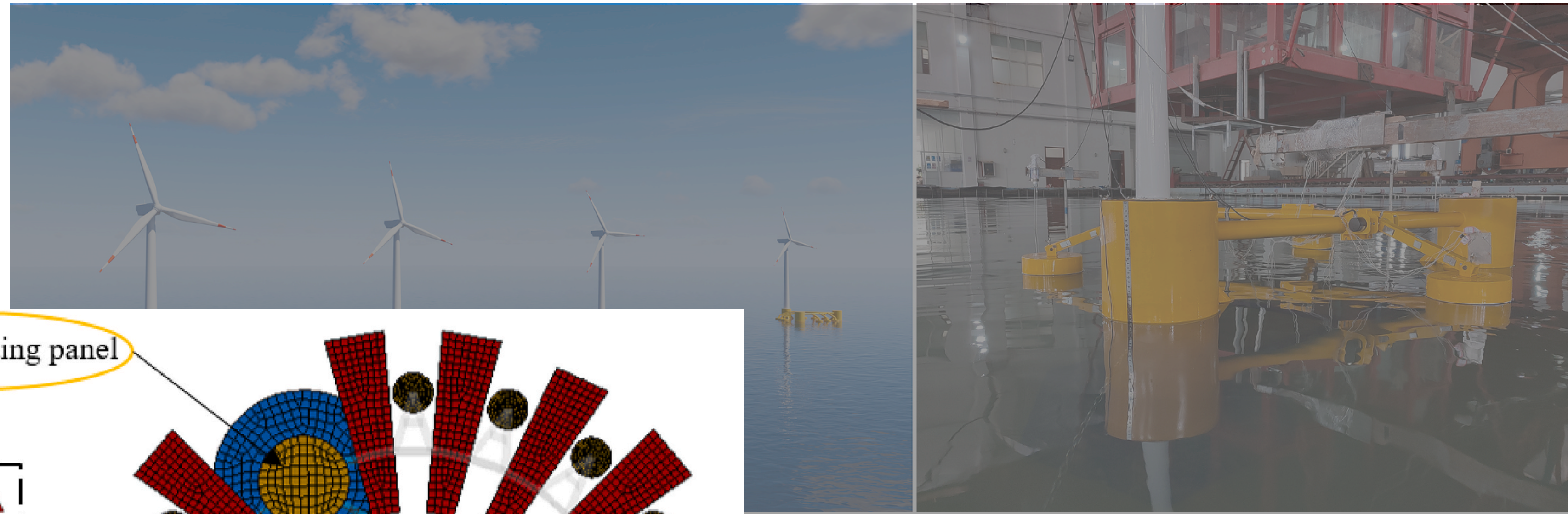
Wei, Z., Borthwick, A. G. L., Cao, F., Zhao, C., Han, M., Dai, M., & Shi, H. (2025). Power performance of an offshore floating hybrid wind and wave energy converter. *Energy Conversion and Management*, 341, 120023. <https://doi.org/10.1016/j.enconman.2025.120023>

Wei, Z., Cao, F., Cao, C., Han, Z., Shi, H., & Ji, T. (2025). Experimental study on the effects of an array of concentric wave energy converters on the dynamic of semi-submersible floating wind turbine. *Renewable Energy*, 242, 122495. <https://doi.org/10.1016/j.renene.2025.122495>

Wave energy combined to wind

- Synergy for performance
- Synergy for infrastructure
- Benefits the power grid

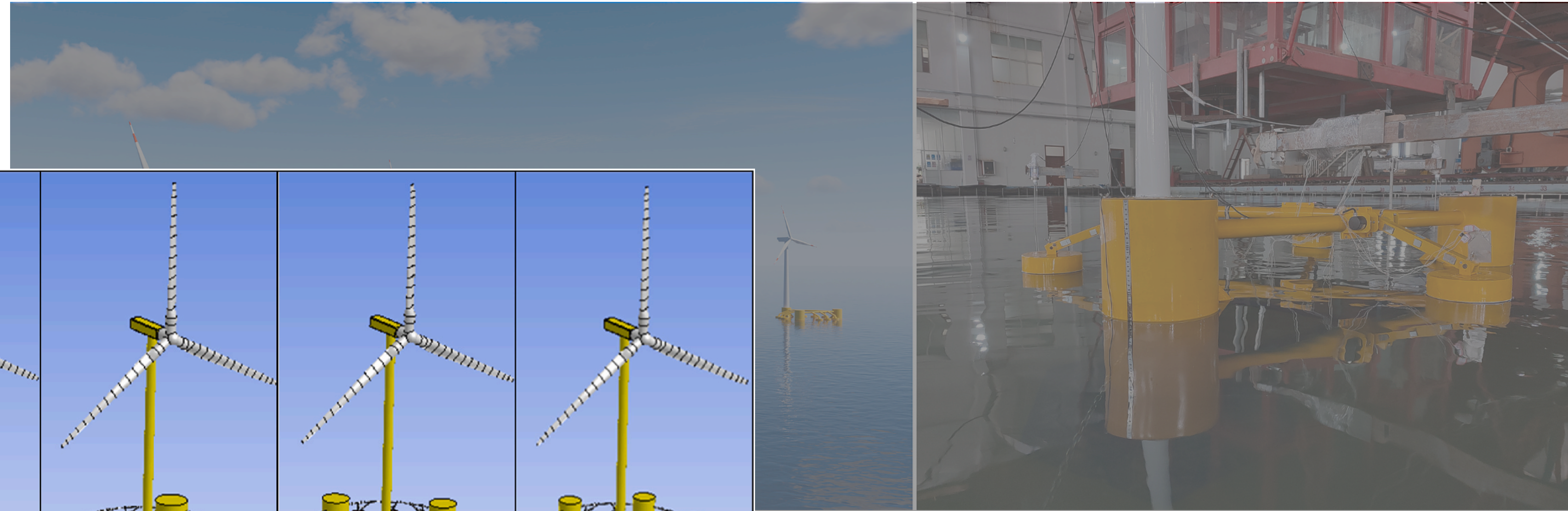
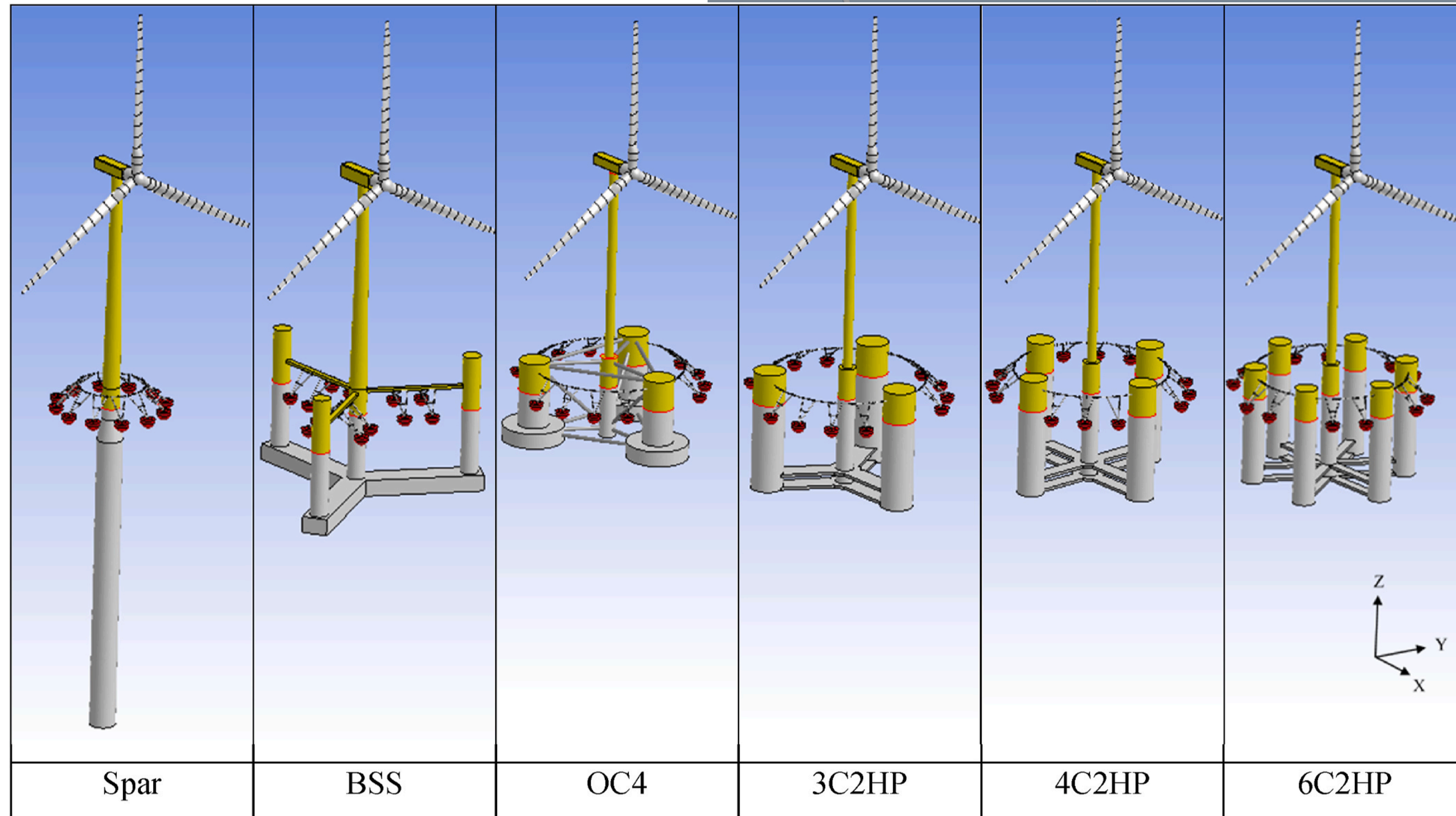
Hybrid Wind-wave platforms



Panel models of the multibody system, including diffracting panels and external LID panels.

Ghafari, H. R., Ghassemi, H., & Akbari Vakilabadi, K. (2025). Hydrodynamic performance and power absorption of the hybrid wind-wave energy systems with different platform geometries. *Ocean Engineering*, 332, 121440. <https://doi.org/10.1016/j.oceaneng.2025.121440>

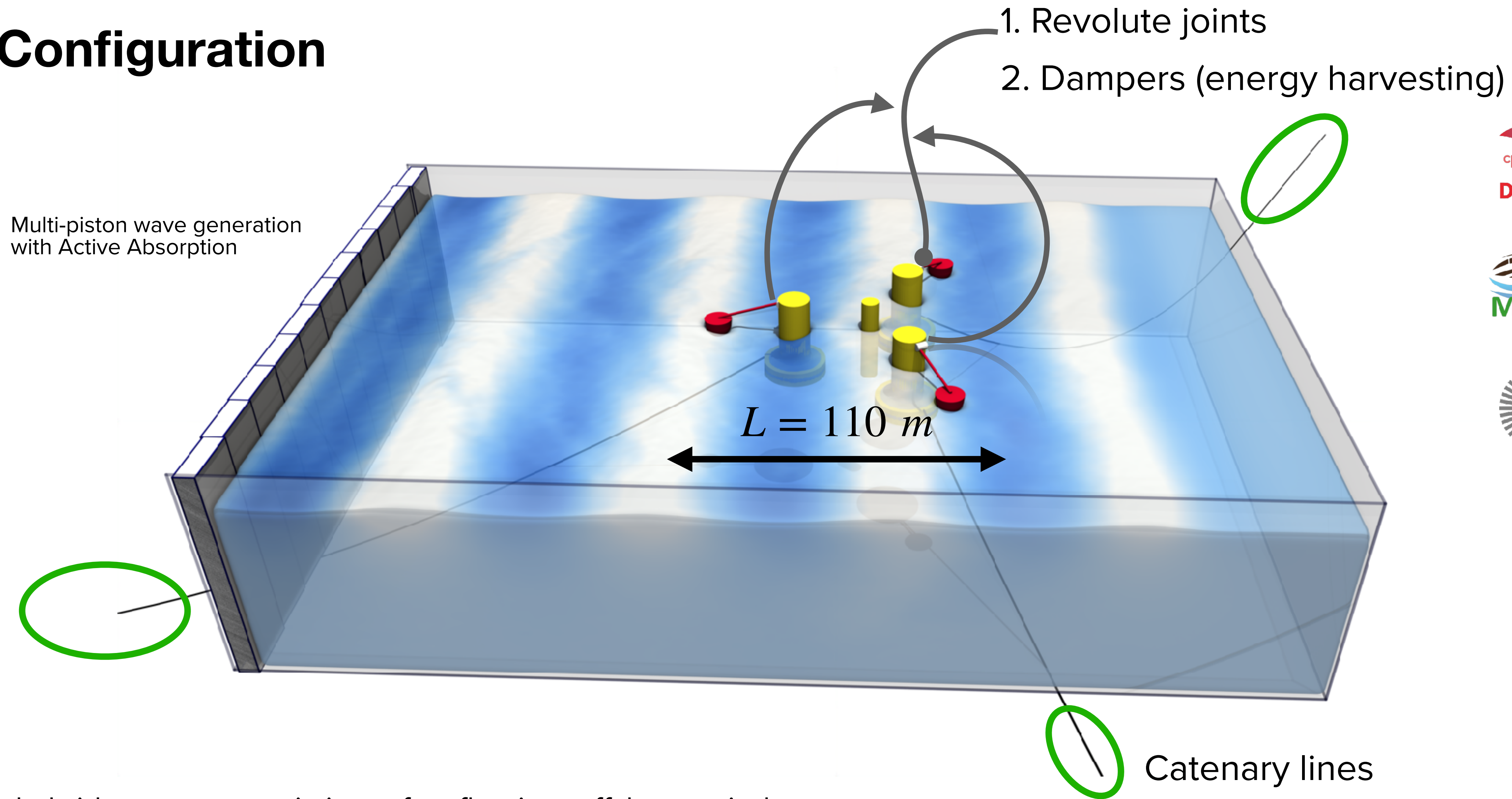
Hybrid Wind-wave platforms



Different types of floating platforms for hybrid wind-wave systems (Wavestar: $N=12$, $D=5.00$ m).

Ghafari, H. R., Ghassemi, H., & Akbari Vakilabadi, K. (2025). Hydrodynamic performance and power absorption of the hybrid wind-wave energy systems with different platform geometries. *Ocean Engineering*, 332, 121440. <https://doi.org/10.1016/j.oceaneng.2025.121440>

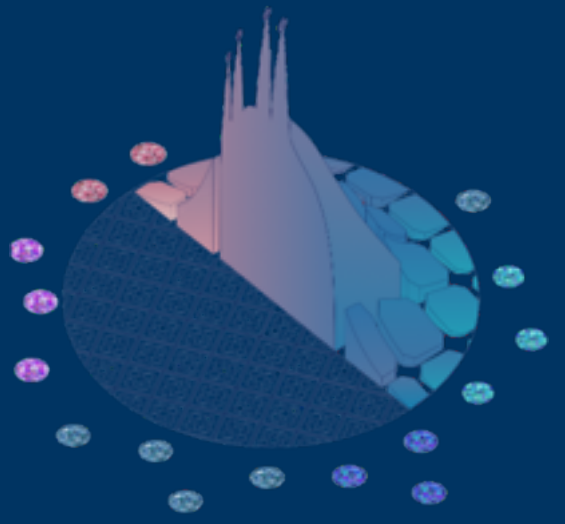
Semi-sub and Wavestar Configuration



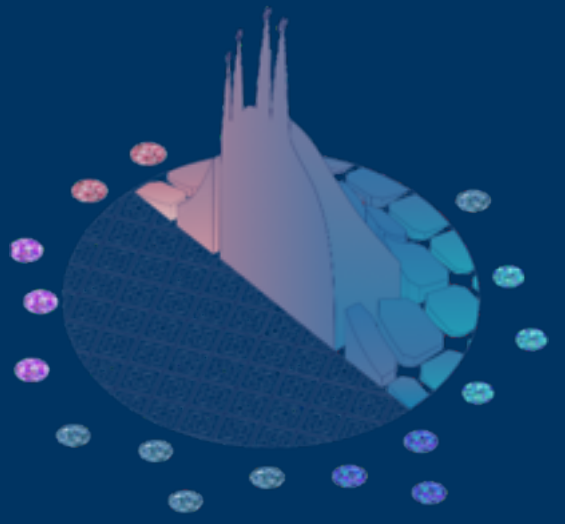
A hybrid system consisting of a floating offshore wind turbine and wave energy converters (WECs) is promising for multiple extractions of ocean renewable energy.

Jin, P., Zheng, Z., Zhou, Z., Zhou, B., Wang, L., Yang, Y., & Liu, Y. (2023). Optimization and evaluation of a semi-submersible wind turbine and oscillating body wave energy converters hybrid system. *Energy*, 282, 128889. <https://doi.org/10.1016/j.energy.2023.128889>

Challenge



- 1. Coexistence of very dissimilar structures (WECs and FOWTs)**
- 2. Simulation of larger domains**
- 3. Long simulations**



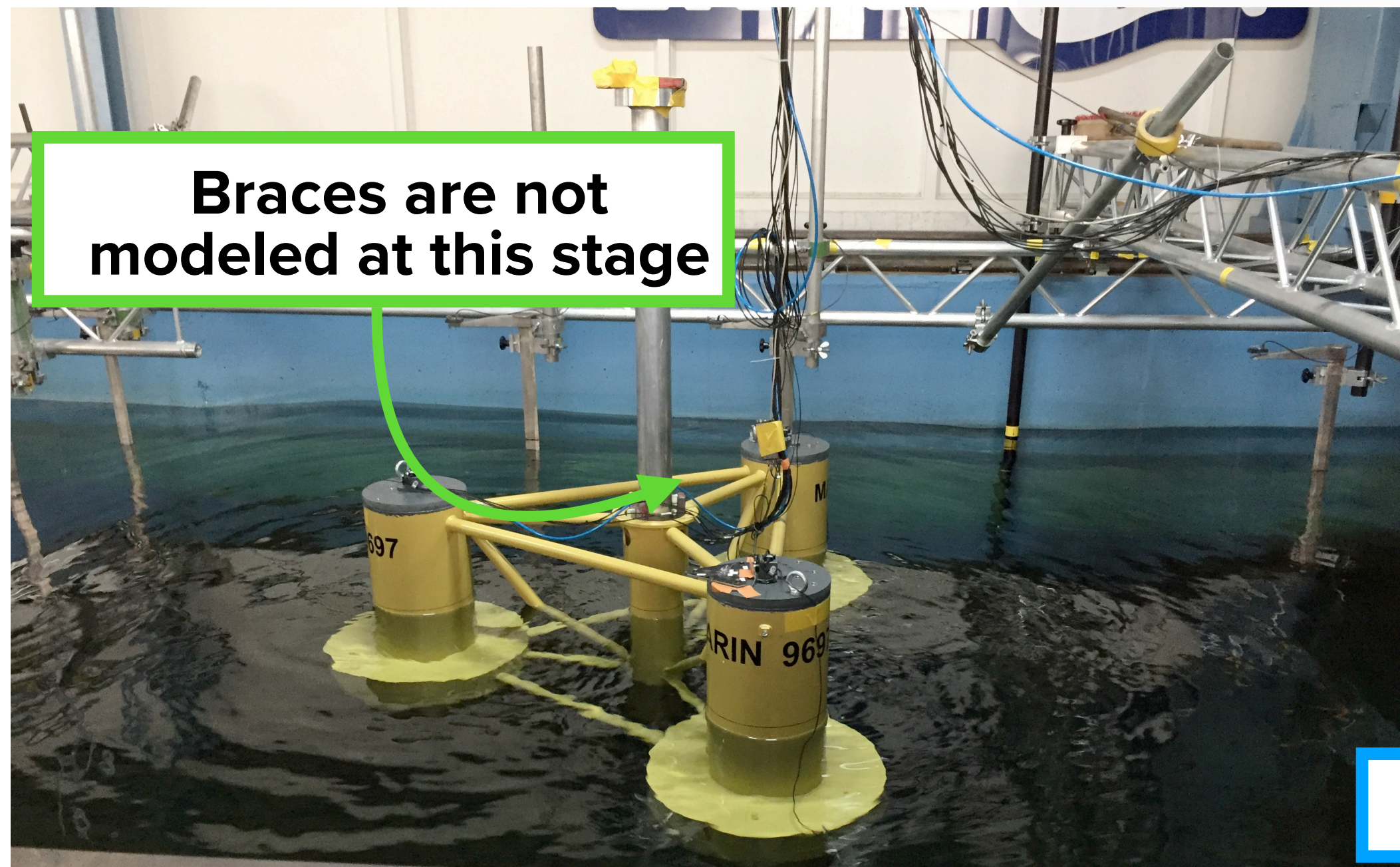
Floating offshore wind

DeepCwind Platform

Packing algorithm for particle positioning

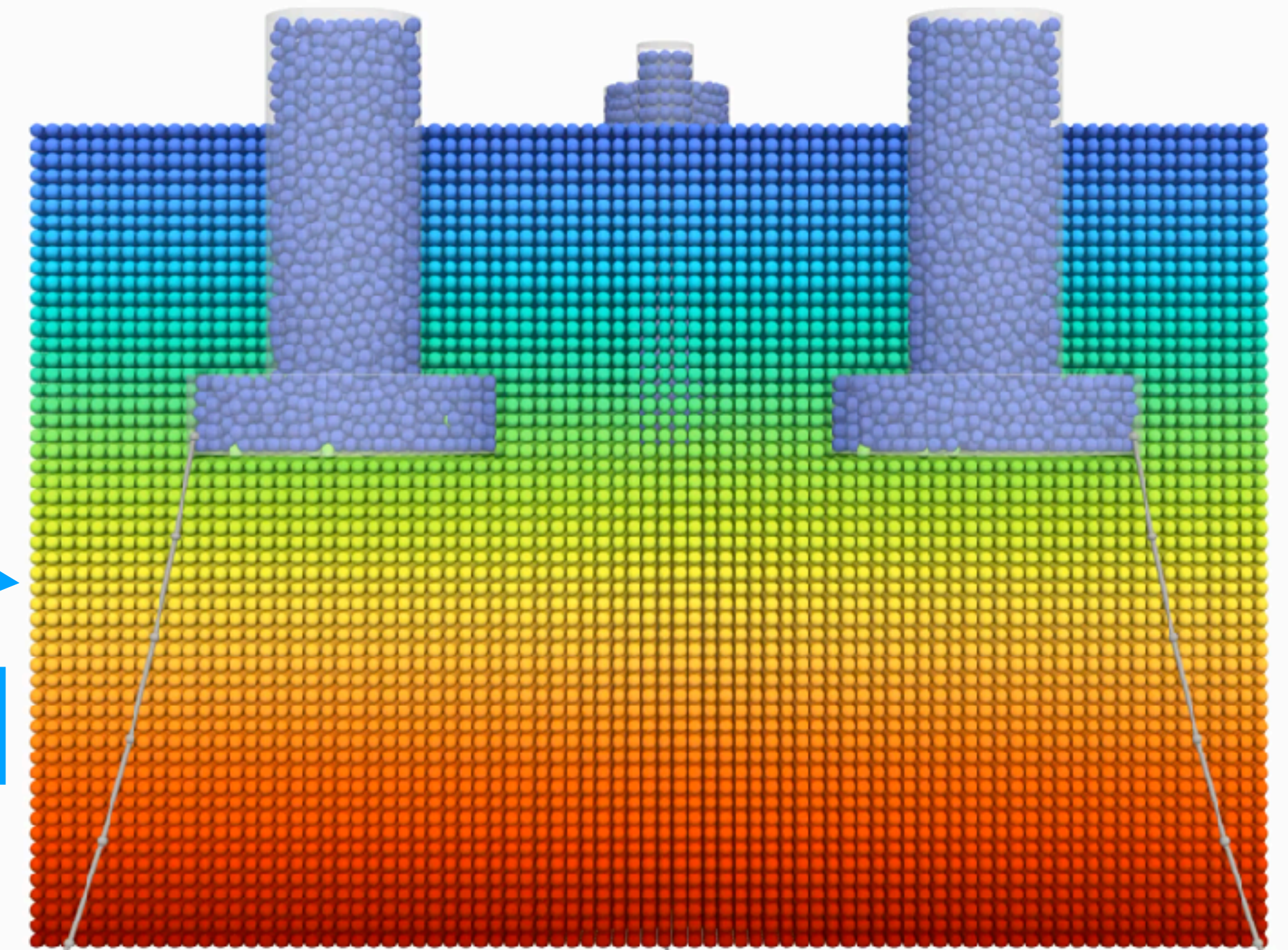
DEEPCWIND USED IN OC6-PHASE IA

	Particle size	Float Particles	Total Particles	Runtime
D_p=T/5	1.25 cm	22 k	3.6 M	2.3 h



Phase I of the OC6 project is focused on examining **why** offshore wind design tools underpredict the response (loads/motion) of the OC5-DeepCwind semisubmersible at its surge and pitch natural frequencies.

Simulation time: 15 seconds



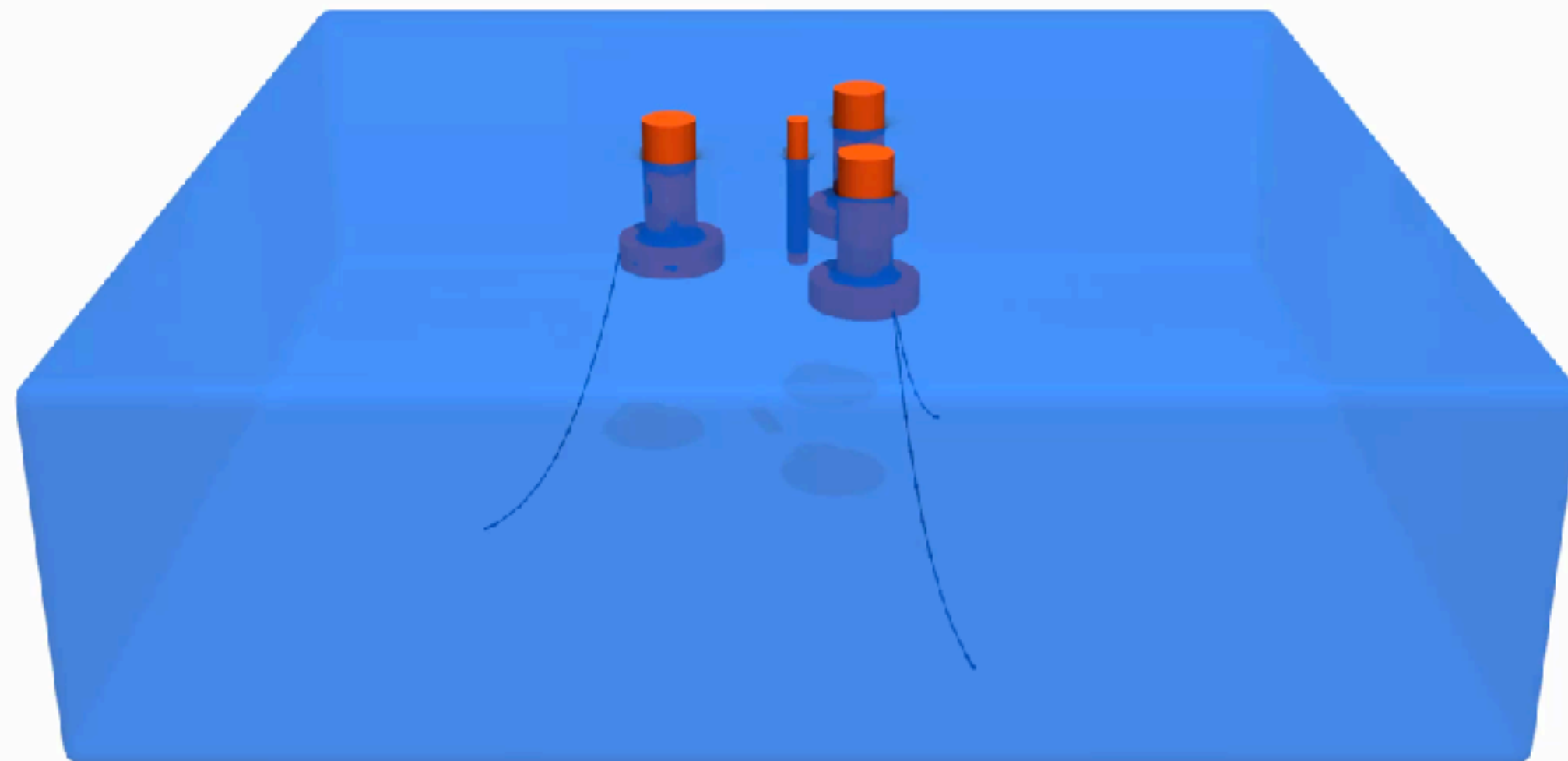
Heave decay test with initial negative displacement

Decay test

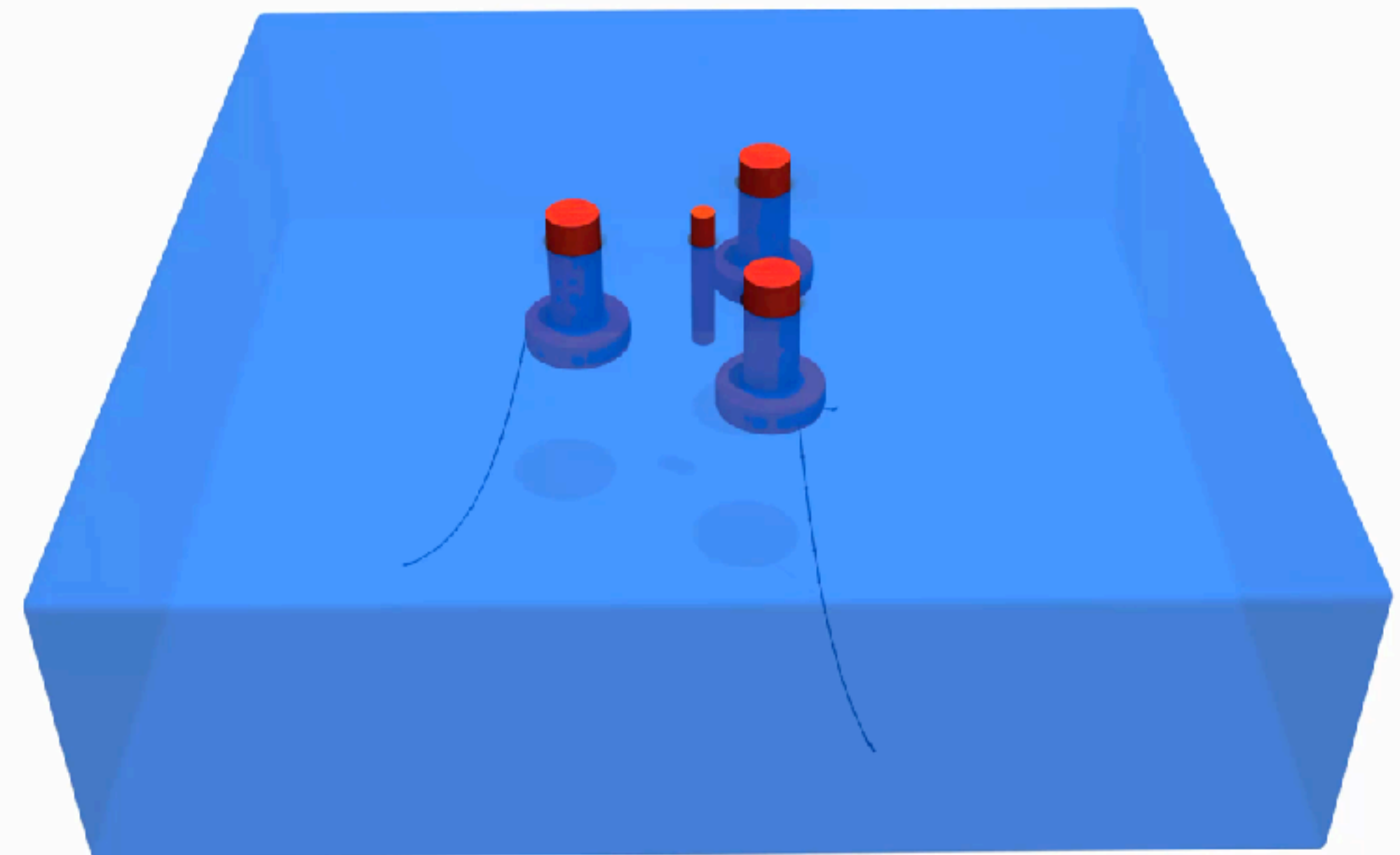
Heave

	Particle size	Float Particles	Total Particles	Runtime
Dp=T/5	1.25 cm	22 k	3.2 M	1.9 h
Dp=T/10	0.62 cm	100 k	20 M	23 h

Simulation time: 15 seconds



Coloring represents magnitude velocity



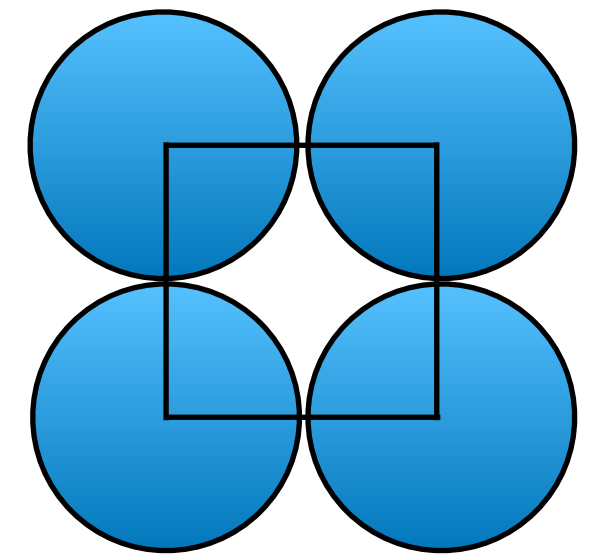
Coloring represents magnitude velocity

Packing algorithm for particle positioning

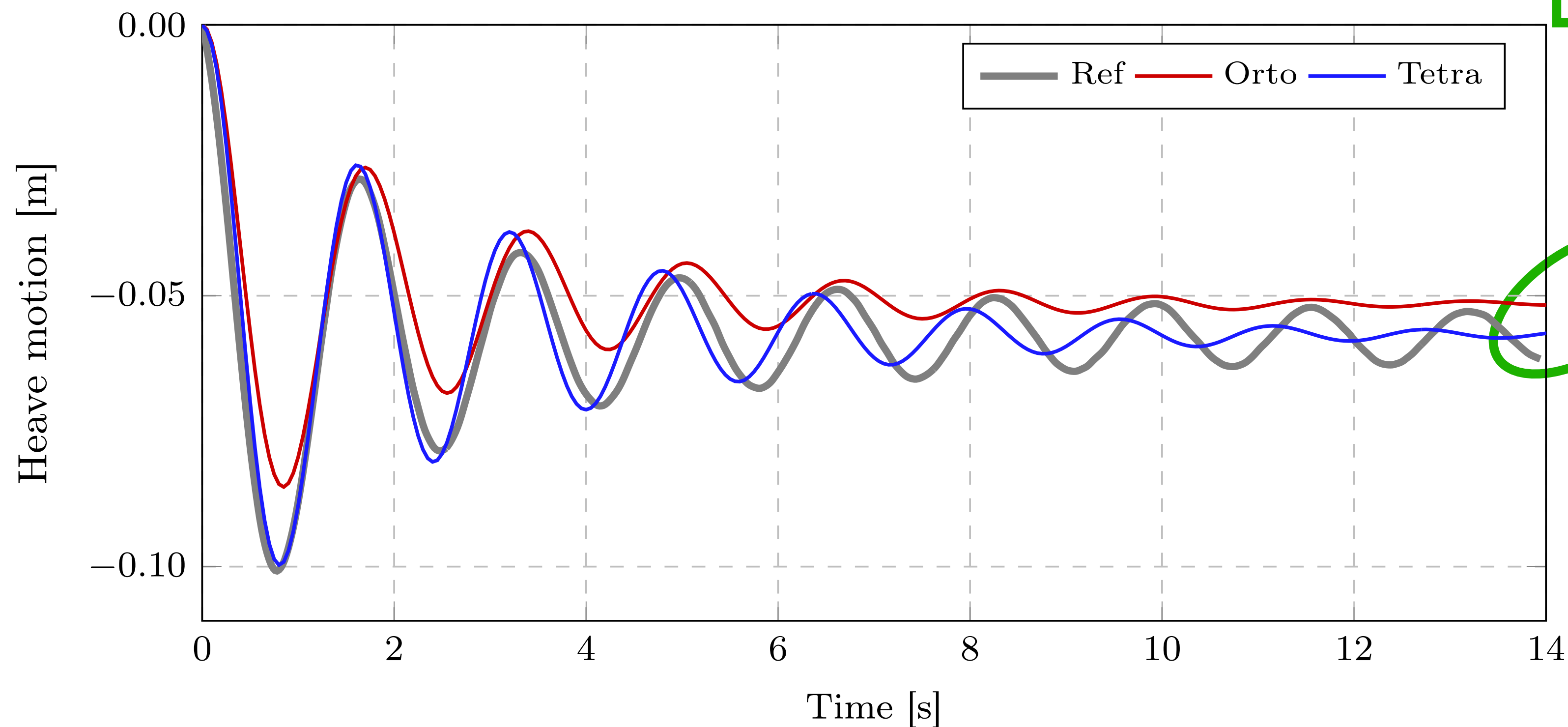
Comparison $D_p = T/5$

Laminar viscosity

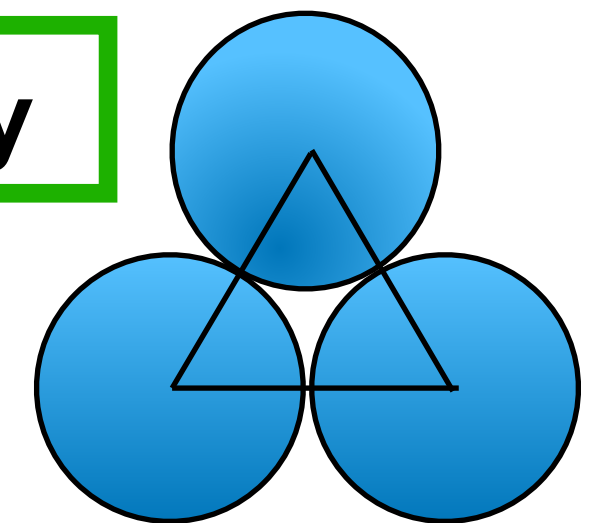
	Main frequency (s)	Damping ratio (δ_2)	Error
Orto	1.65	3.5%	7%
Tetra	1.60	3.0%	4%
Reference	1.64	2.0%	-



Orto Lattice



Better buoyancy



Triangular Lattice

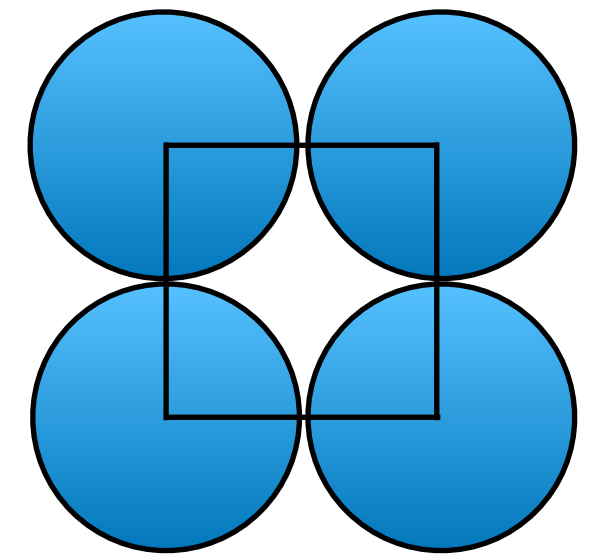
CHRONO
DEM-Engine

cpu gpu
DualSPHysics

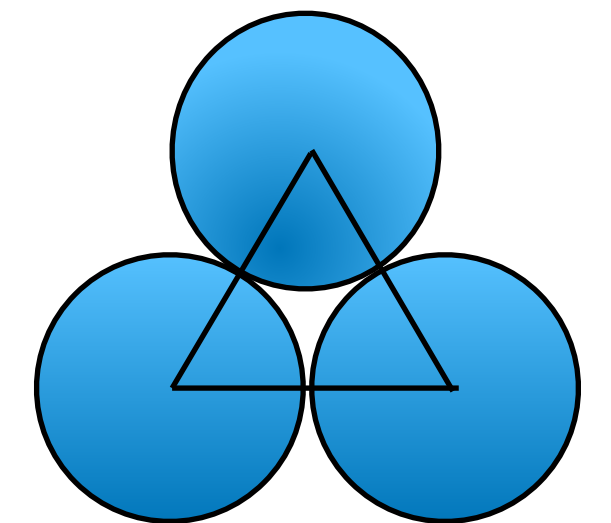
Packing algorithm for particle positioning

Viscosity model

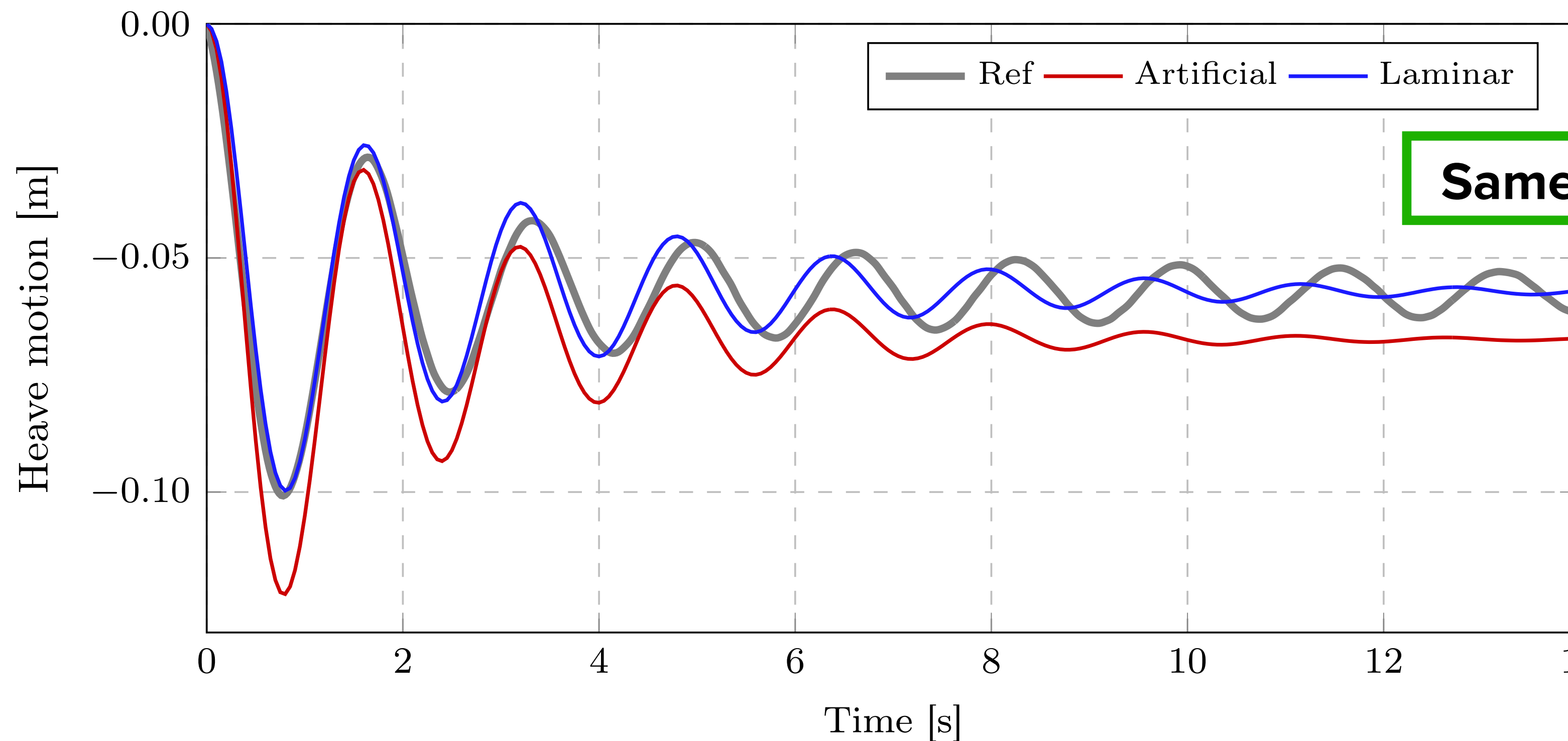
	Main frequency (s)	Damping ratio (δ_2)	Error
Orto	1.65	3.5%	7%
Tetra	1.60	3.0%	4%
Reference	1.64	2.0%	-



Orto Lattice



Triangular Lattice

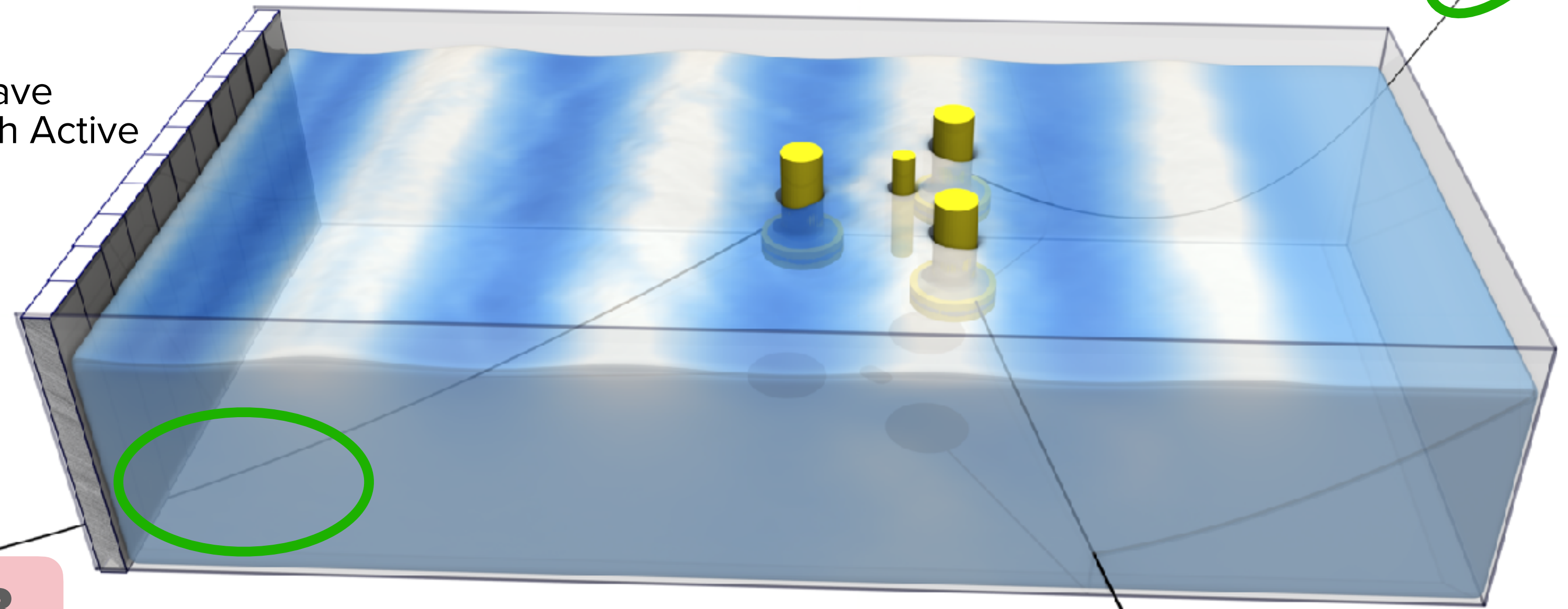


CHRONO
DEM-Engine

cpu gpu
DualSPHysics

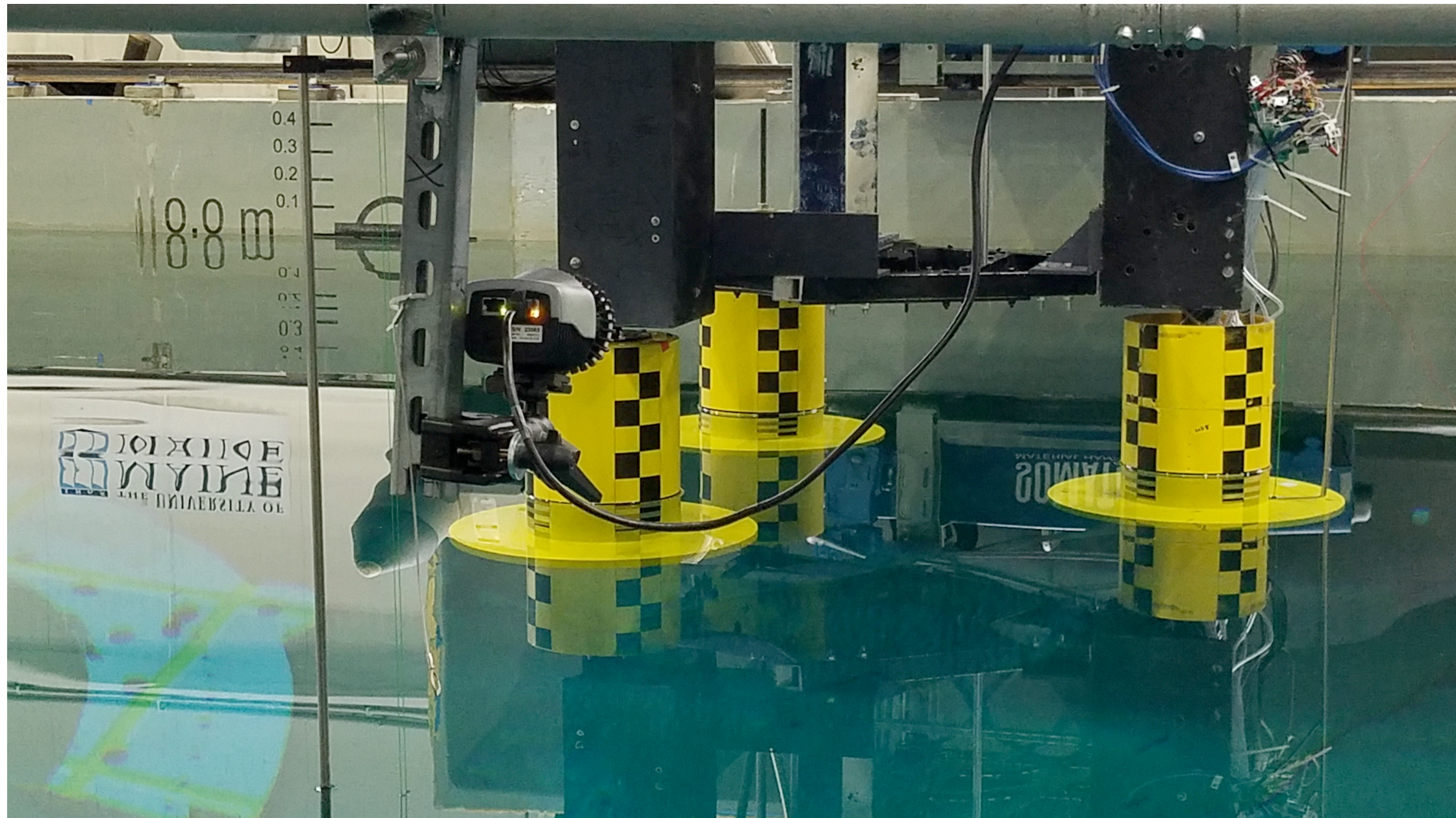
Hydrodynamic load validation

Multi-piston wave generation with Active Absorption

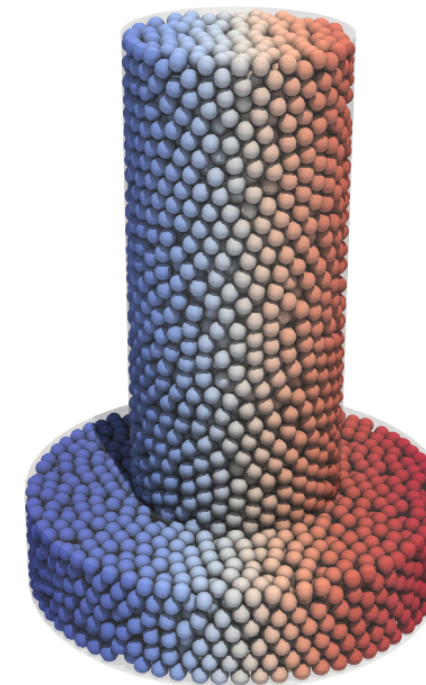


Images courtesy of Amy Robertson (NREL)

DEEPCWIND USED IN OC6-PHASE IB



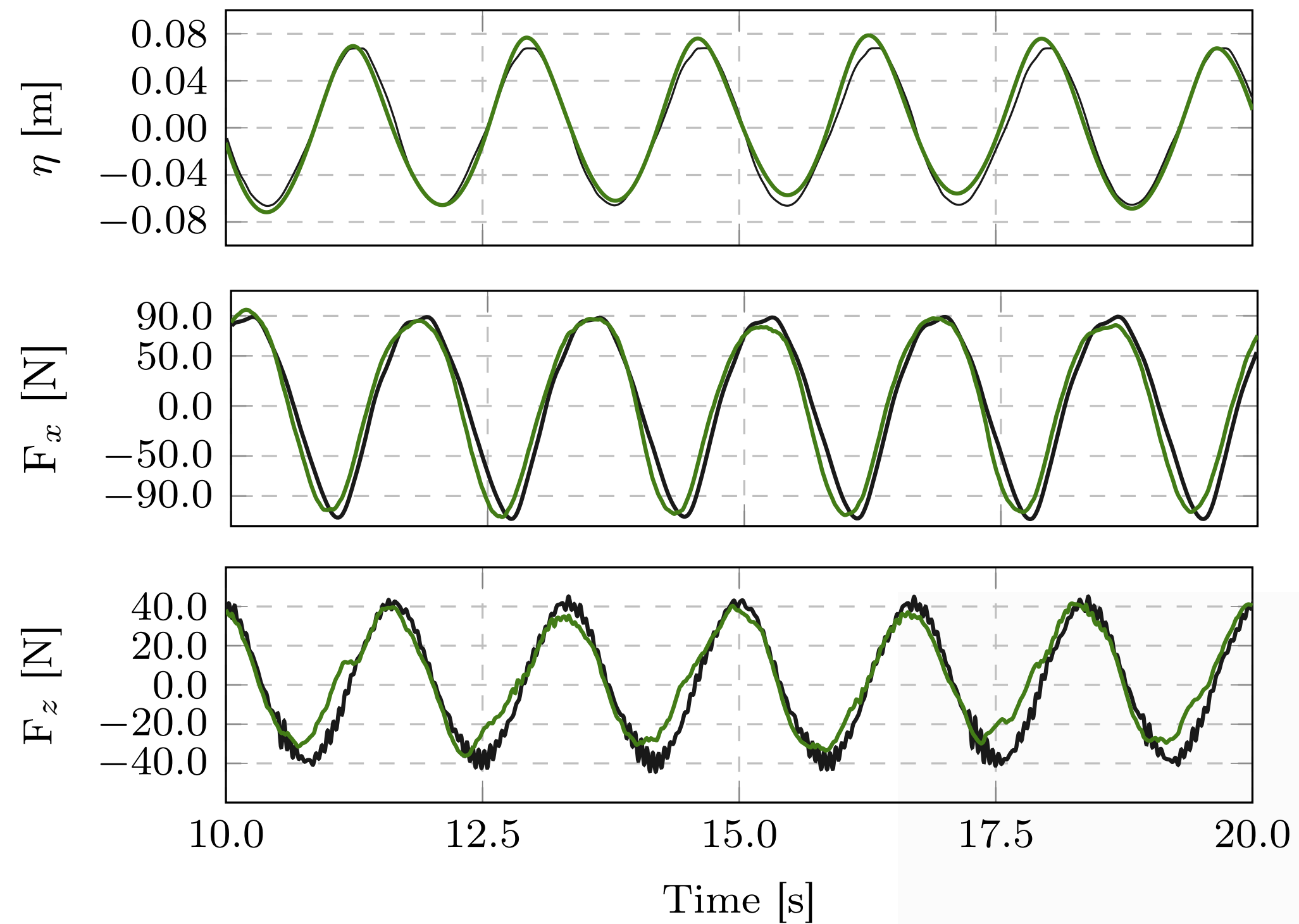
BC Initialization



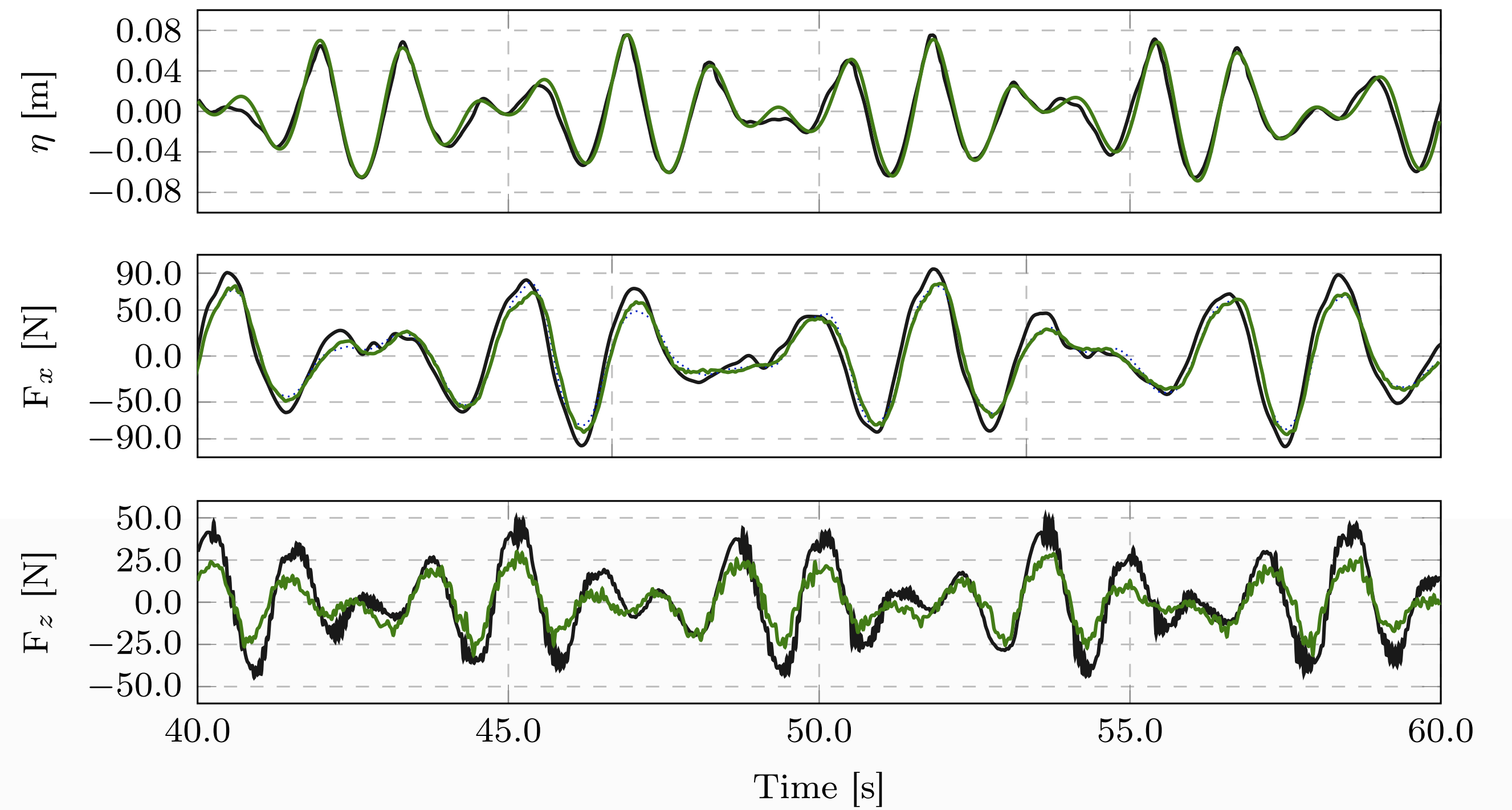
Tagliafierro, B., Karimirad, M., Altomare, C., Göteman, M., Martínez-Estévez, I., Capasso, S., Domínguez, J. M., Viccione, G., Gómez-Gesteira, M., & Crespo, A. J. C. (2023). Numerical validations and investigation of a semi-submersible floating offshore wind turbine platform interacting with ocean waves using an SPH framework. *Applied Ocean Research*, 141, 103757. <https://doi.org/10.1016/j.apor.2023.103757>

Validation

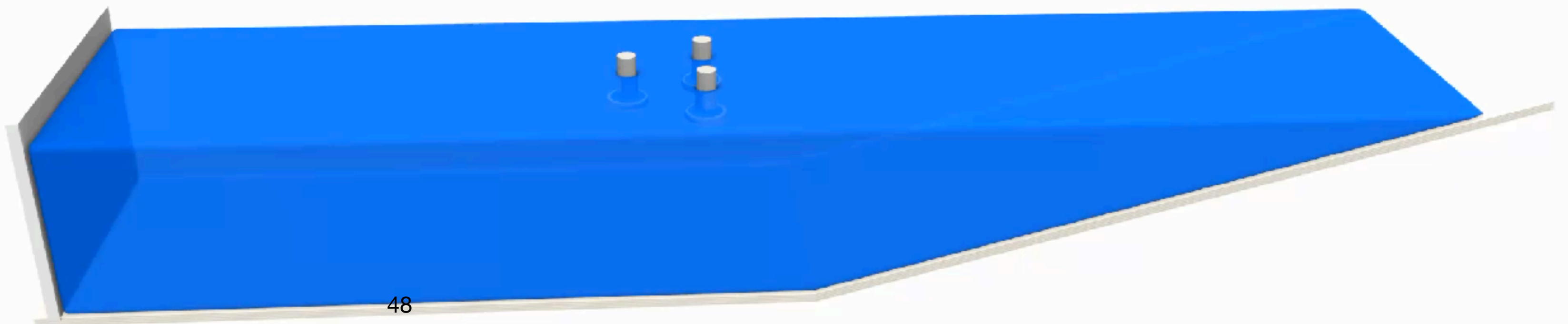
Regular waves



Bichromatic waves

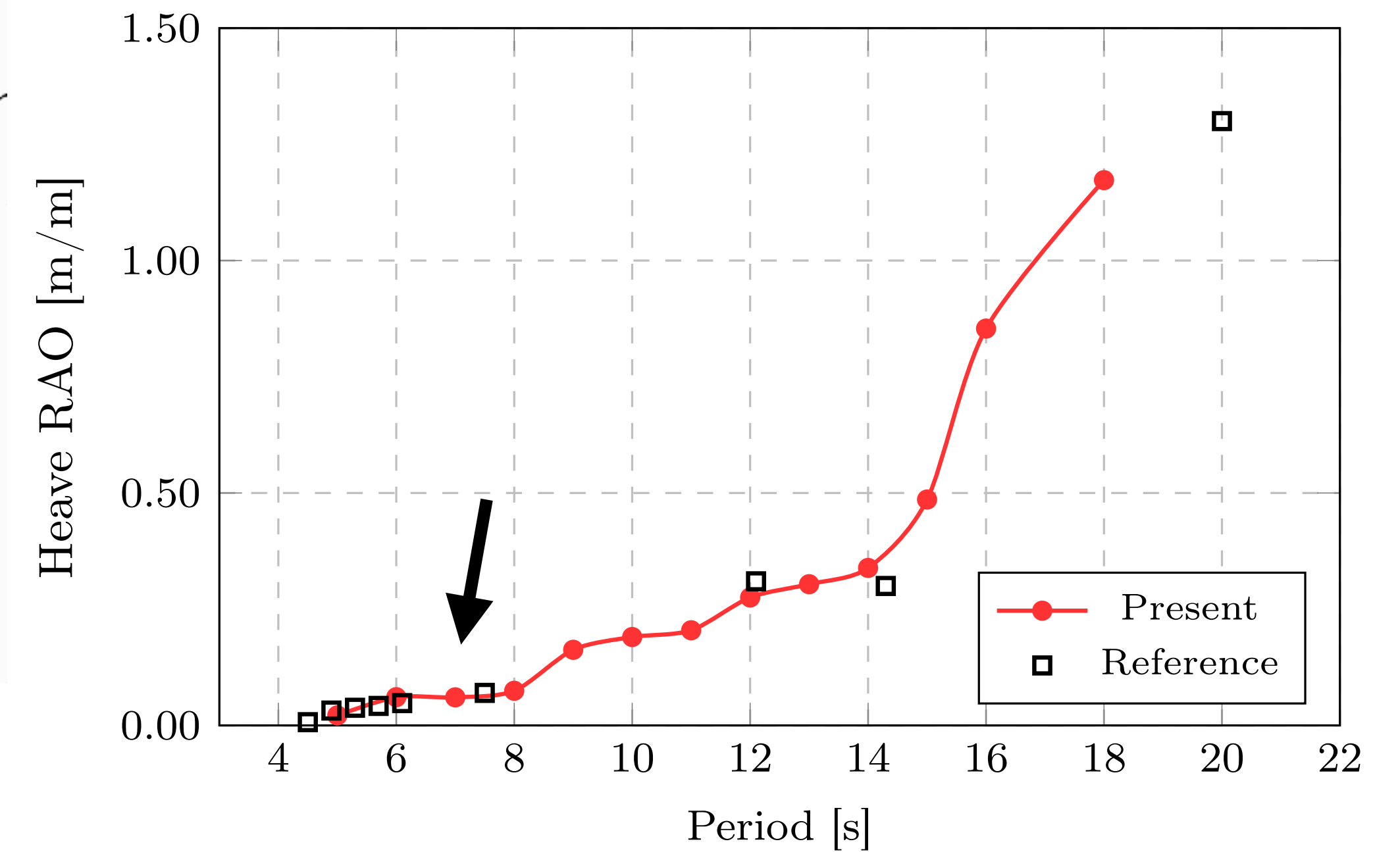
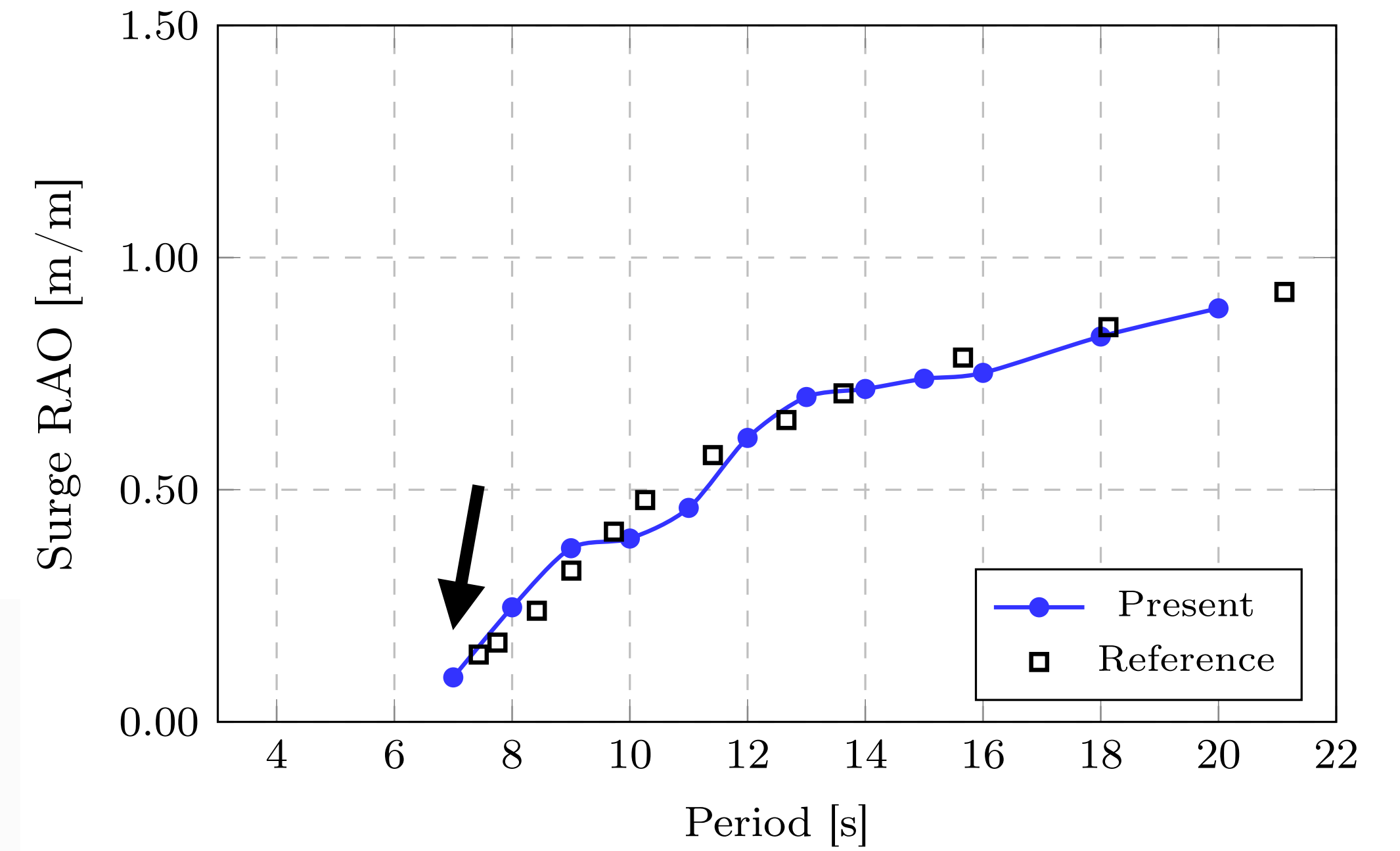
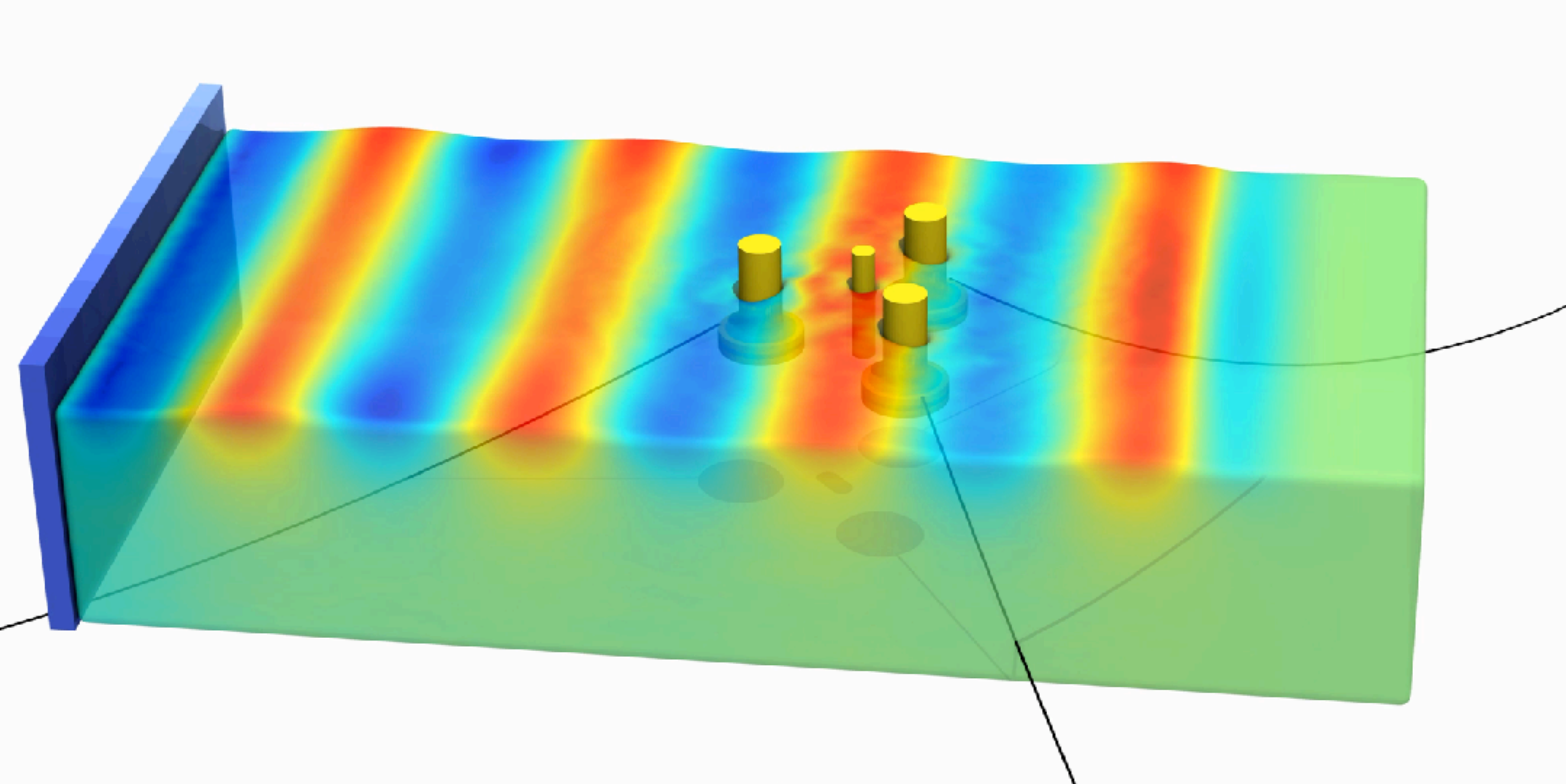


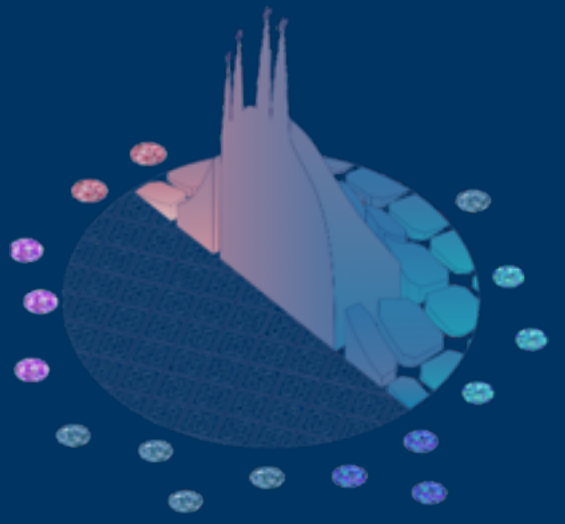
The platform is fixed, so these simulations do not include any external library.



Spectral response

	H	T
R7	3.00 m	7.00 s



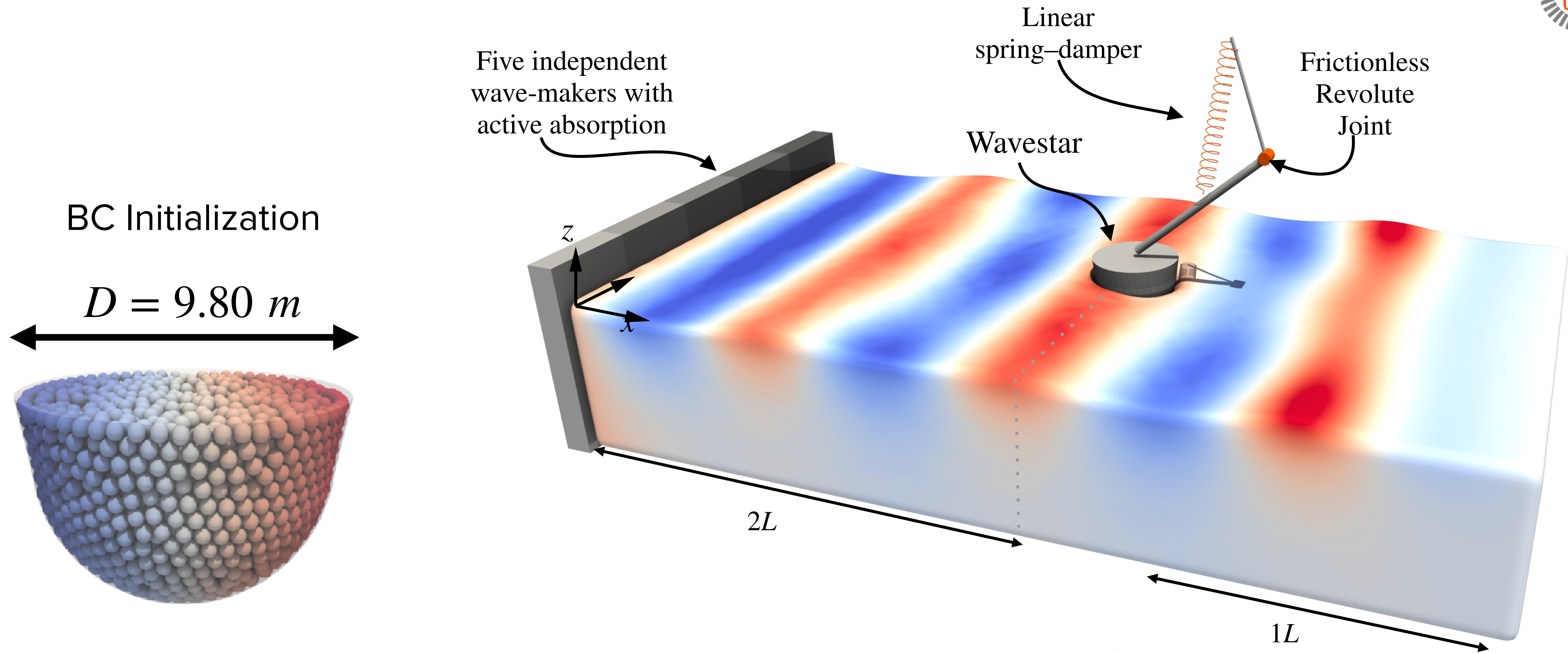


Wave energy converters

Wavestar

Wavestar

General overview

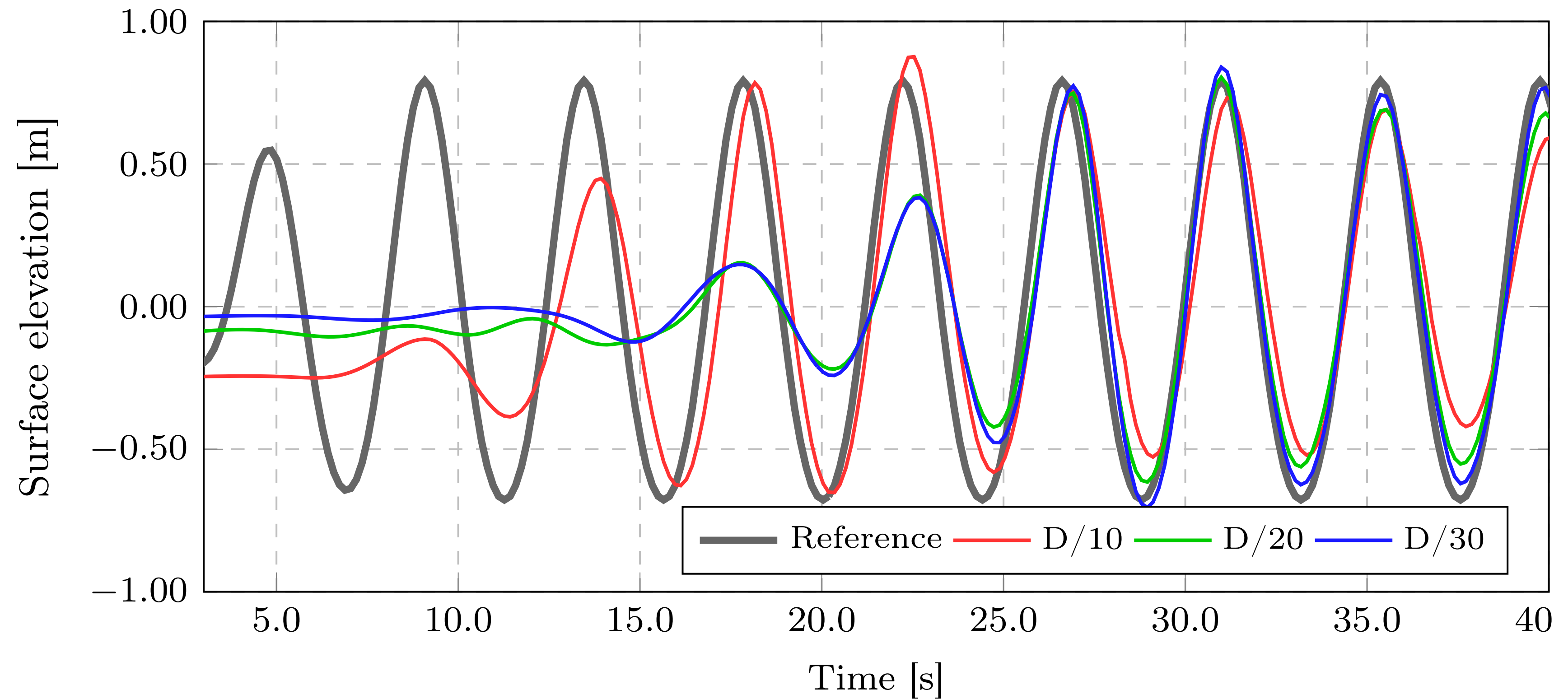


Windt et al. (2020). Validation of a CFD-based numerical wave tank model for the power production assessment of the wavestar ocean wave energy converter. *Renewable Energy*, 146, 2499-2516. <https://doi.org/10.1016/j.renene.2019.08.059>

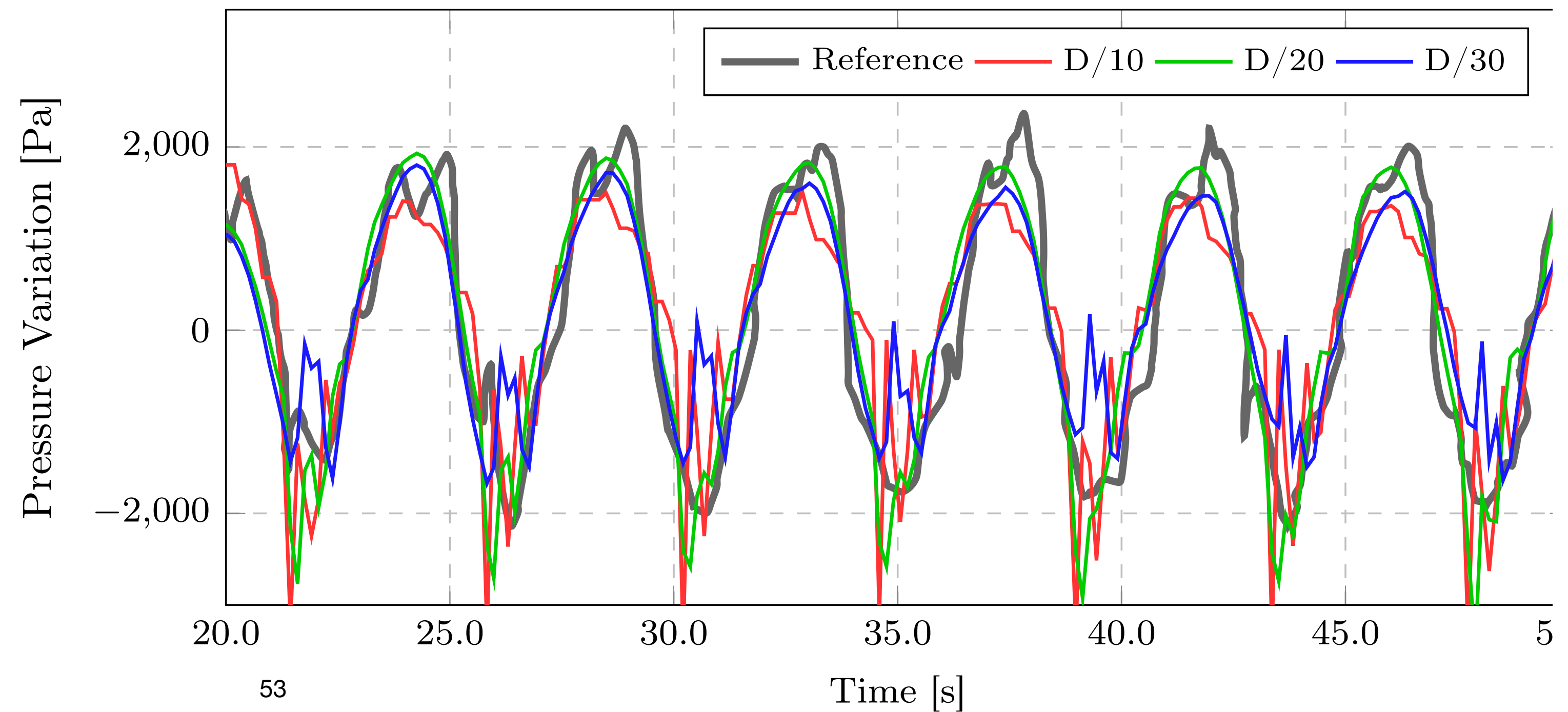
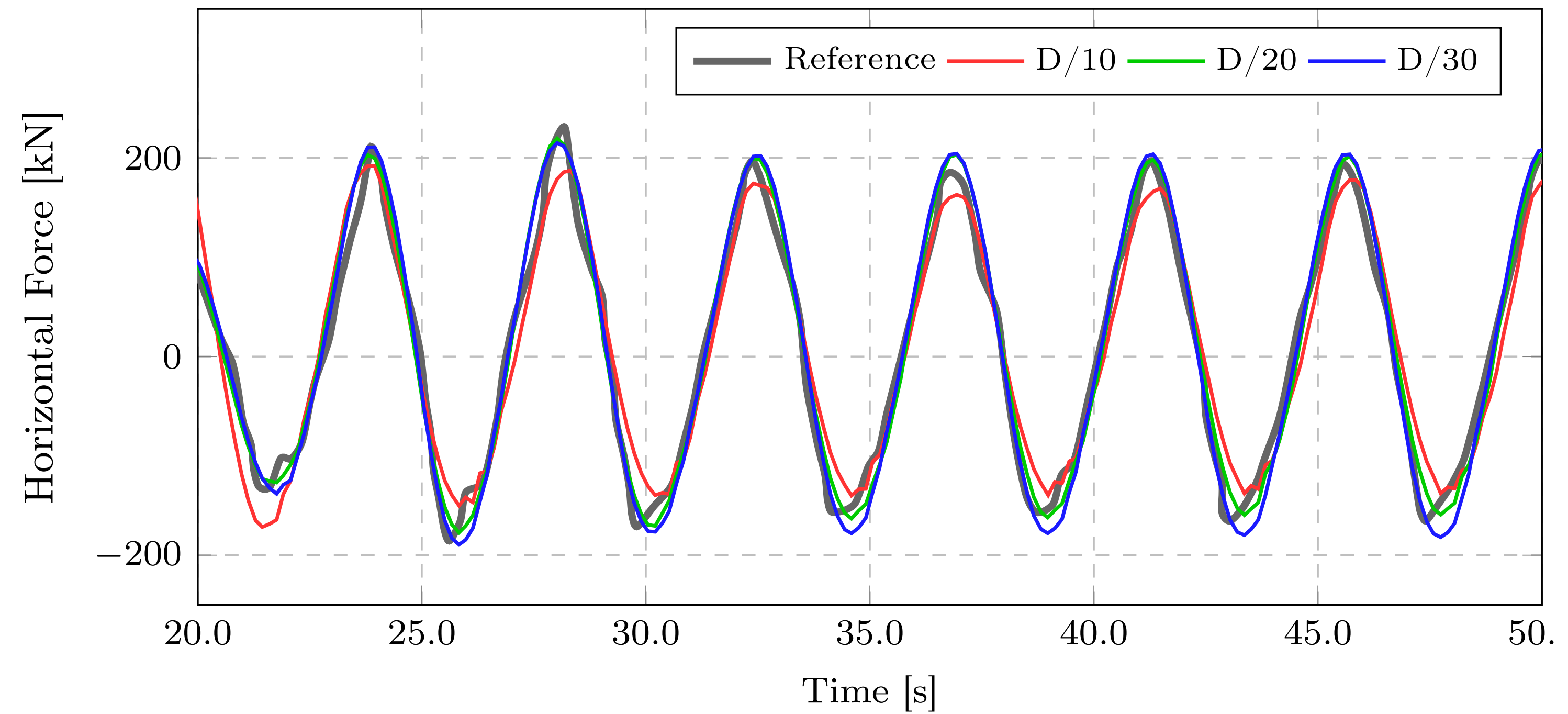
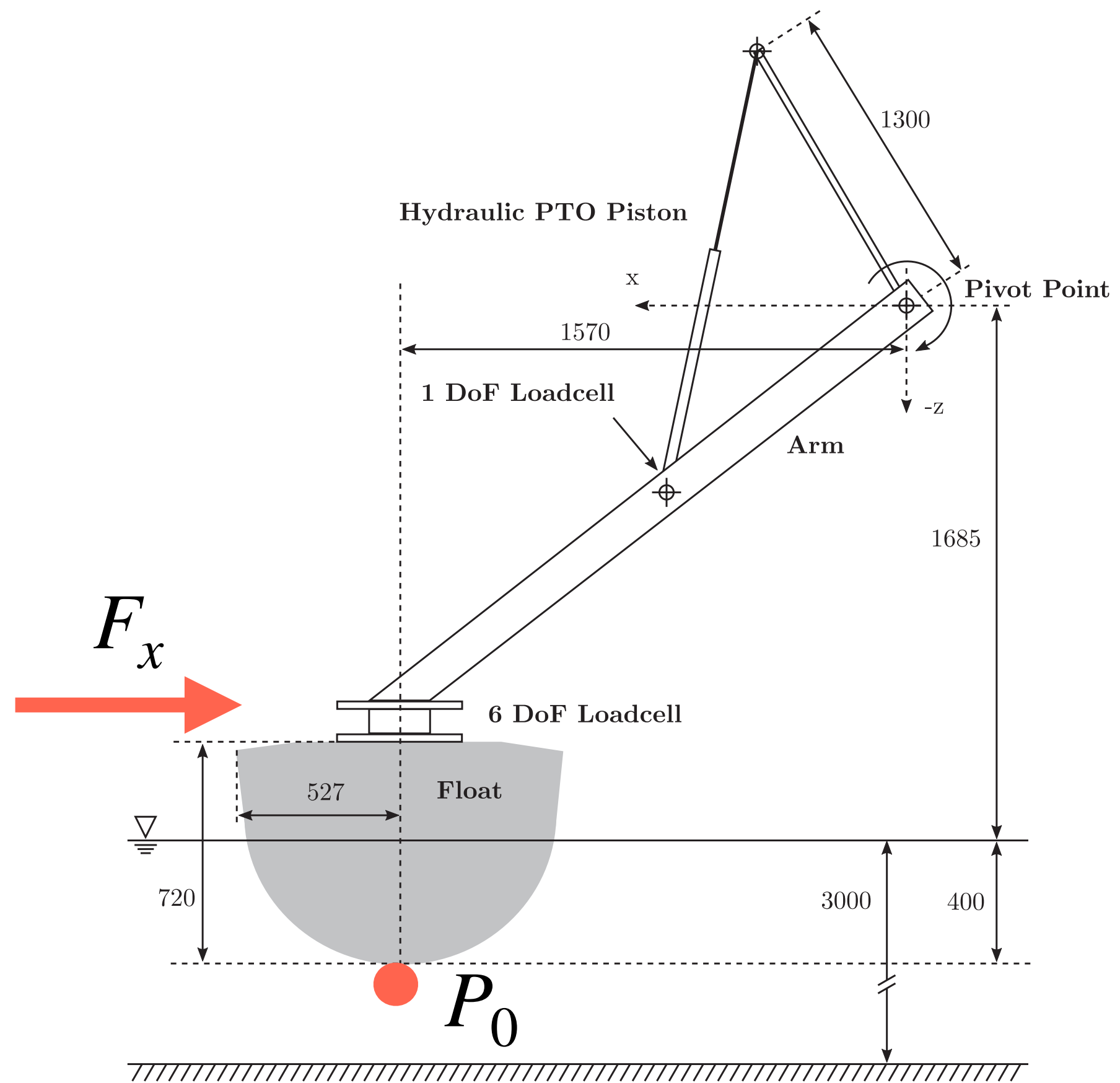
Wave validation

	Wave Height	Wave Period	Wave Length
MS02	1.50 m	4.40 s	30.92 m

	Particle size	H/dp
Dp=D/10	1.00 m	1.50
Dp=D/20	0.50 m	3.00
Dp=D/30	0.33 m	5.00



Fixed Float Hydrodynamics

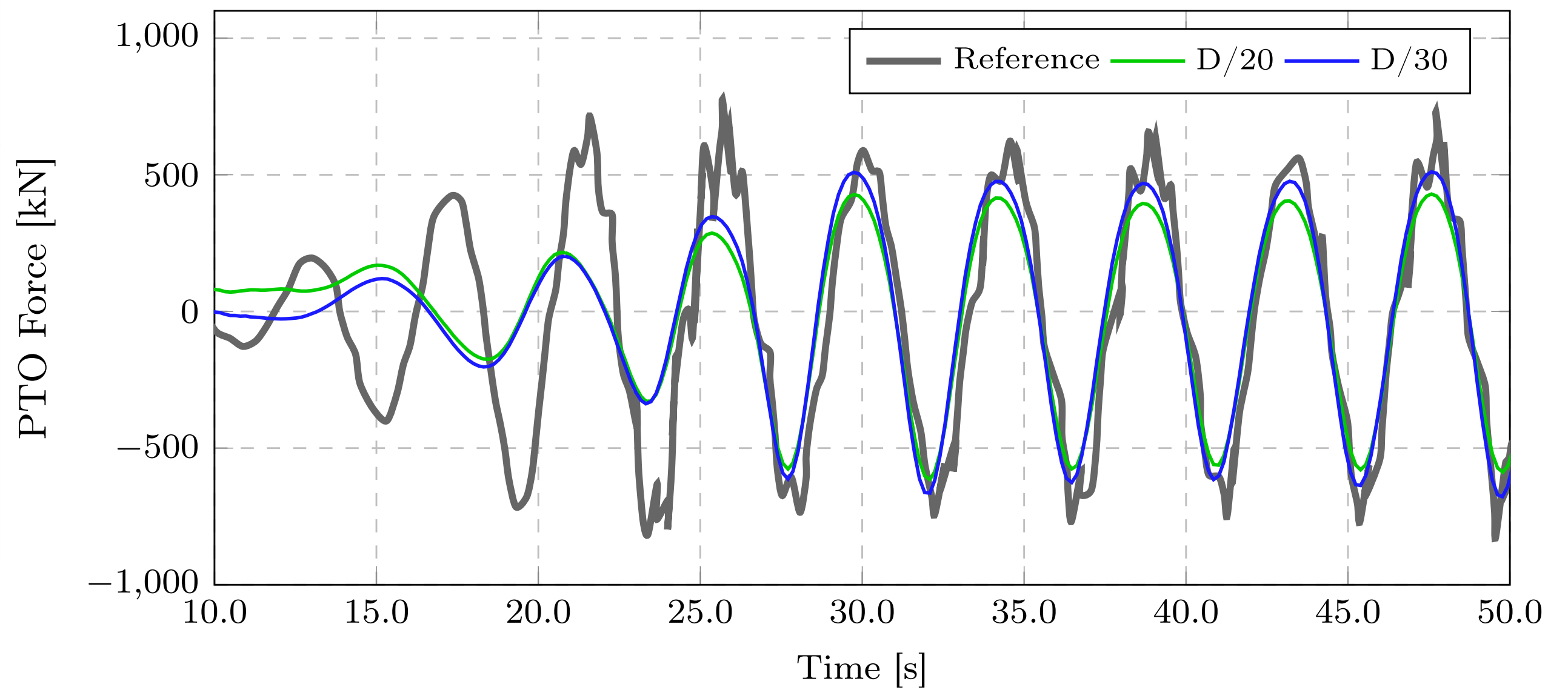
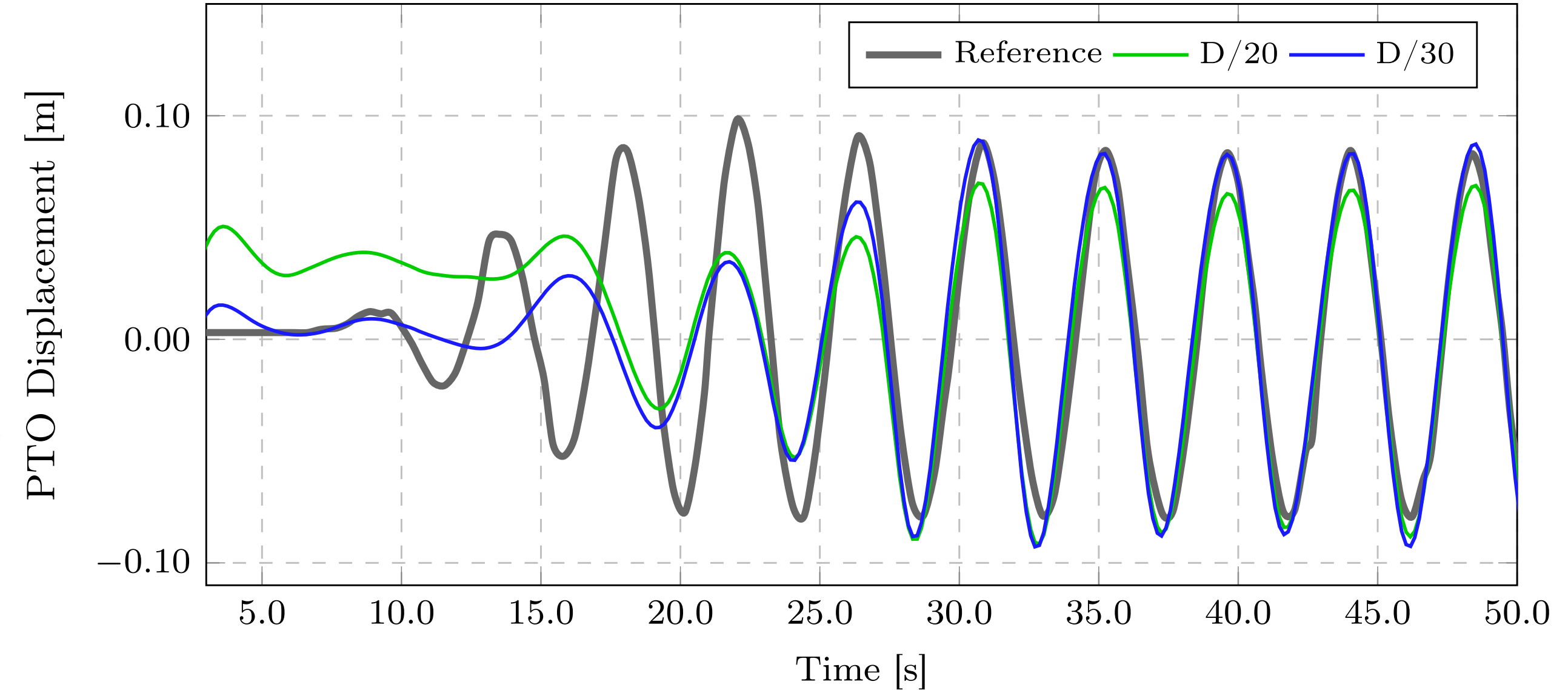
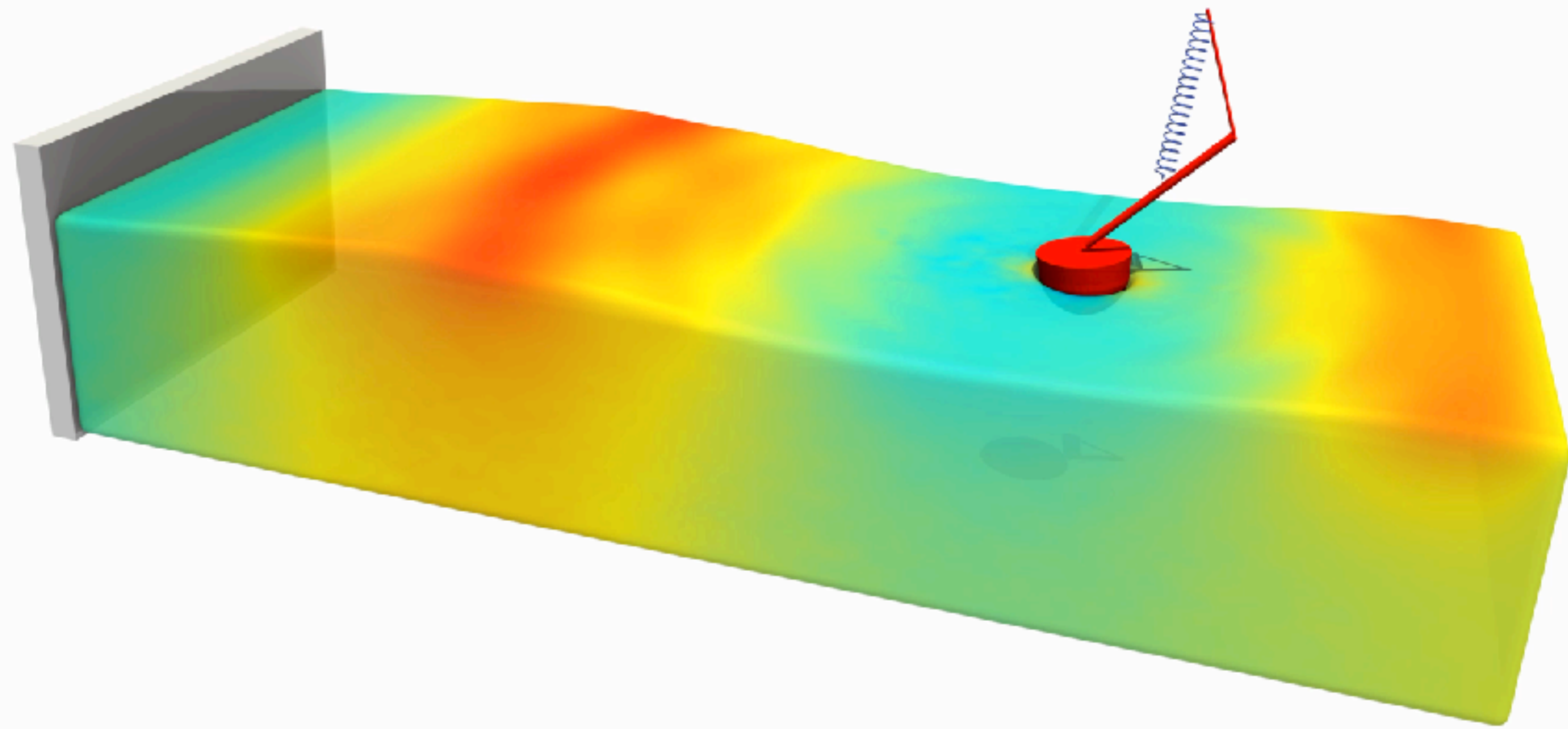


Windt et al. (2020). Validation of a CFD-based numerical wave tank model for the power production assessment of the wavestar ocean wave energy converter. *Renewable Energy*, 146, 2499-2516. <https://doi.org/10.1016/j.renene.2019.08.059>

Wave energy conversion

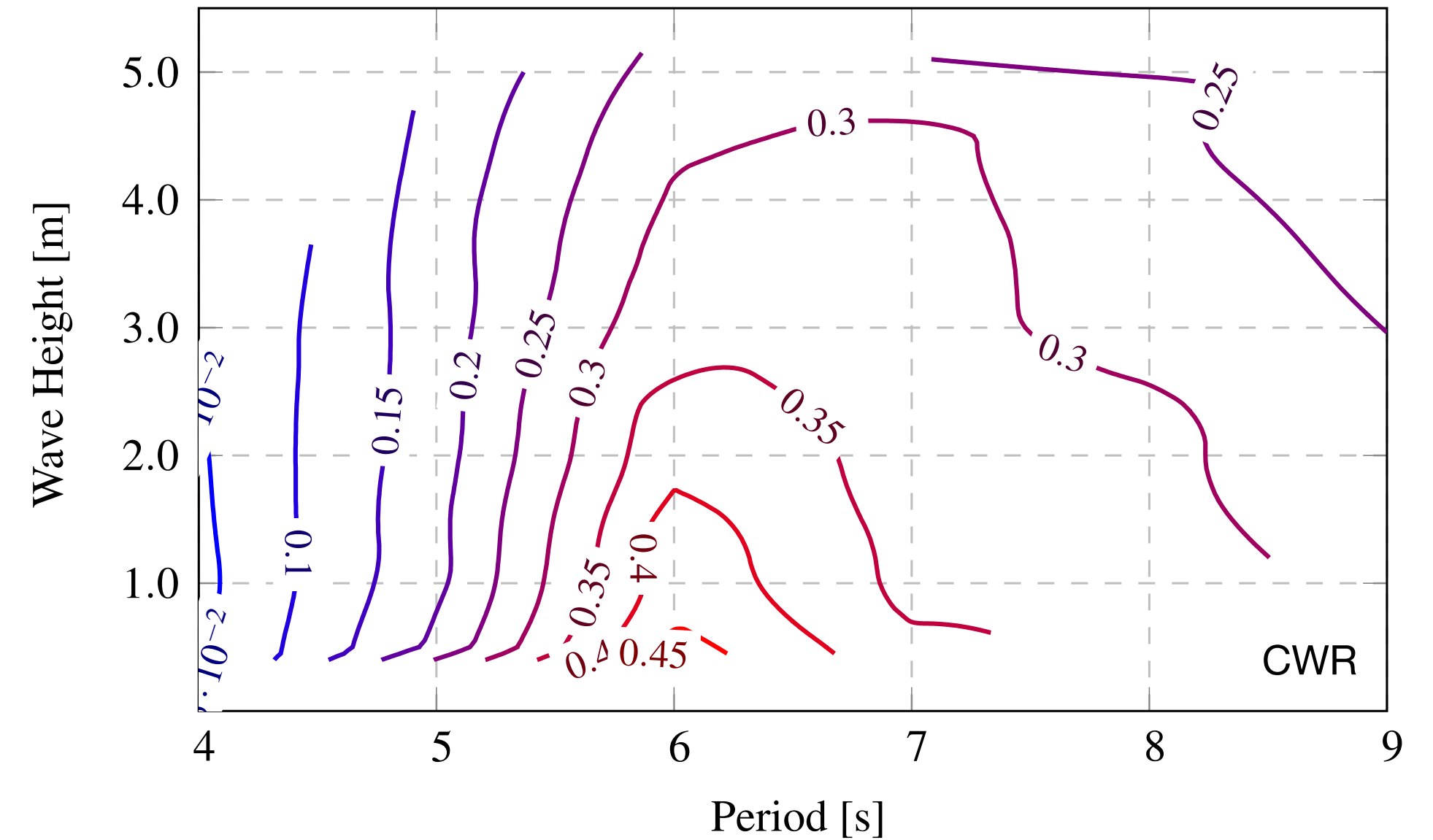
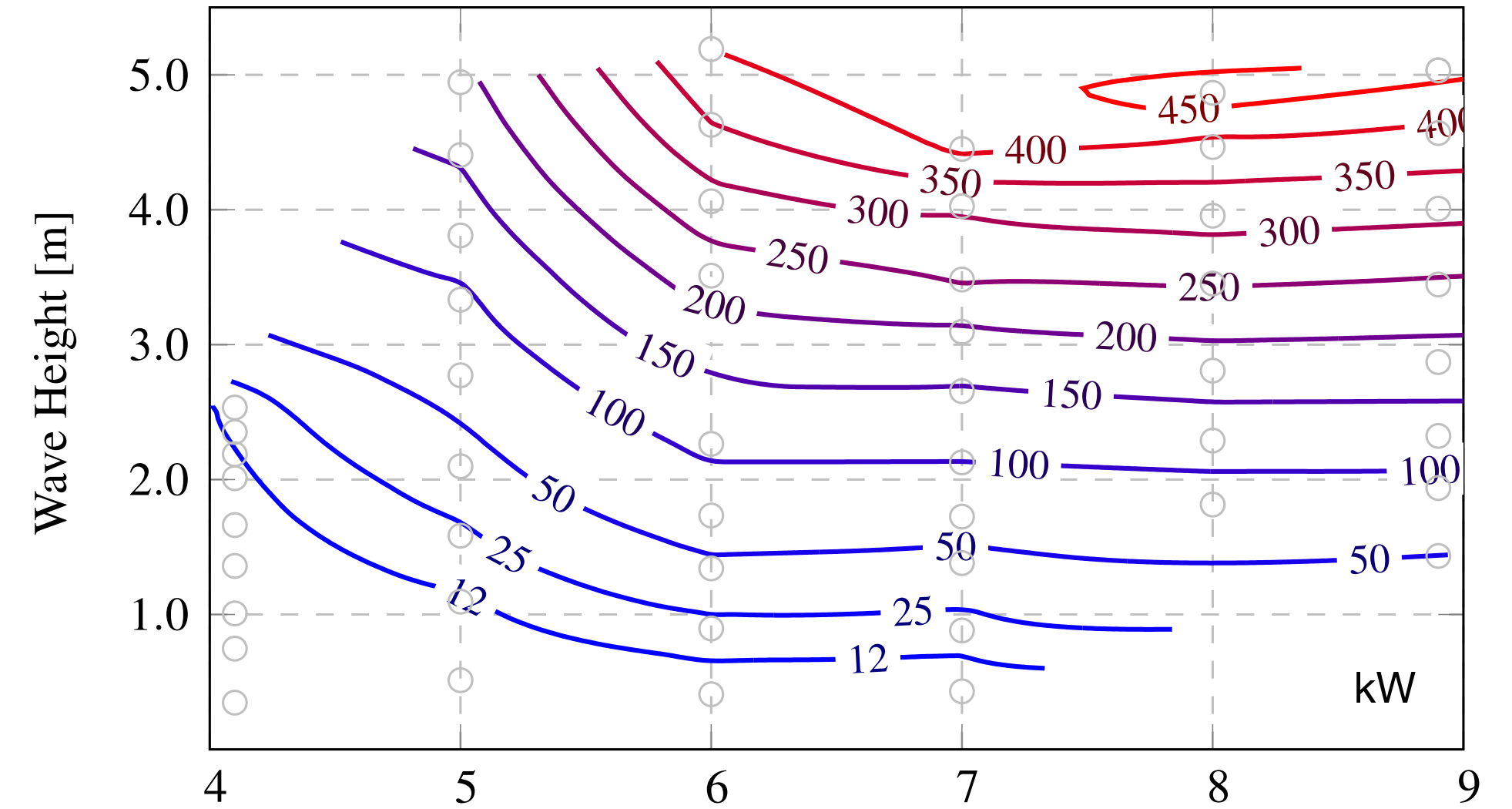
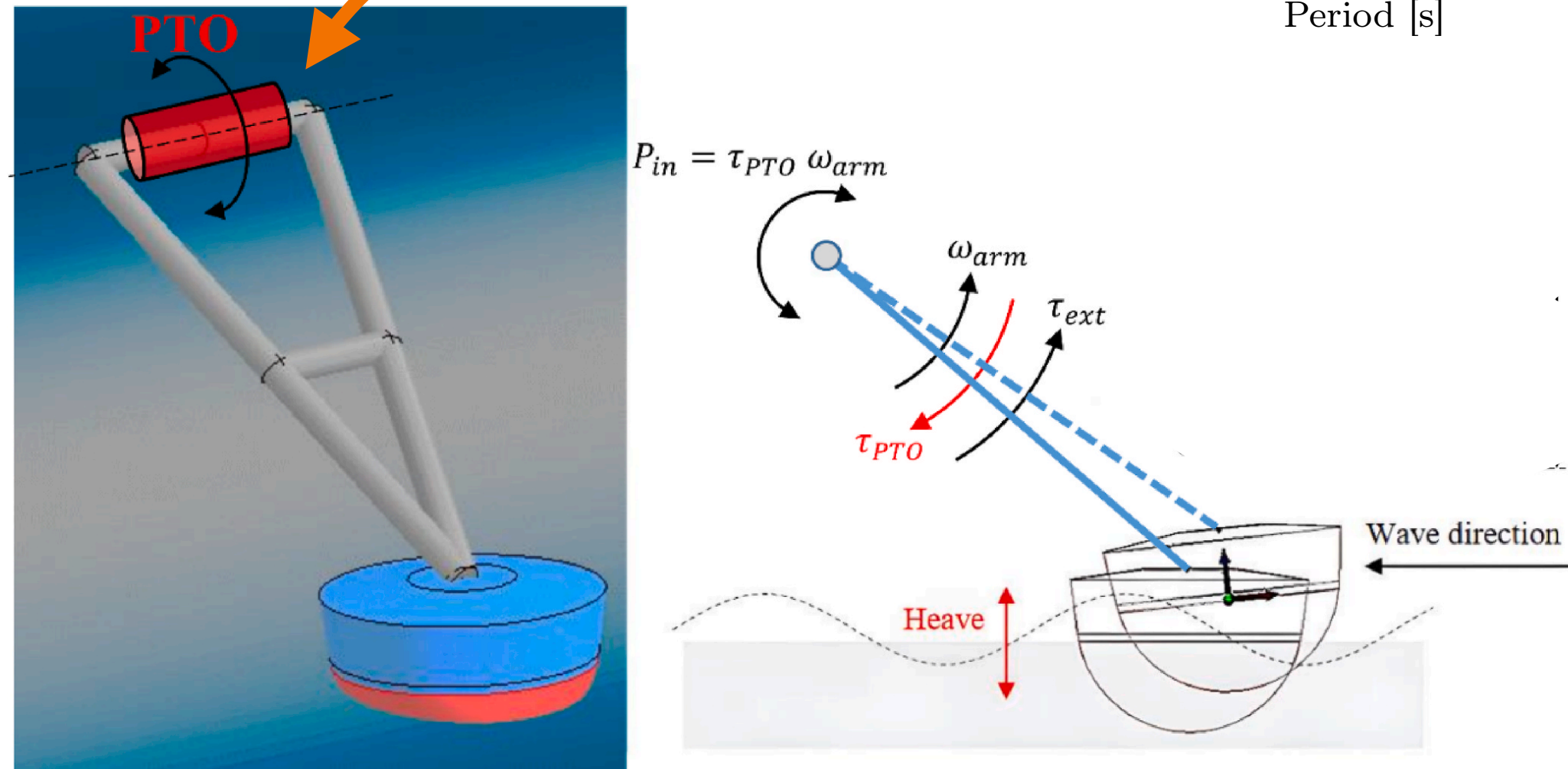
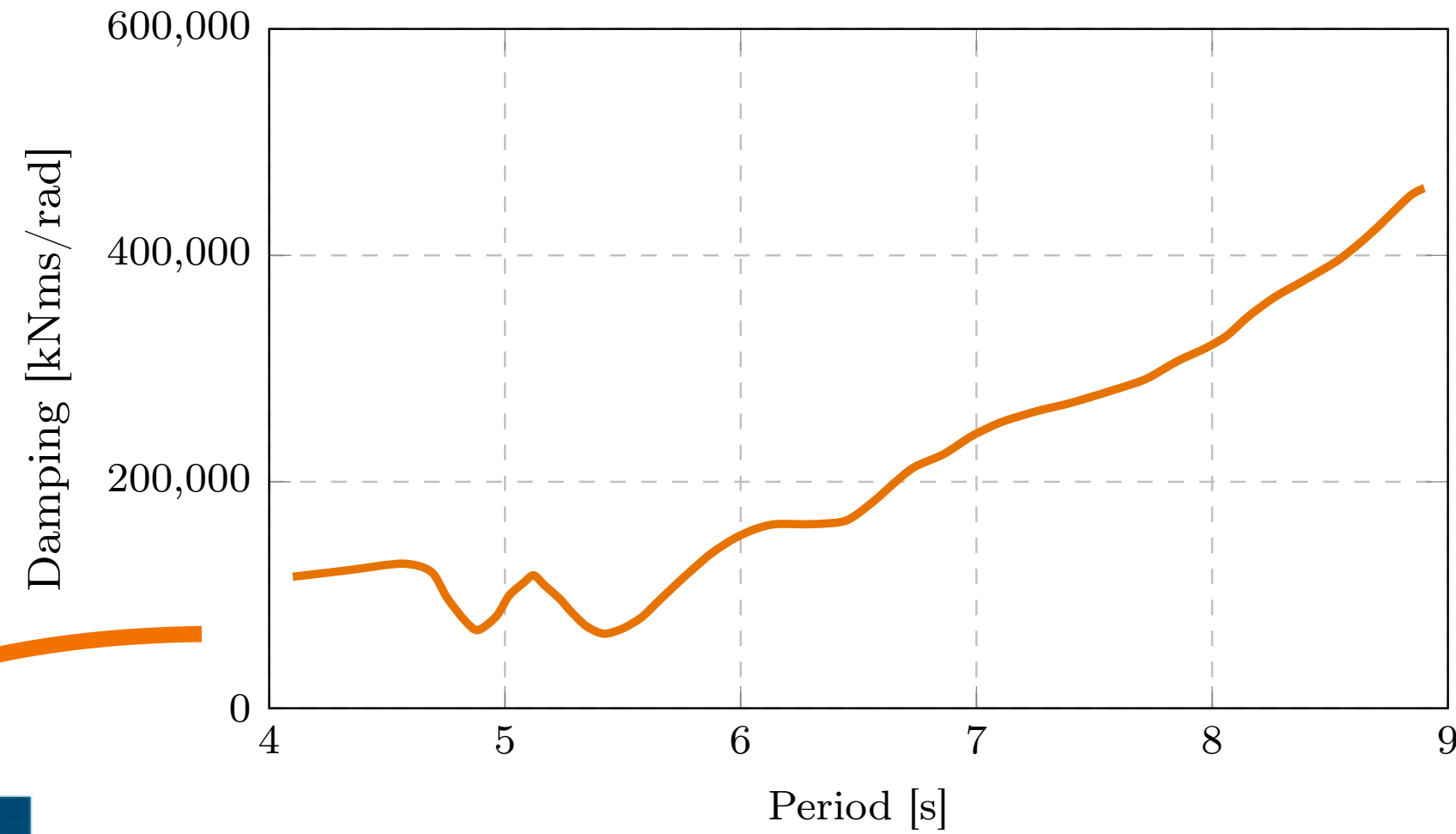
PTO aggressive configuration

	Damping	Stiffness	Initial Length
PTO	21 MNs/m	3.80 MN/m	11.30 m



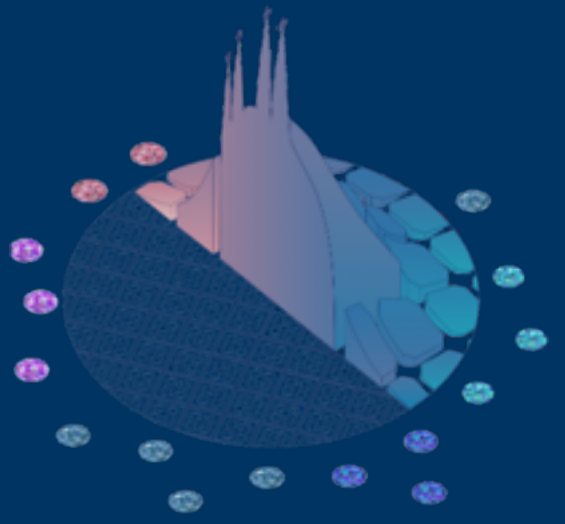
Wave energy conversion

Power matrix



Ghafari, H. R., Ghassemi, H., & Akbari Vakilabadi, K. (2025). Hydrodynamic performance and power absorption of the hybrid wind-wave energy systems with different platform geometries. *Ocean Engineering*, 332, 121440. <https://doi.org/10.1016/j.oceaneng.2025.121440>

Tagliafierro, B., Martínez-Estévez, I., Capasso, S., Domínguez, J. M., Karimirad, M., Viccione, G., Gómez-Gesteira, M., Crespo, A. J. C., & Götteman, M. (2025). Wave power extraction from semi-submersible hybrid platforms with multi-physics and high-fidelity simulations powered by SPH (*Paper No. OMAE2025-156719*). Vancouver, Canada.



Hybrid platform configuration

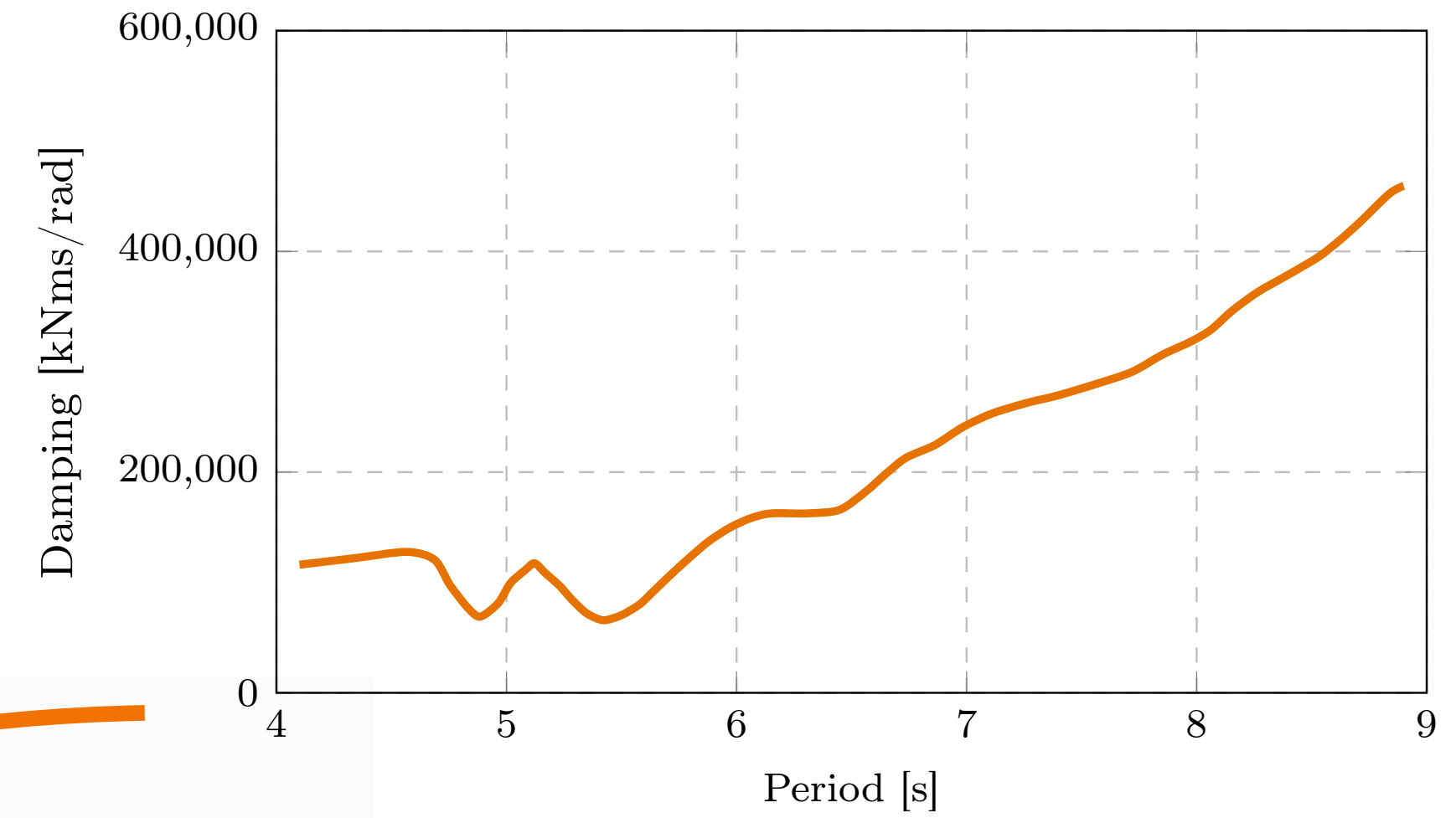
DeepCwind Platform



UPPSALA
UNIVERSITET

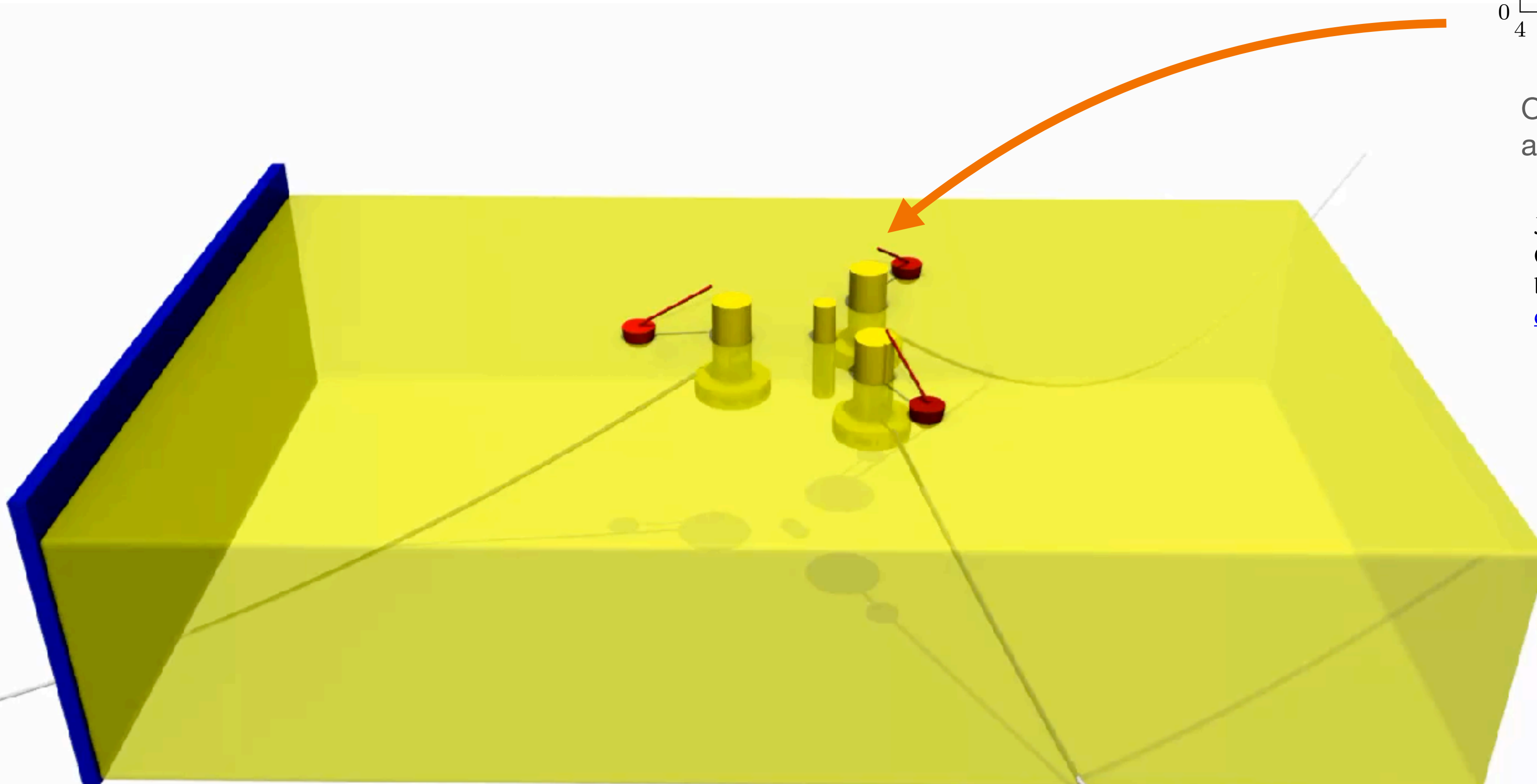
Hybrid Platform

	H	T	Wind
R8	2.00 m	8.00 s	0 m/s



Optimal damping function for passive PTO control as defined in Jin et al. (2023).

Jin, P., Zheng, Z., Zhou, Z., Zhou, B., Wang, L., Yang, Y., & Liu, Y. (2023). Optimization and evaluation of a semi-submersible wind turbine and oscillating body wave energy converters hybrid system. *Energy*, 282, 128889. <https://doi.org/10.1016/j.energy.2023.128889>



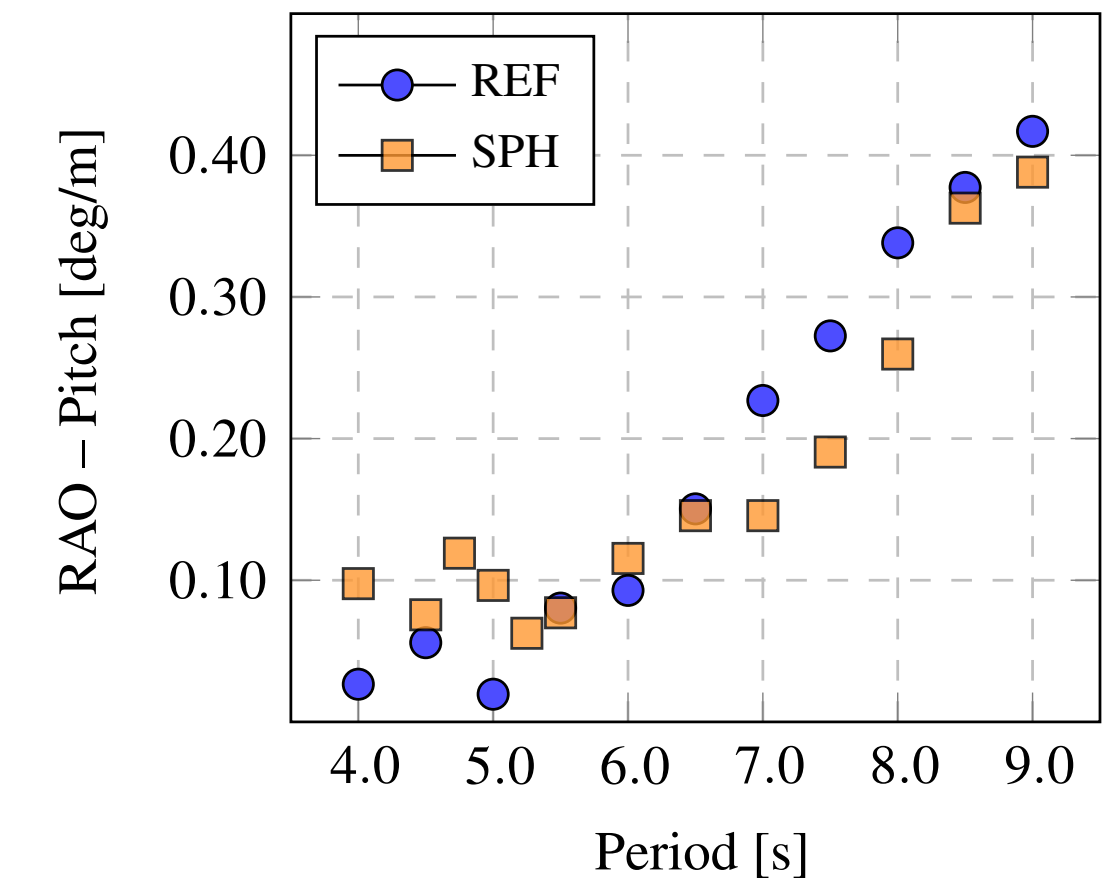
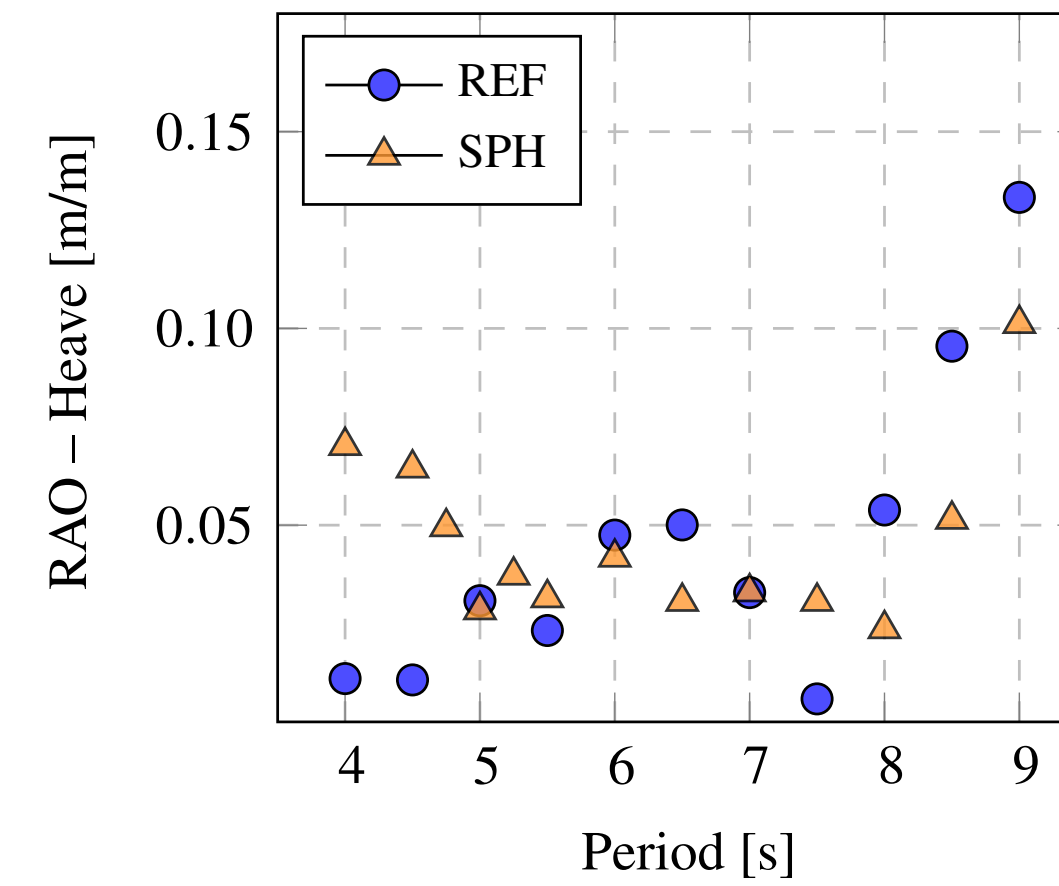
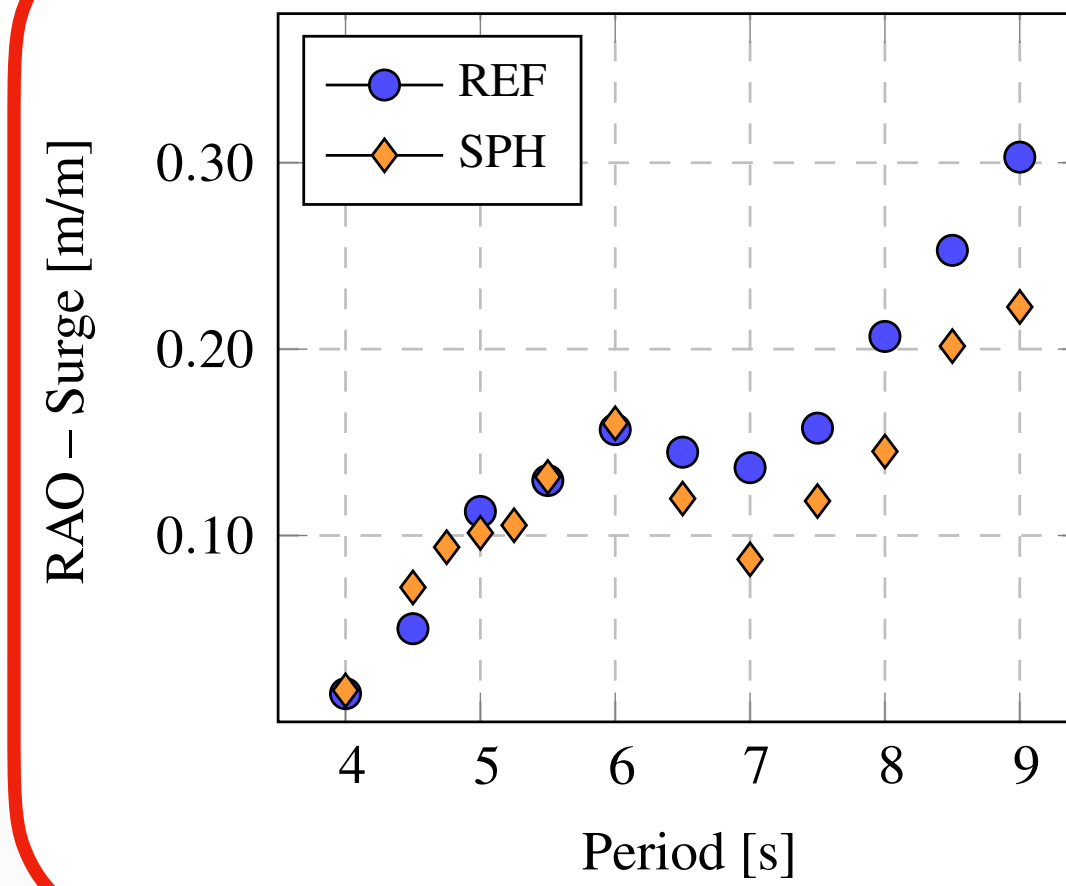
Coloring represents longitudinal velocity



Hybrid Platform

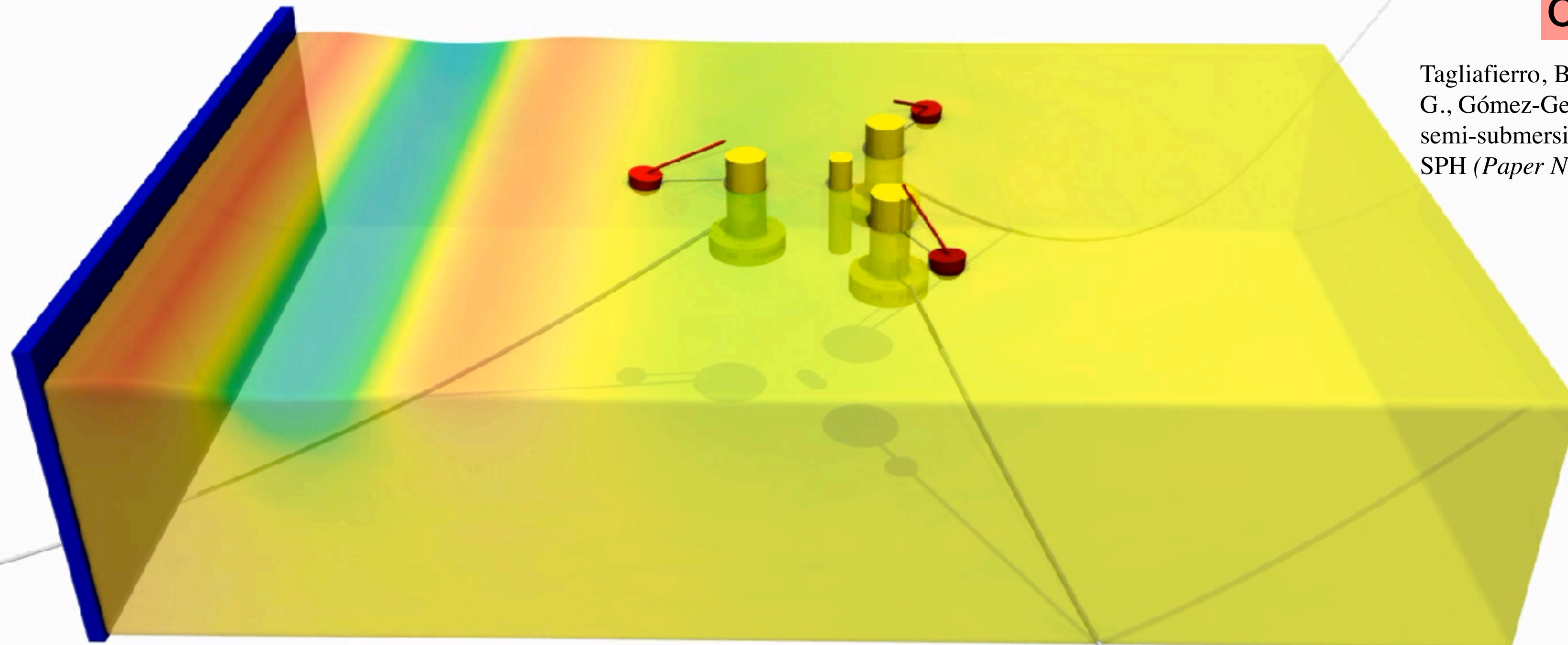
	H	T	Wind
R	2.00 m	-	0 m/s

Platform response



Comparison

Tagliafierro, B., Martínez-Estévez, I., Capasso, S., Domínguez, J. M., Karimirad, M., Viccione, G., Gómez-Gesteira, M., Crespo, A. J. C., & Göteman, M. (2025). Wave power extraction from semi-submersible hybrid platforms with multi-physics and high-fidelity simulations powered by SPH (*Paper No. OMAE2025-156719*). Vancouver, Canada.



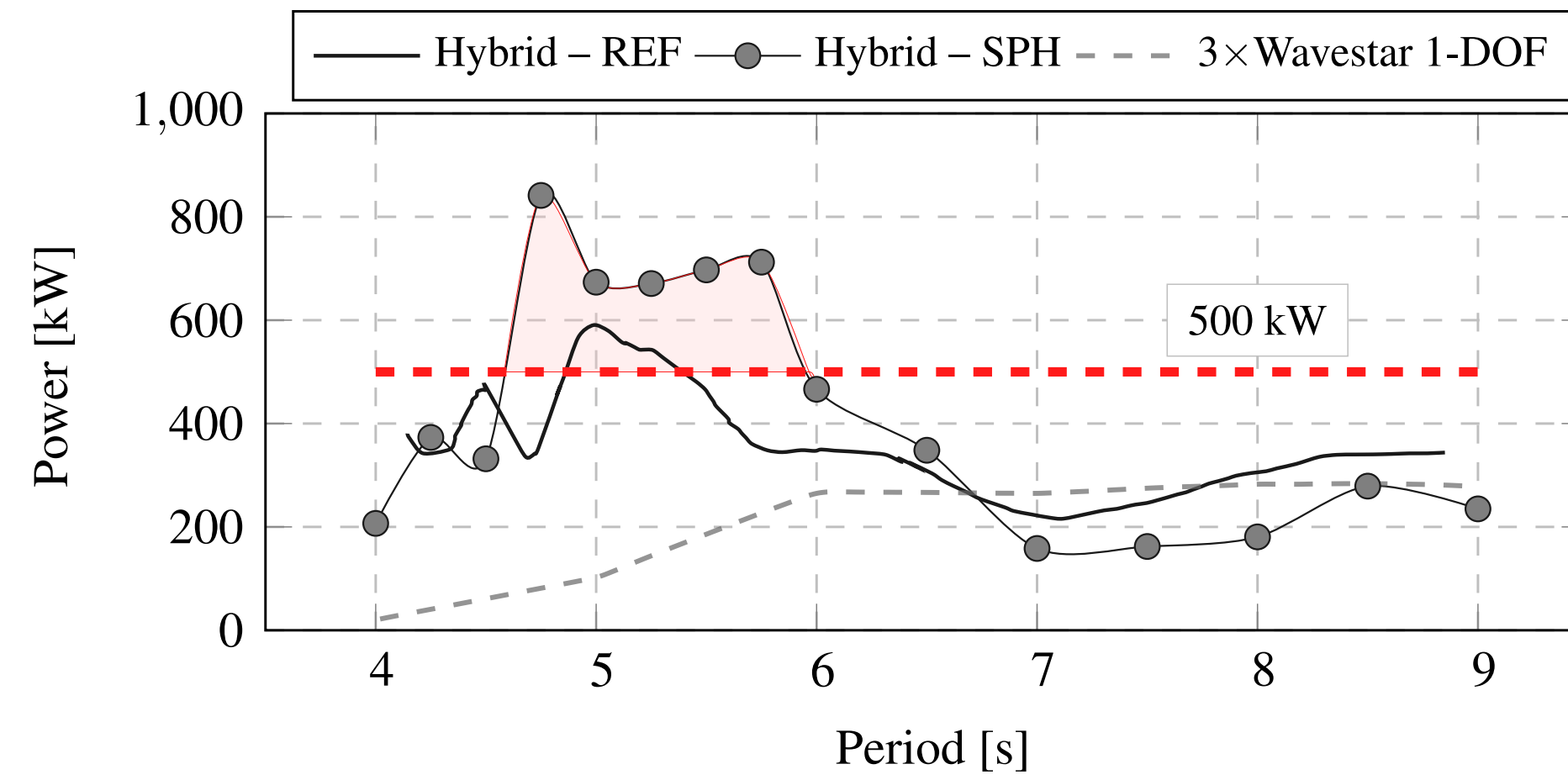
Coloring represents longitudinal velocity



Hybrid Platform

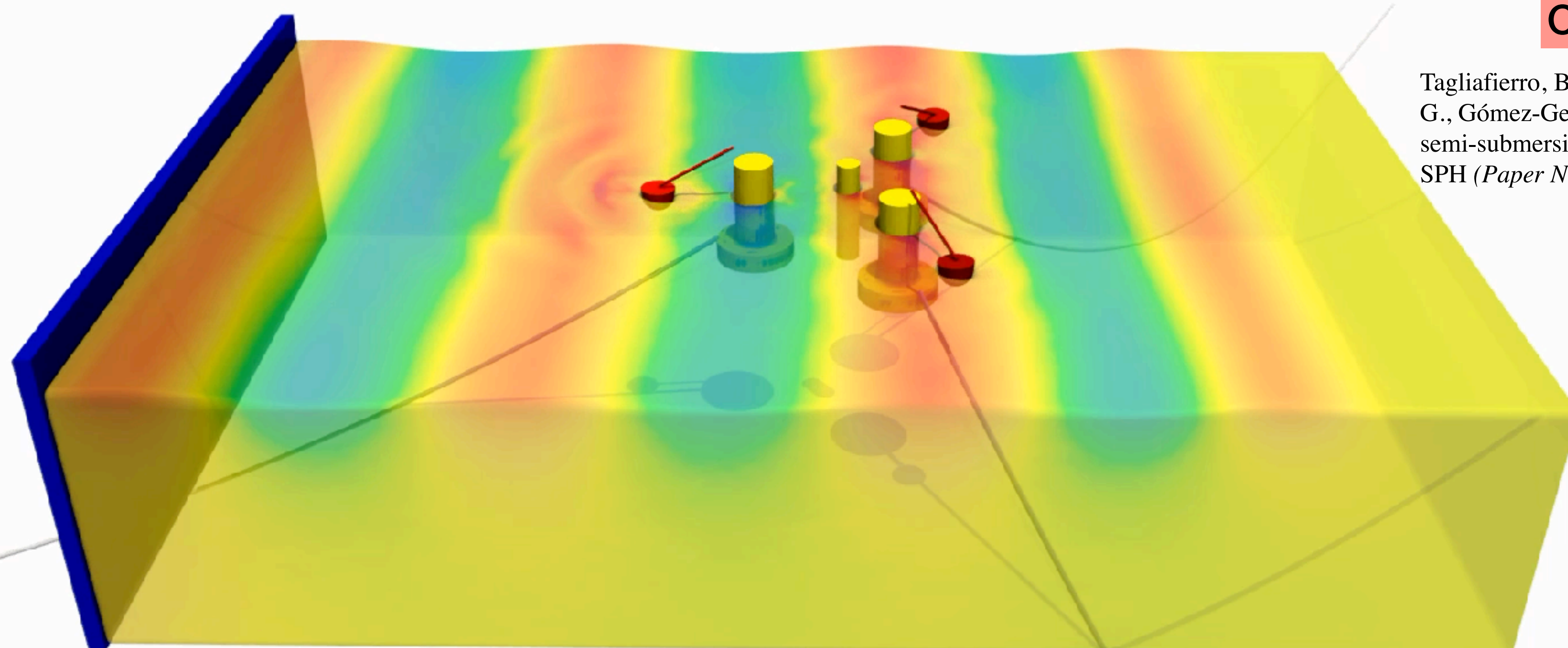
	H	T	Wind
R	2.00 m	-	0 m/s

Total wave power



Comparison

Tagliafierro, B., Martínez-Estévez, I., Capasso, S., Domínguez, J. M., Karimirad, M., Viccione, G., Gómez-Gesteira, M., Crespo, A. J. C., & Göteman, M. (2025). Wave power extraction from semi-submersible hybrid platforms with multi-physics and high-fidelity simulations powered by SPH (*Paper No. OMAE2025-156719*). Vancouver, Canada.

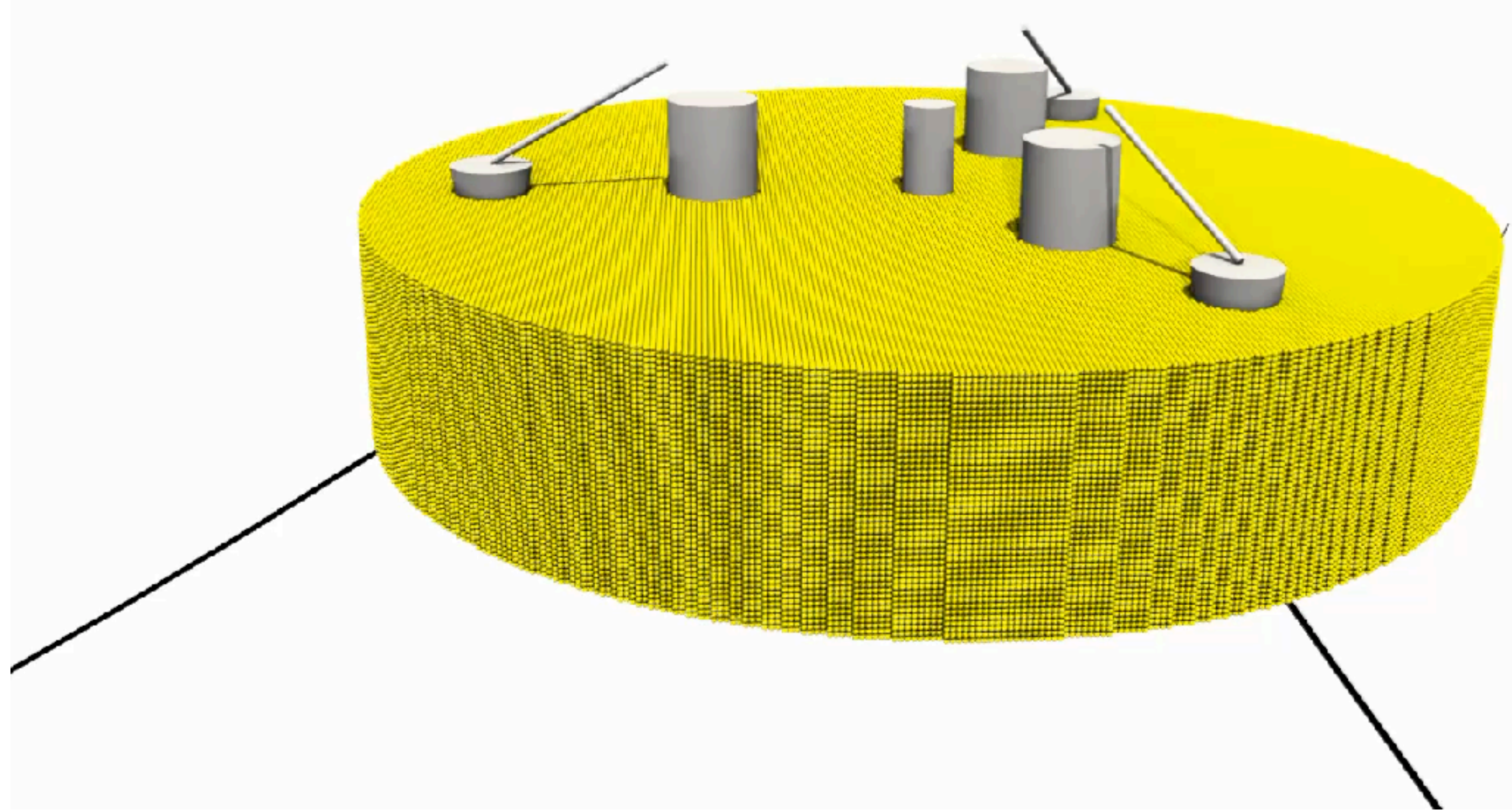


Coloring represents longitudinal velocity

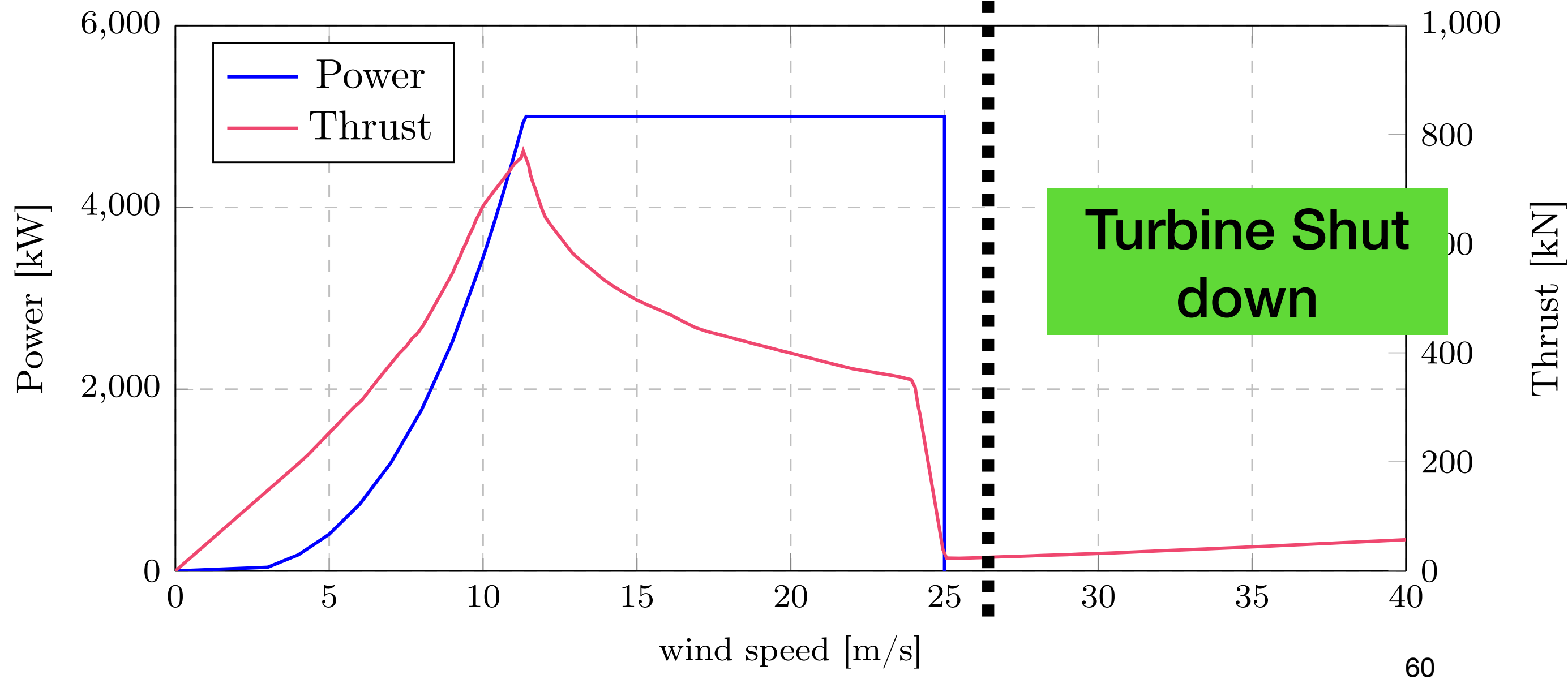


Power performance

	Hs	Tp	Wind
Random	3.20 m	7.70 s	25 kN



Wind speed at 26 m/s – turbine parked

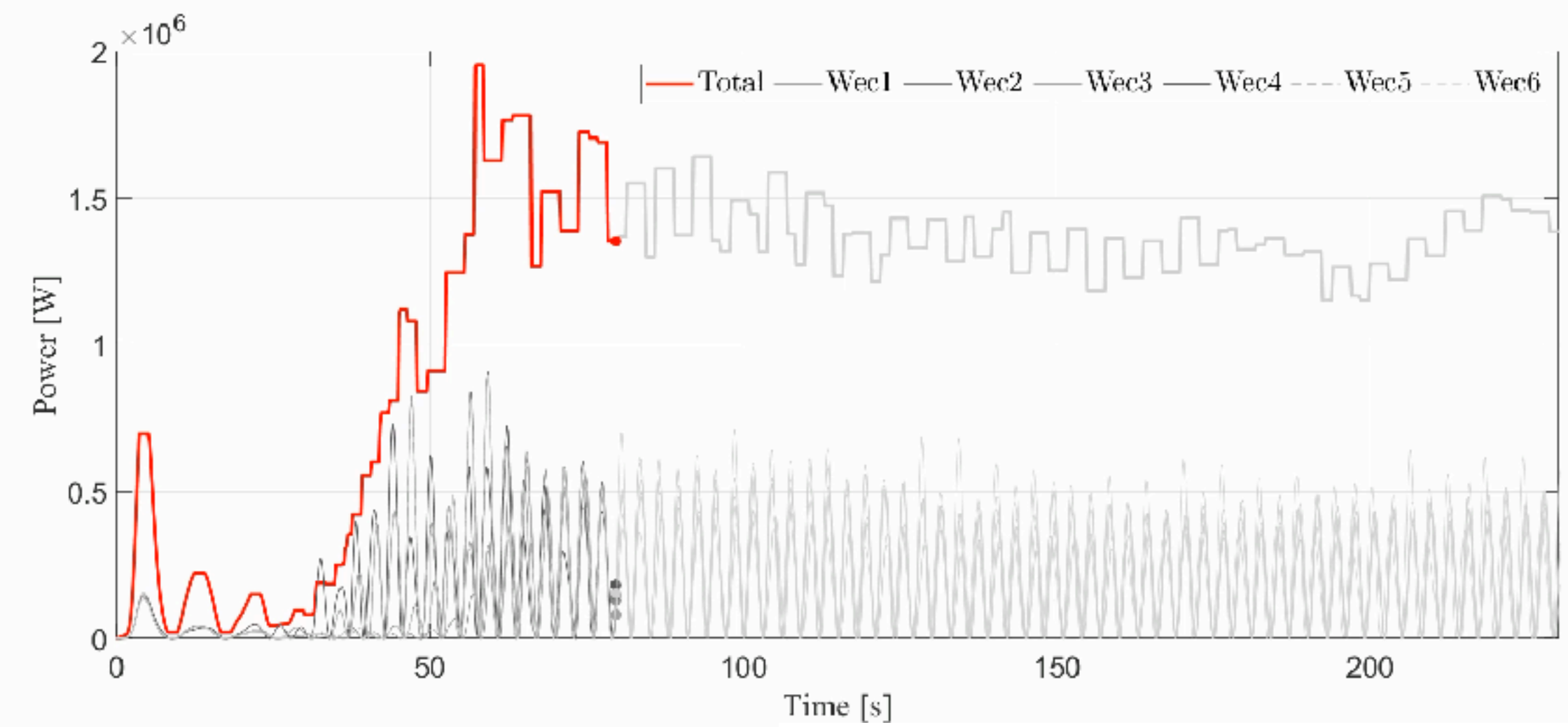


Most critical event for power grid stability

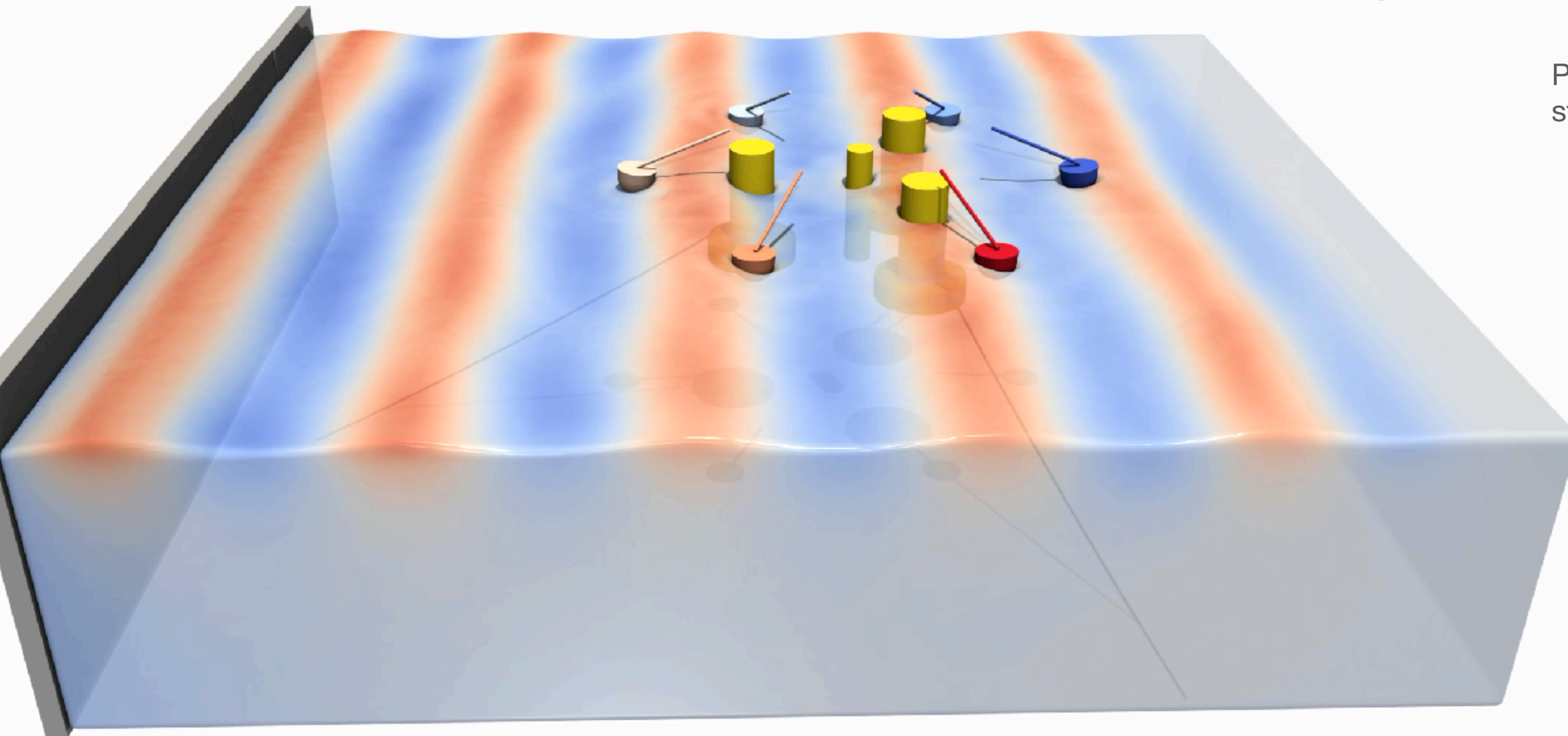


Hybrid Platform (6 WECs)

	H [m]	T [s]
R6	2.50 m	6.00 s



Possible on-board flywheel for 10-15 seconds stabilized output.



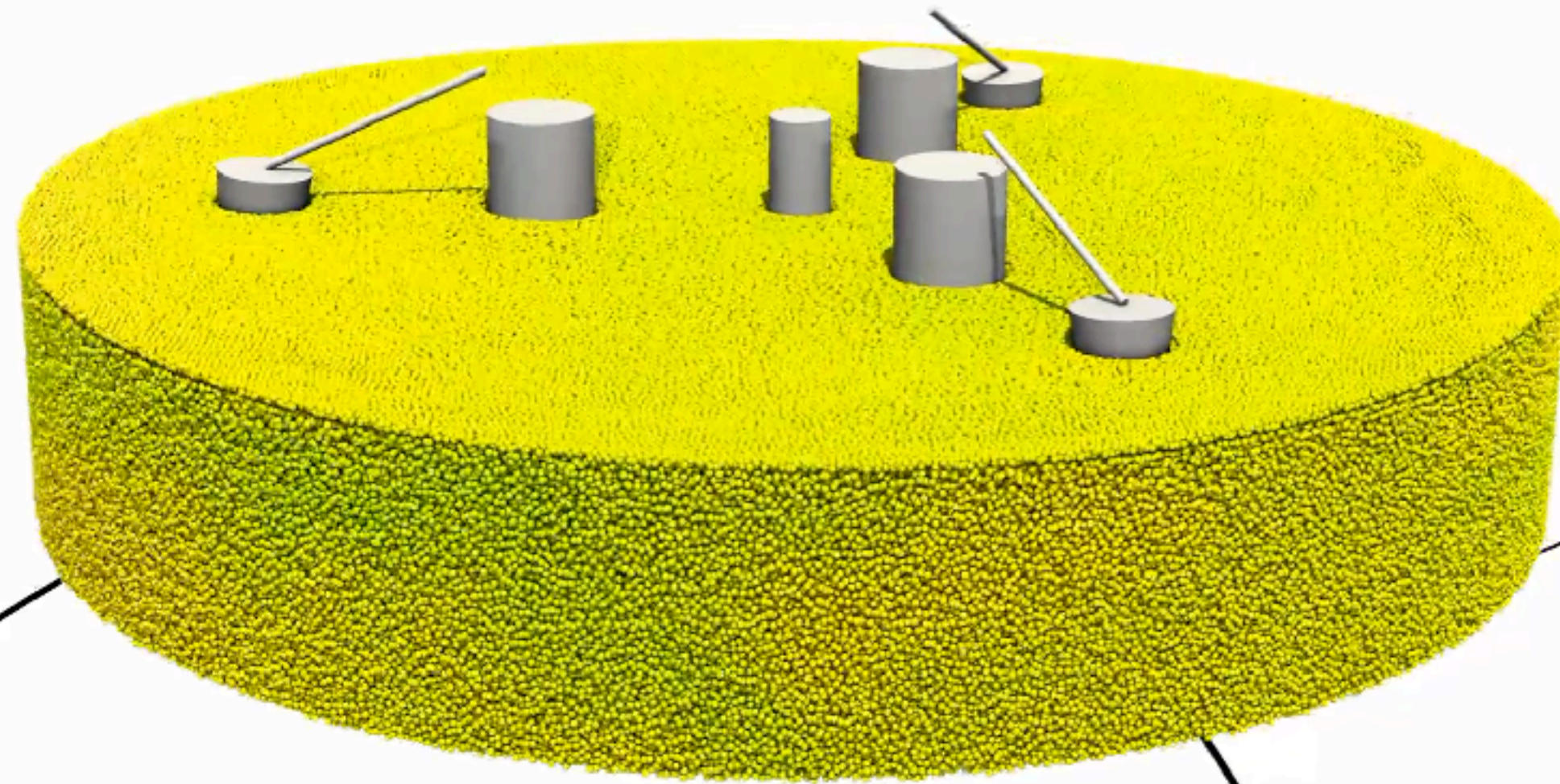
Only hydrodynamic elements are displayed

Coloring represents transversal velocity



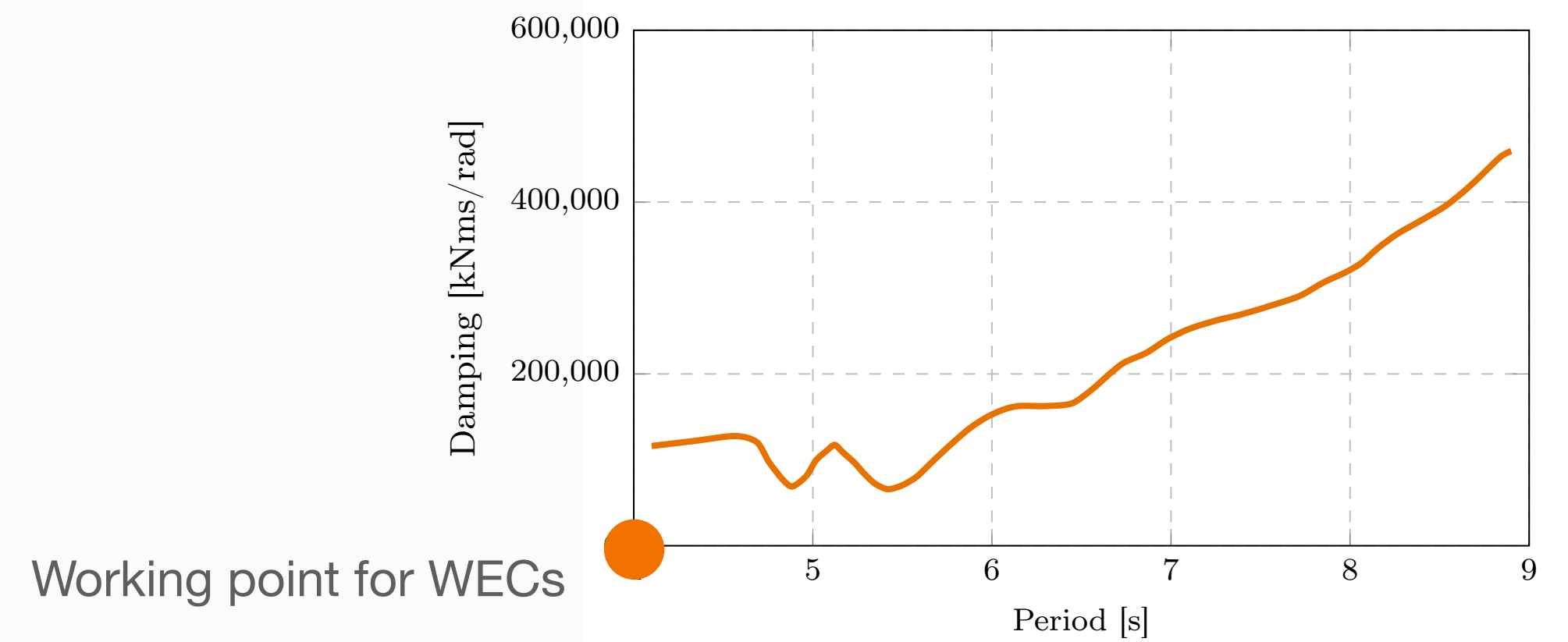
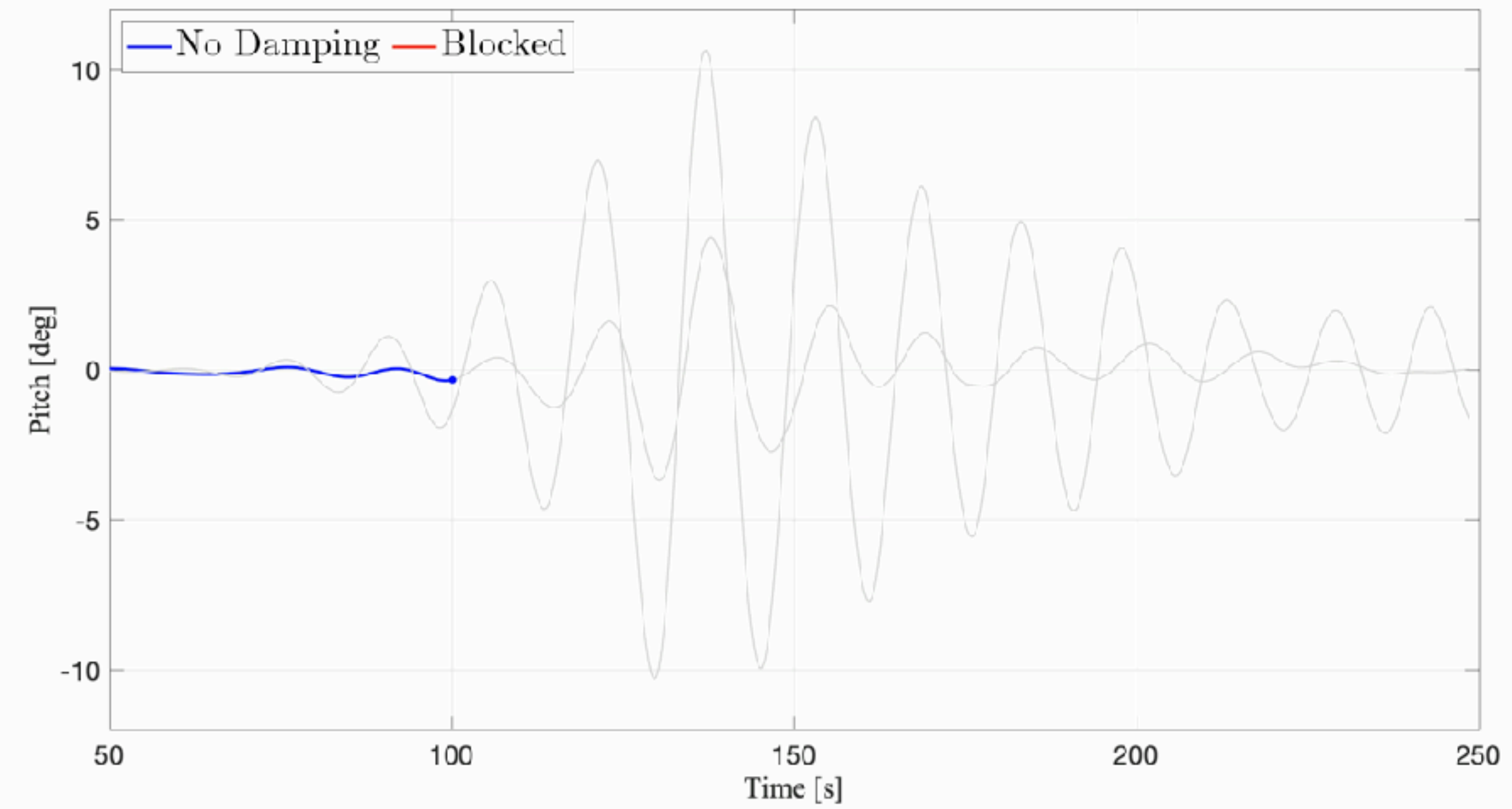
Extreme conditions (Free)

	Hs	Tp
Focused wave	14 m	15 s



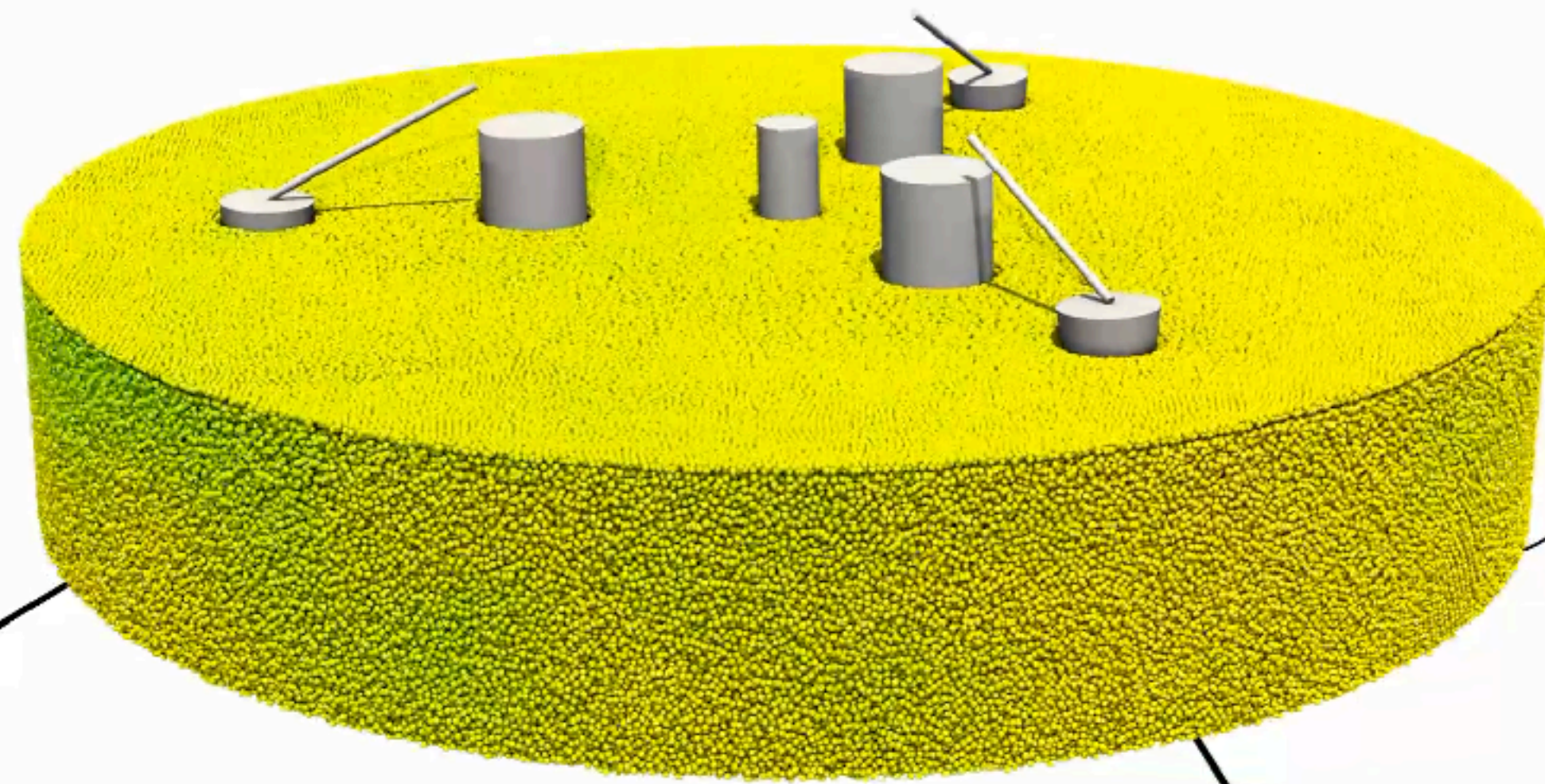
Only hydrodynamic elements are displayed

Coloring represents transversal velocity



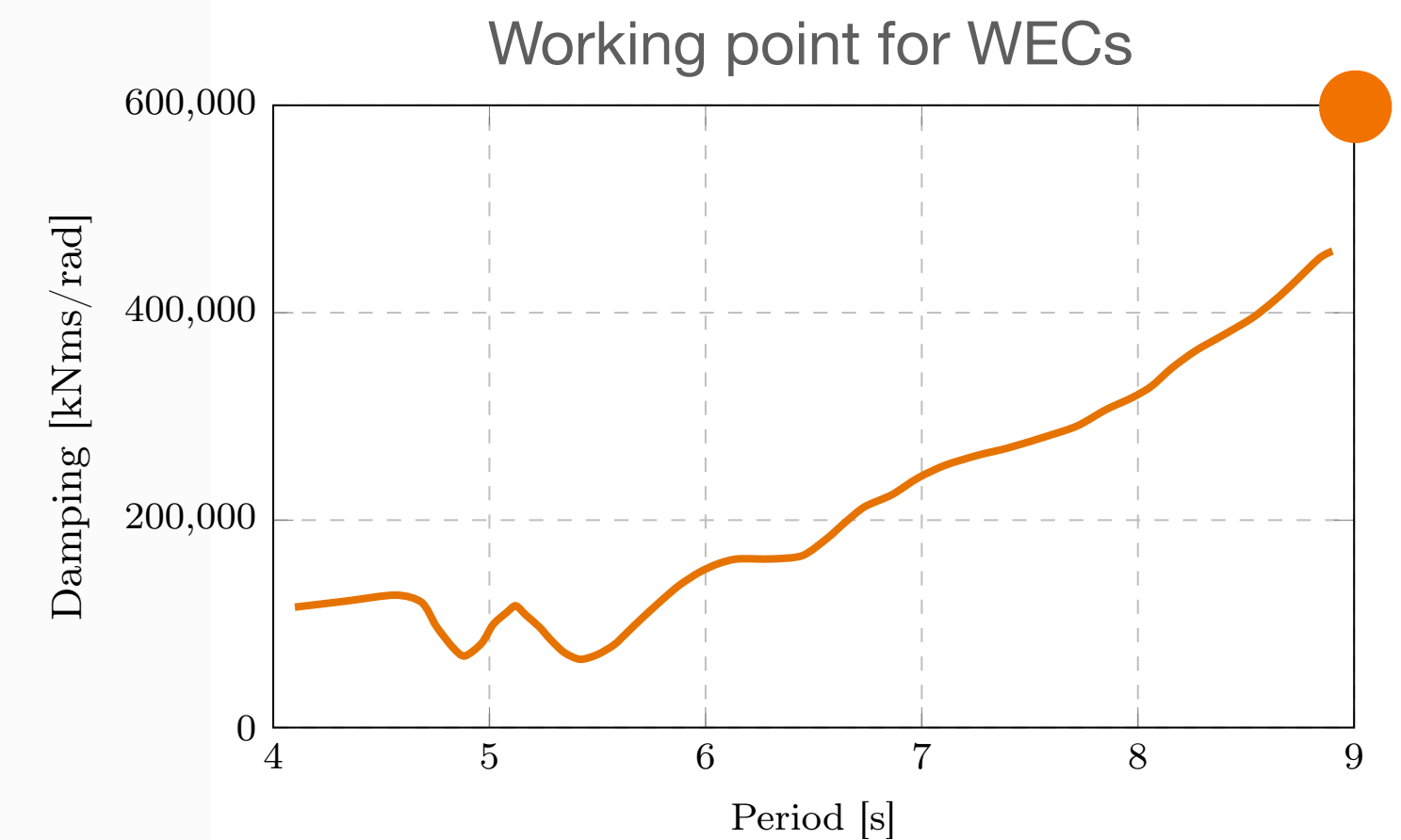
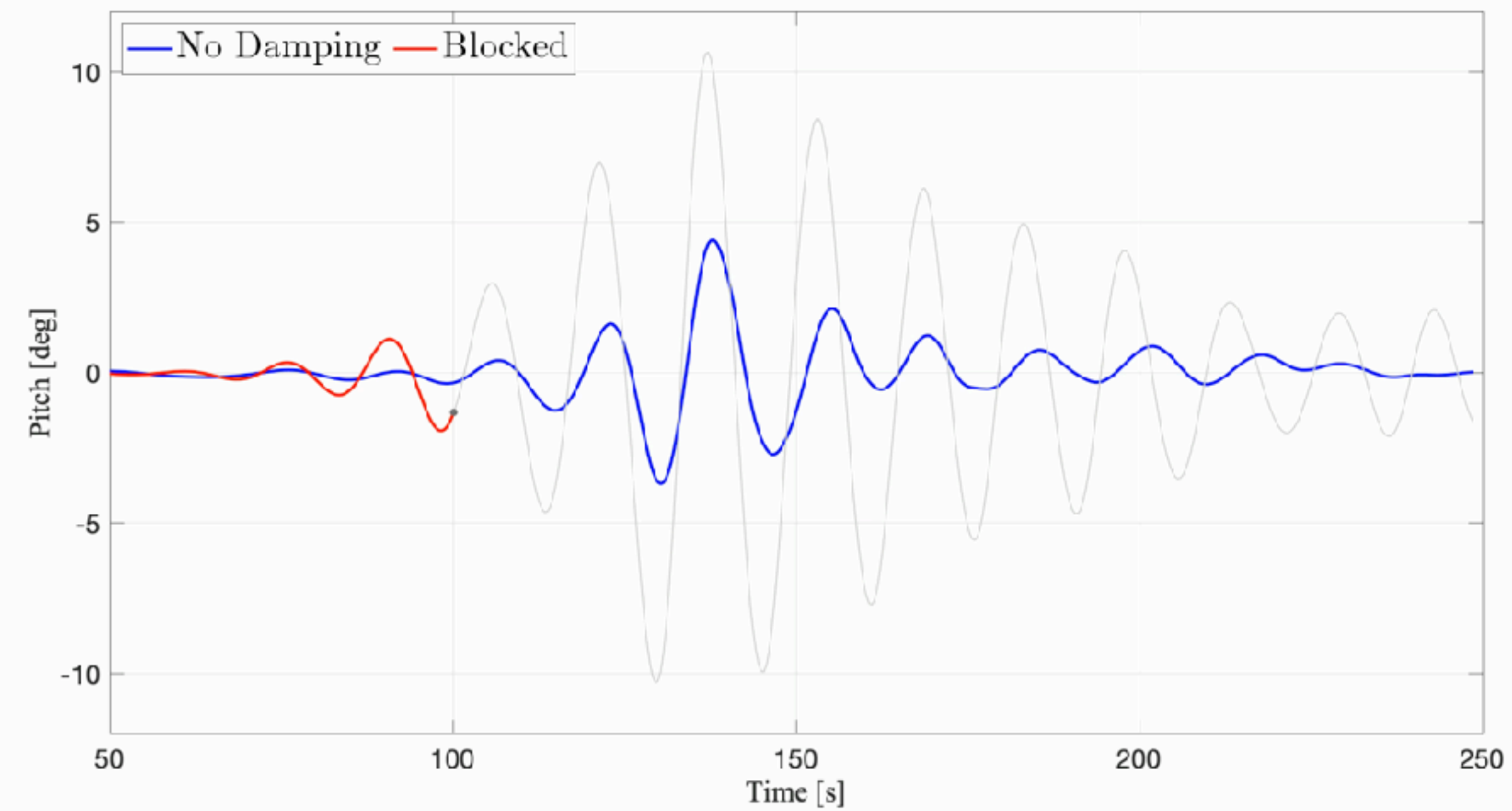
Extreme conditions (Locked)

	Hs	Tp
Focused wave	14 m	15 s



Only hydrodynamic elements are displayed

Coloring represents transversal velocity



Discussion

1. High-fidelity has found its niche for marine renewable energy
2. SPH is catching up with (applicability is key)
3. Combined validation are deemed reliable for most applications
4. We can do engineering!

THANK YOU!

Bonaventura Tagliaferro – June 16, 2025

btagliaferro@gmail.com

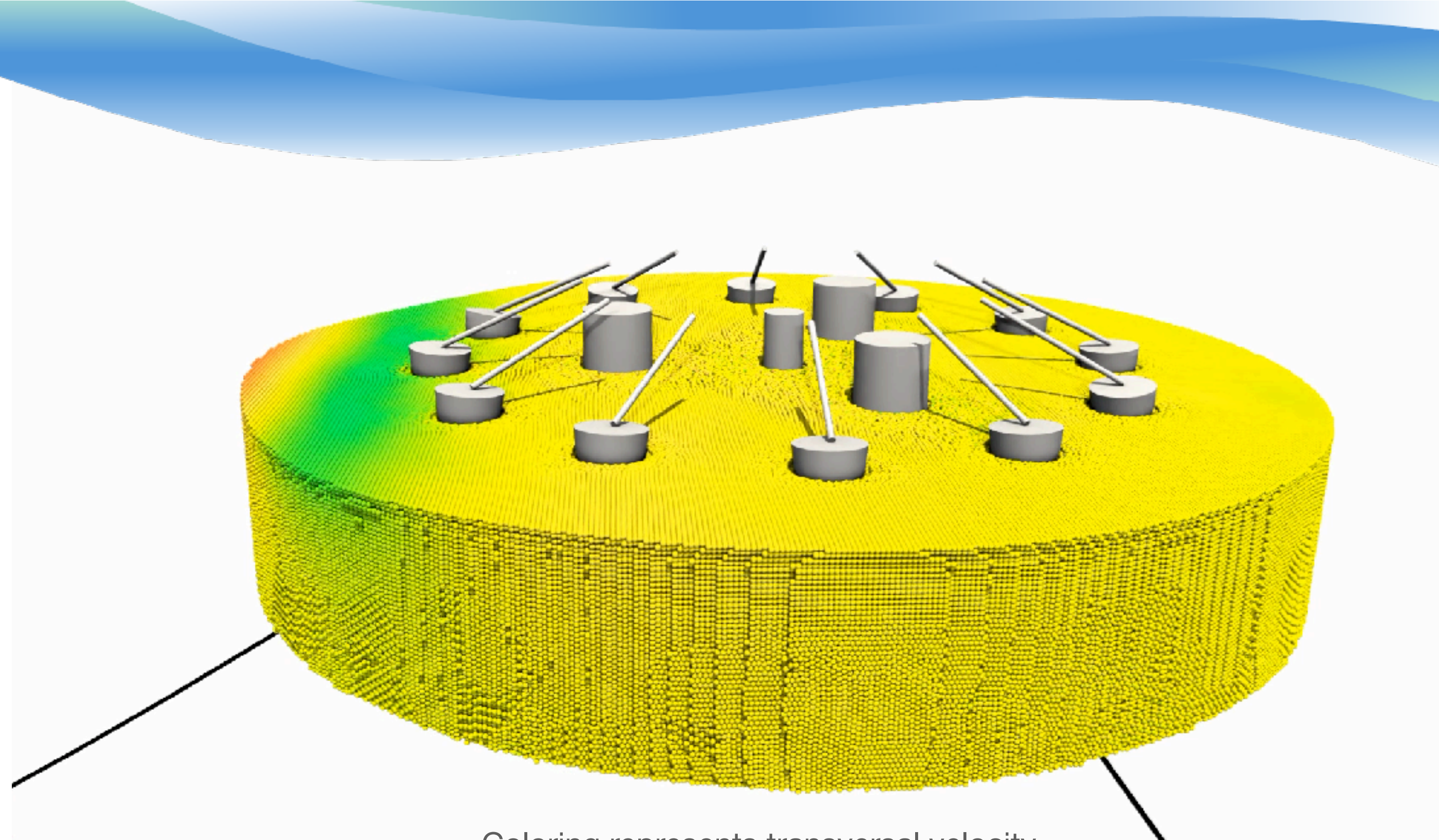
This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No: 101109440.



Funded by
the European Union



MARIE SKŁODOWSKA-CURIE ACTIONS
Research Fellowship Programme



Coloring represents transversal velocity



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